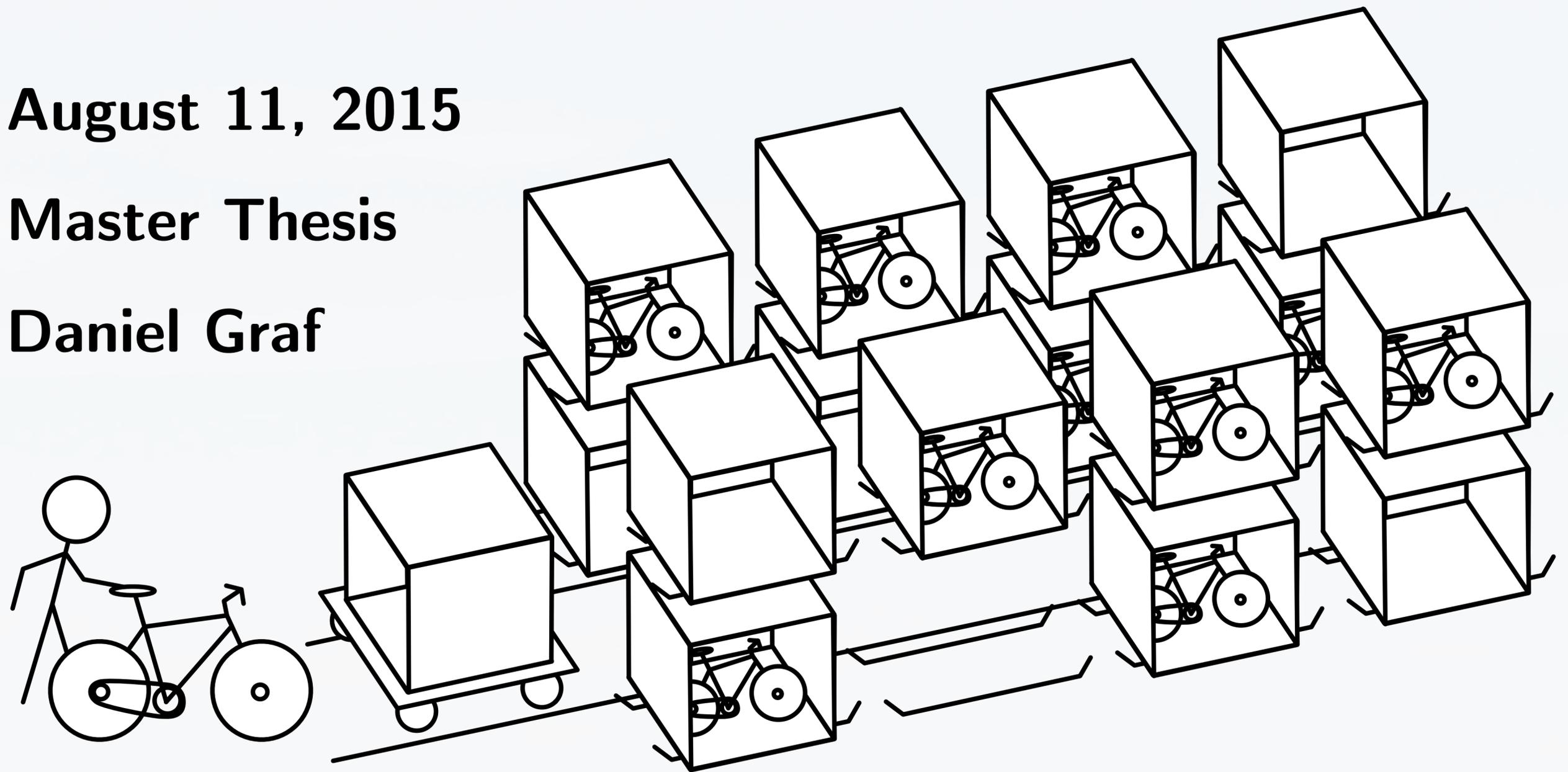


Scheduling and Sorting Algorithms for Robotic Warehousing Systems

August 11, 2015

Master Thesis

Daniel Graf



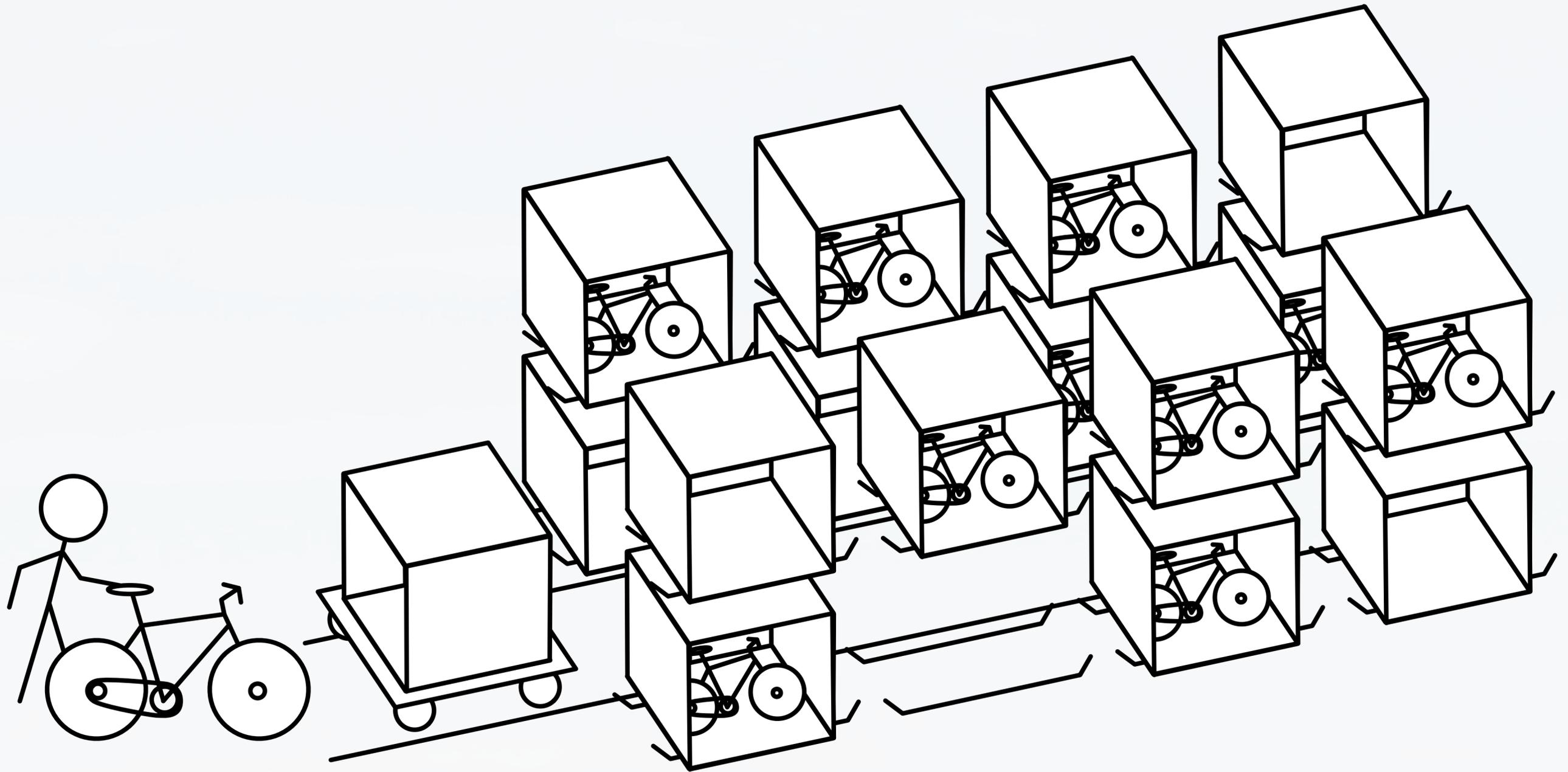
Motivation







Bike Loft



Scheduling problem

- How do we efficiently serve the customers?

Sorting problem

- How do we efficiently rearrange the stored boxes?

Survey of other bicycle storage systems

Scheduling



Given:

- robot specification
- customer arrival and departure times

Wanted:

- customer-to-slot-and-door-assignment
that does not keep the customers waiting

Sorting

Sorting



Given:

- a graph that describes the layout
- an initial permutation of the boxes
- starting position of the robot

Wanted:

- shortest possible sorting walk

Scheduling Problem

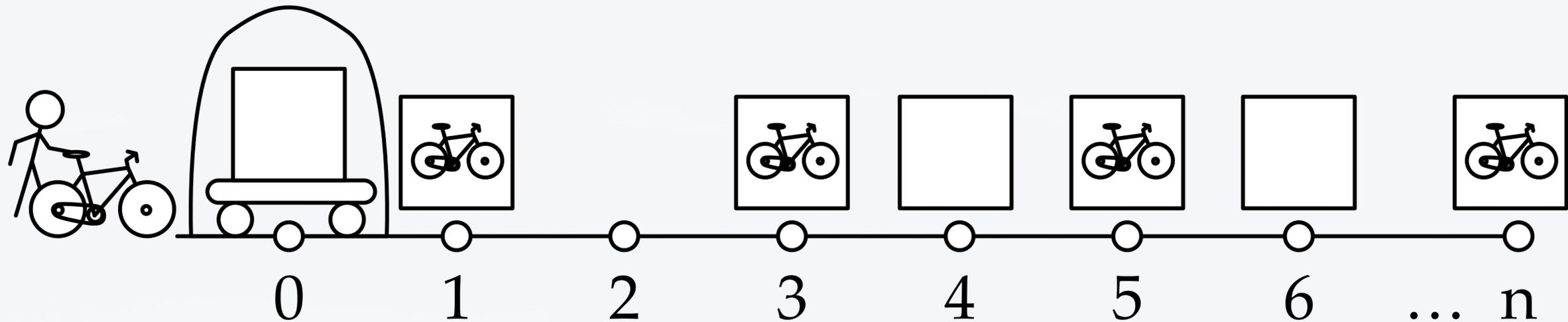
- algorithms for arrival-only with a single door
- *NP*-hardness of the two-door problem
- *NP*-hardness of the all-day problem

Sorting Problem

- algorithms for sorting on paths, trees and cycles
- *NP*-hardness for planar graphs
- *NP*-hardness for trees when minimizing swaps

Scheduling Problem



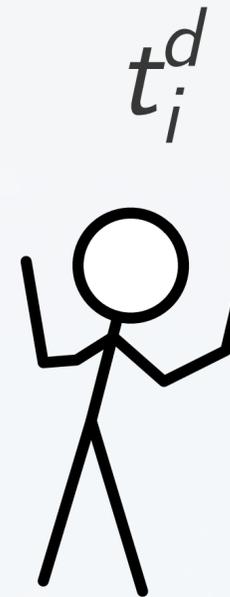


Storage System Model

- one-dimensional layout
- n slots that can store a single box each
- initially all boxes are empty
- single door for customer interaction



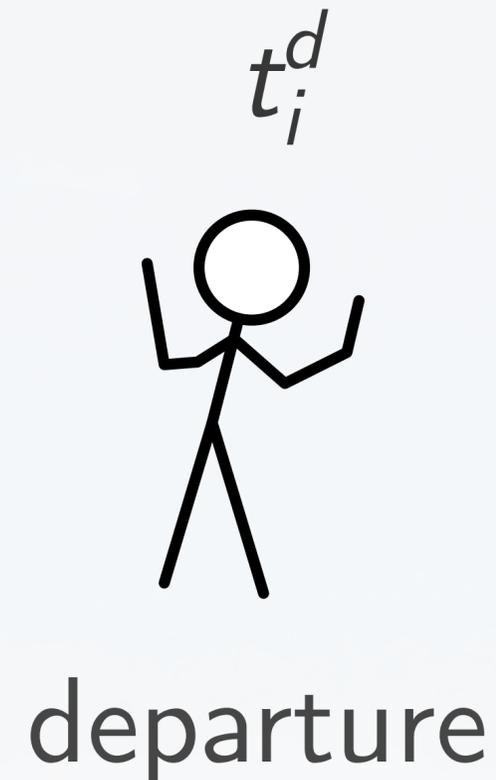
arrival



departure

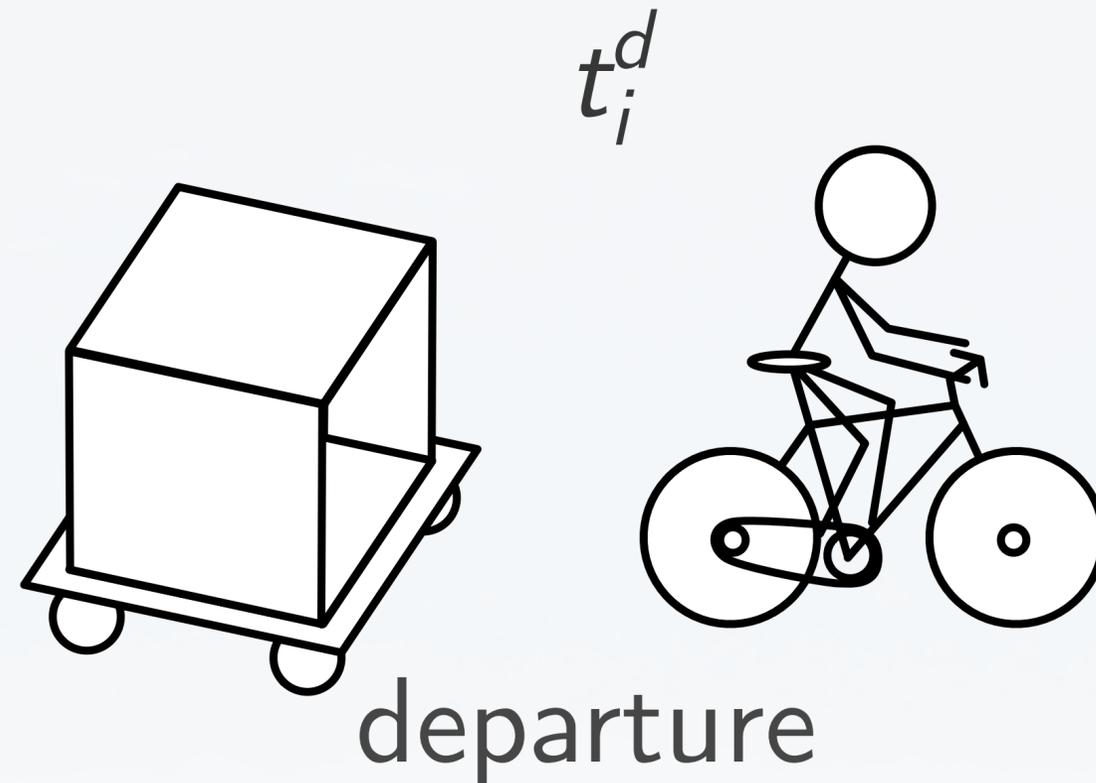
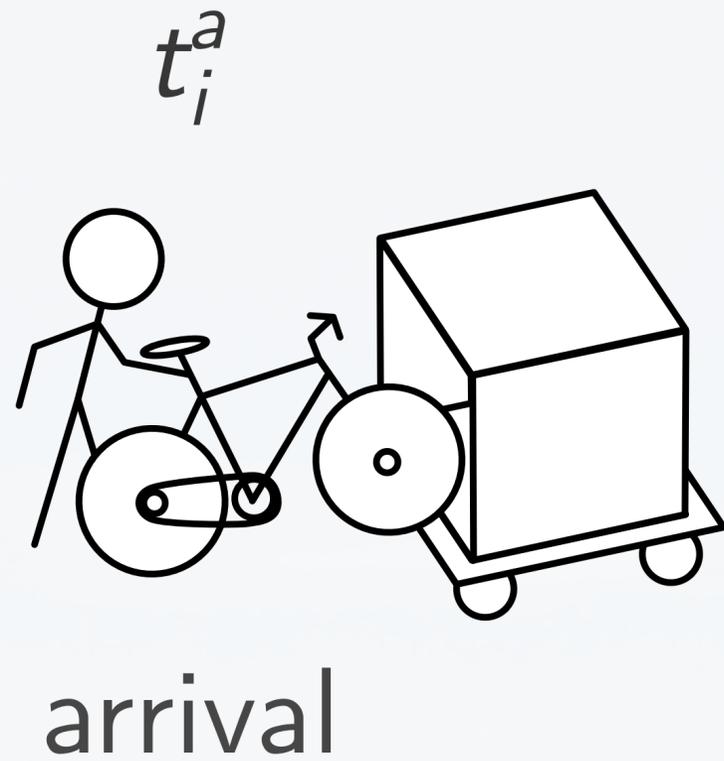
Customer Model

- m customers, each with arrival time t_i^a and departure time t_i^d that are known in advance



Customer Model

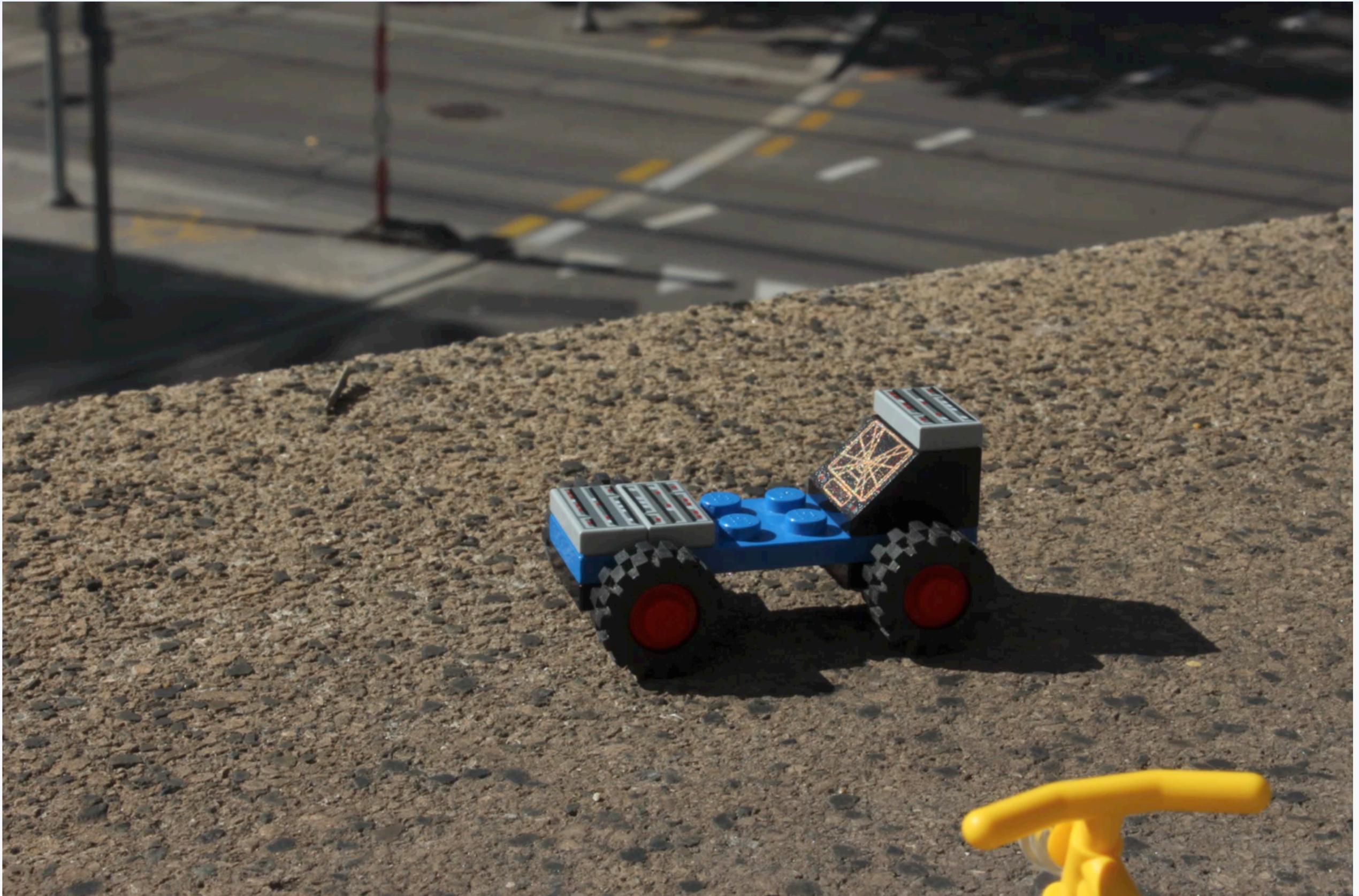
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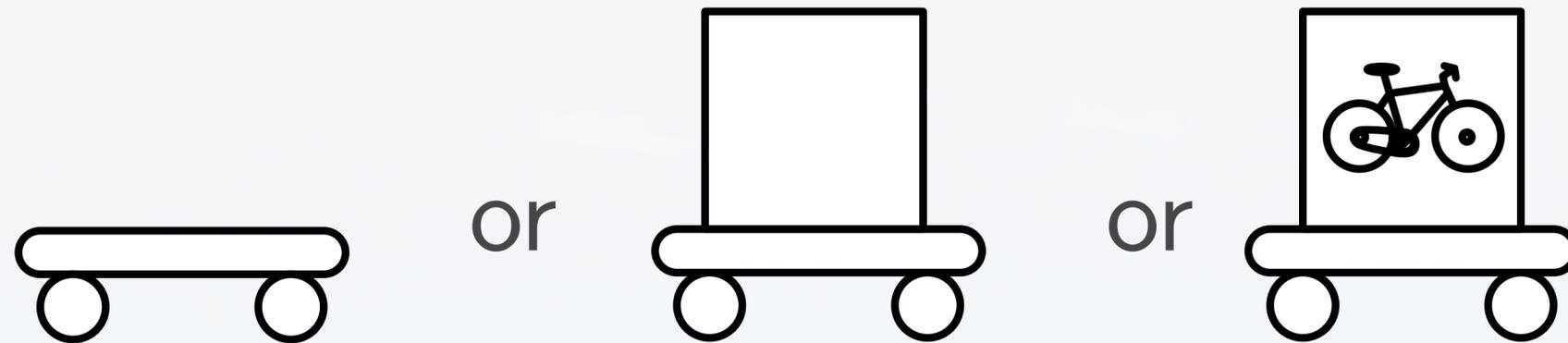
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Robot Model

- a single box at a time
- unit velocity, no acceleration
- instant box handling
- starts at the door
- distinction: can boxes be swapped or not?

Goal

- no customer should ever wait at the door
(neither for an empty box nor for his bike)

Task

- find a robot schedule that achieves this

Assumption

- boxes not rearranged while in storage

Early morning scenario - no departures yet.



Every slot can be used for at most one customer.

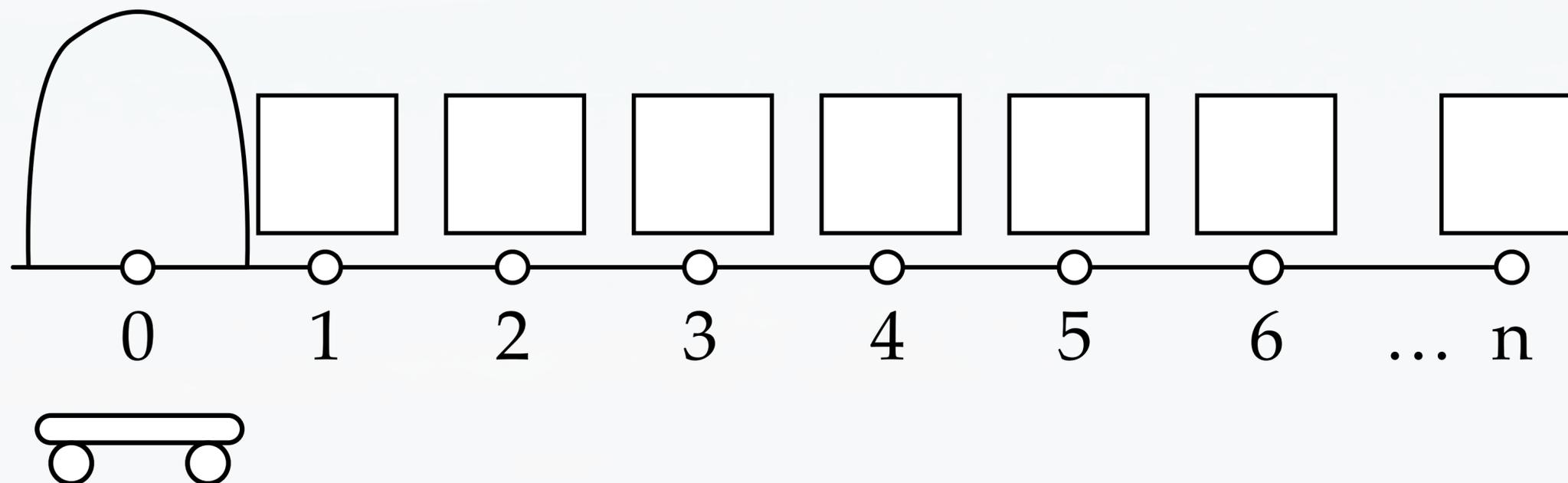
If $n = m$, we can describe the schedule by a permutation $\pi \in S_n$.

The box of customer i gets stored at slot $\pi(i)$.

Which permutations correspond to feasible, wait-free robot schedules?

No swaps and initially no box on the robot.

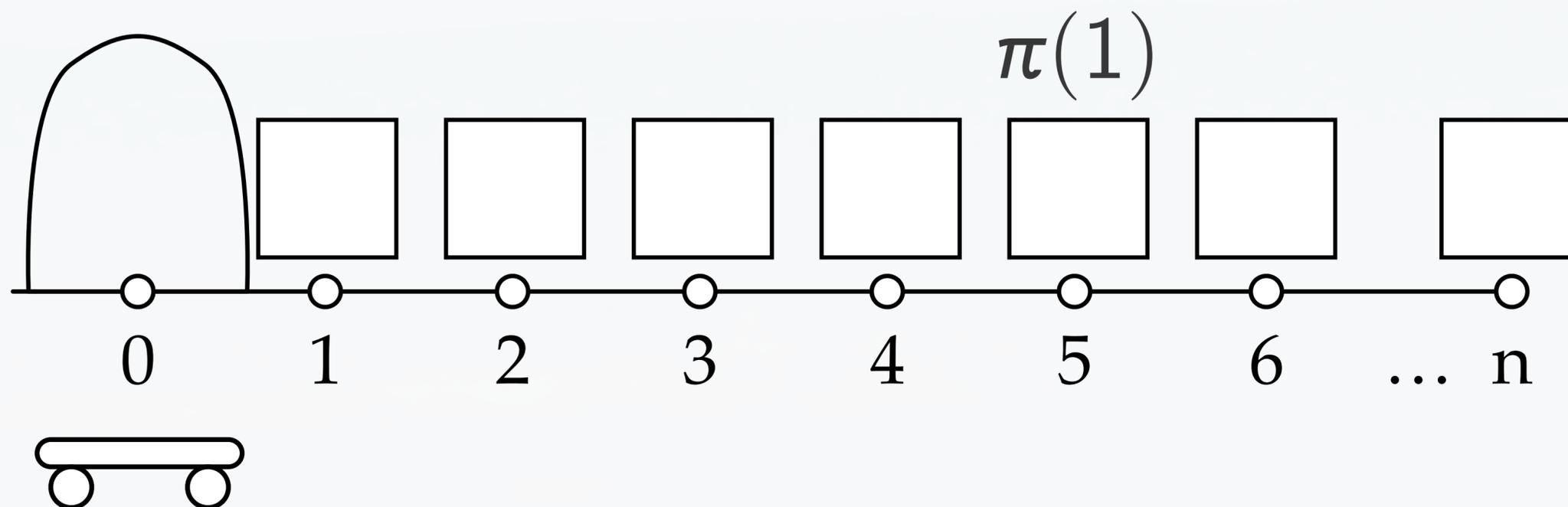
How to serve the first customer?



No swaps and initially no box on the robot.

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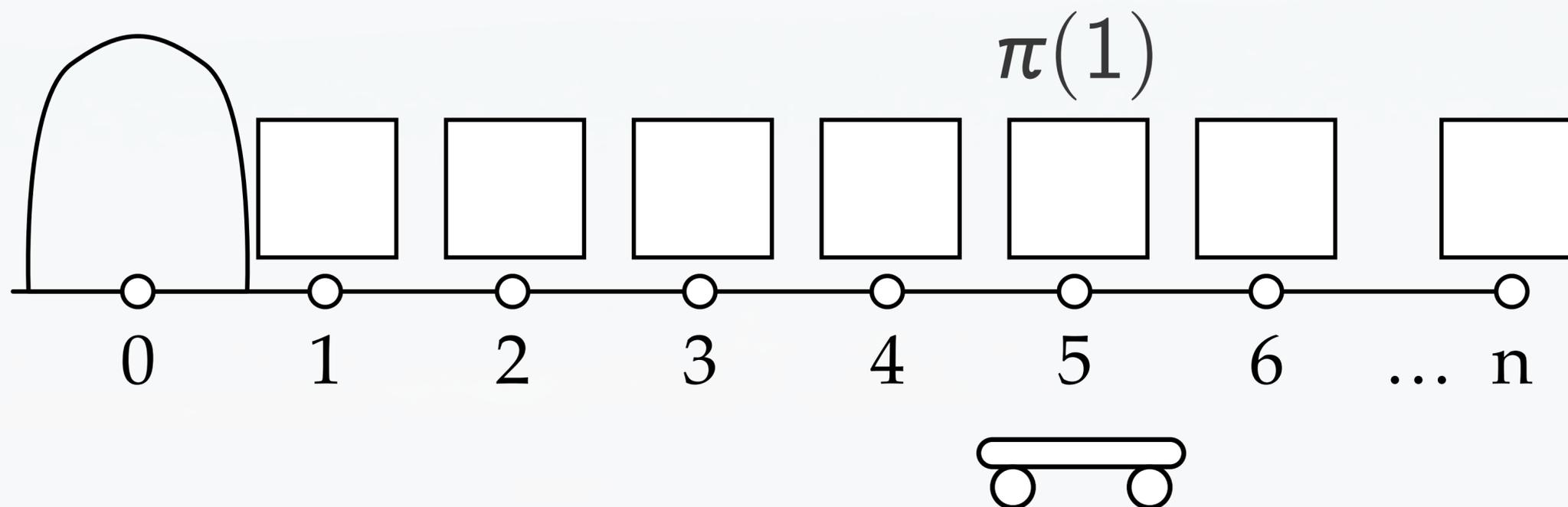
Getting the empty box at slot $\pi(1)$ ready for the first customer takes time $2\pi(1)$.



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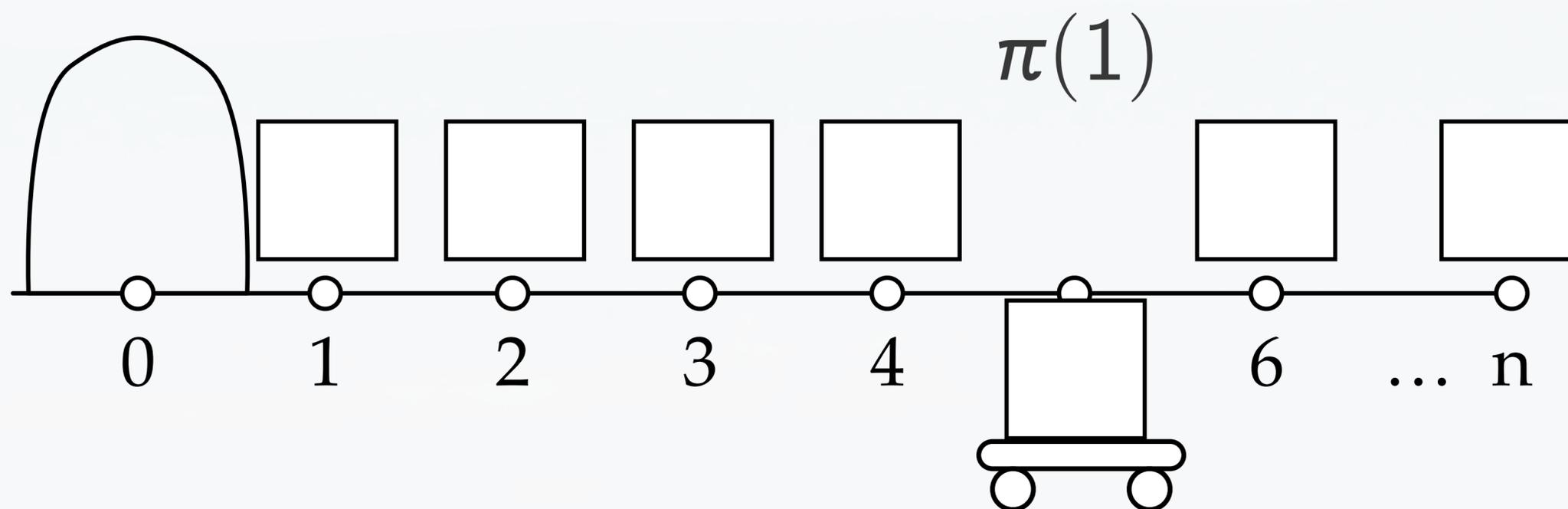
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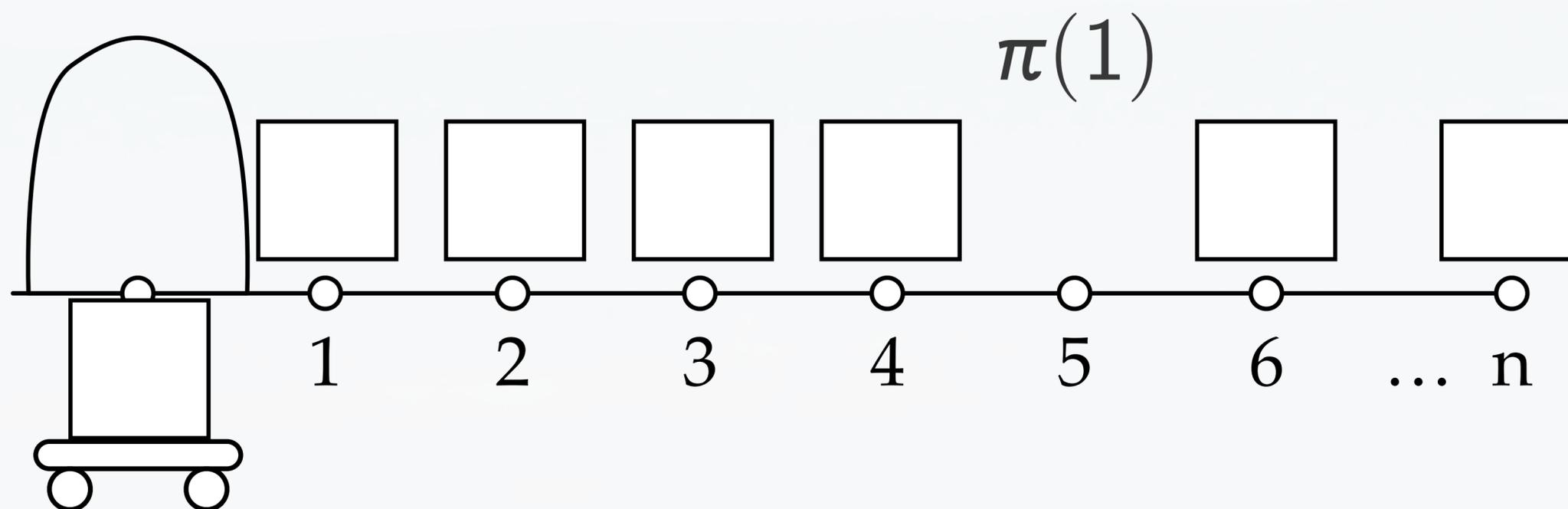
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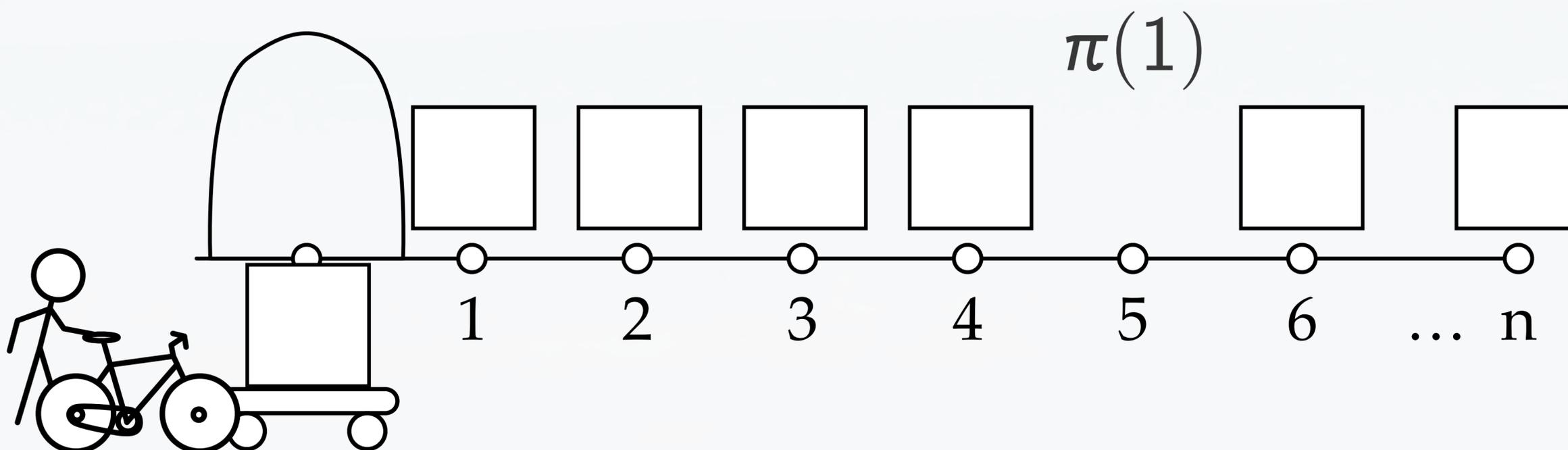
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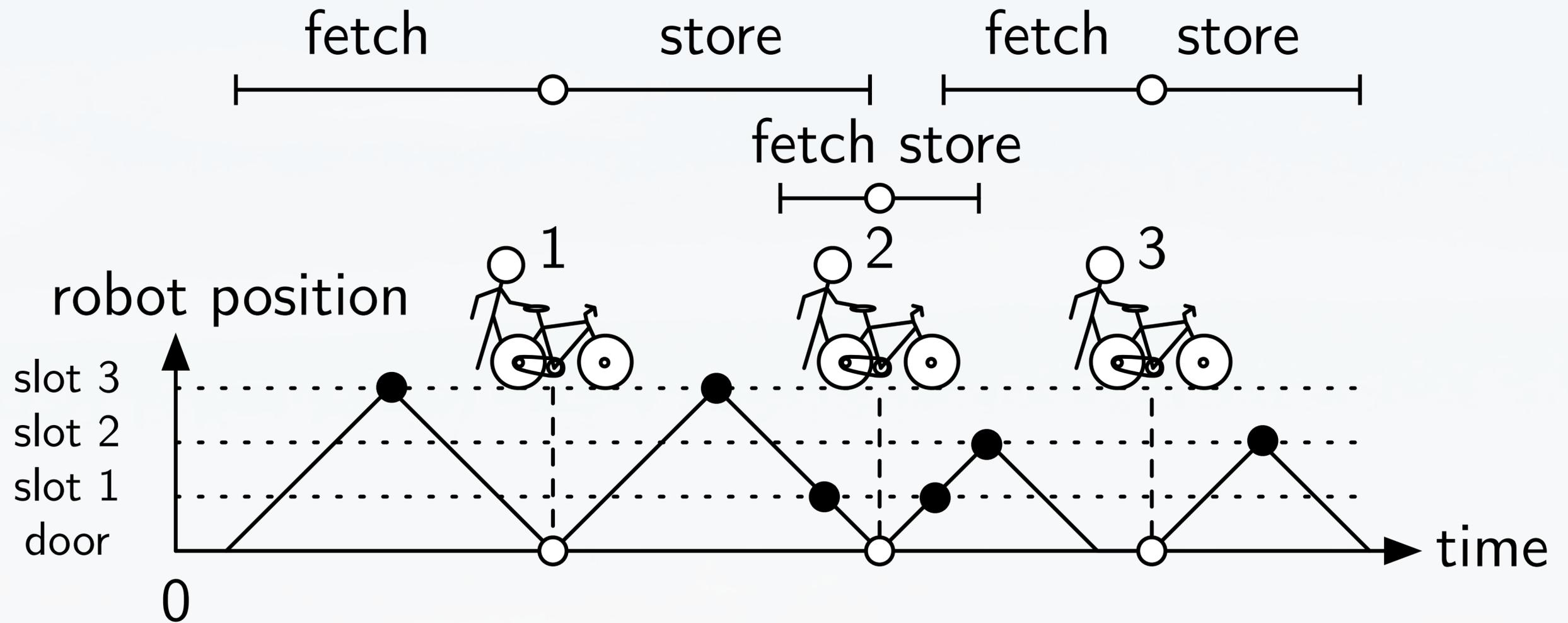
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No Swapping

Example:

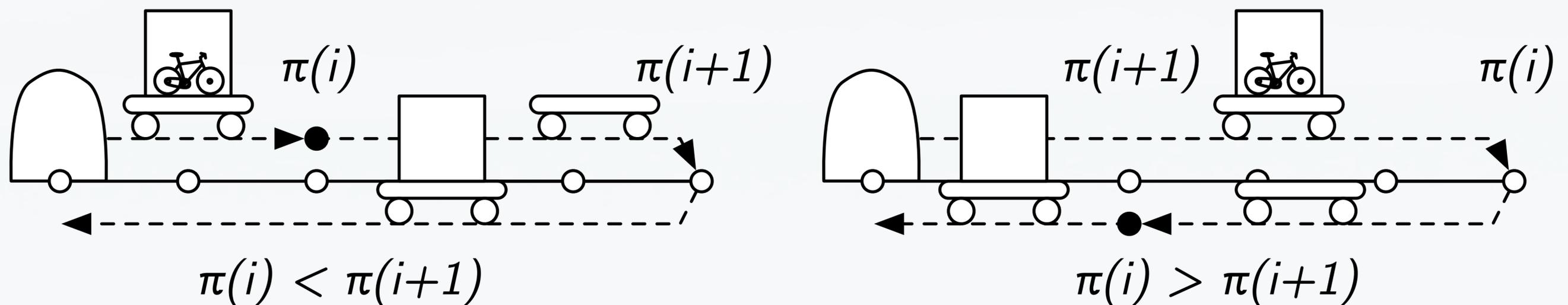


Between the arrivals of customers i and $i+1$:

- store the full box at slot $\pi(i)$
- fetch the empty box from slot $\pi(i+1)$.

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In either case, the robot needs $2 \cdot \max(\pi(i), \pi(i+1))$.

Definition: Inter request times

Let $\Delta = \{\Delta_0, \Delta_1, \dots, \Delta_n\}$, where $\Delta_i = t_{i+1}^a - t_i^a$.

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Given Δ , find π with $2 \cdot \max(\pi(i), \pi(i+1)) \leq \Delta_i$.

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Equivalently:

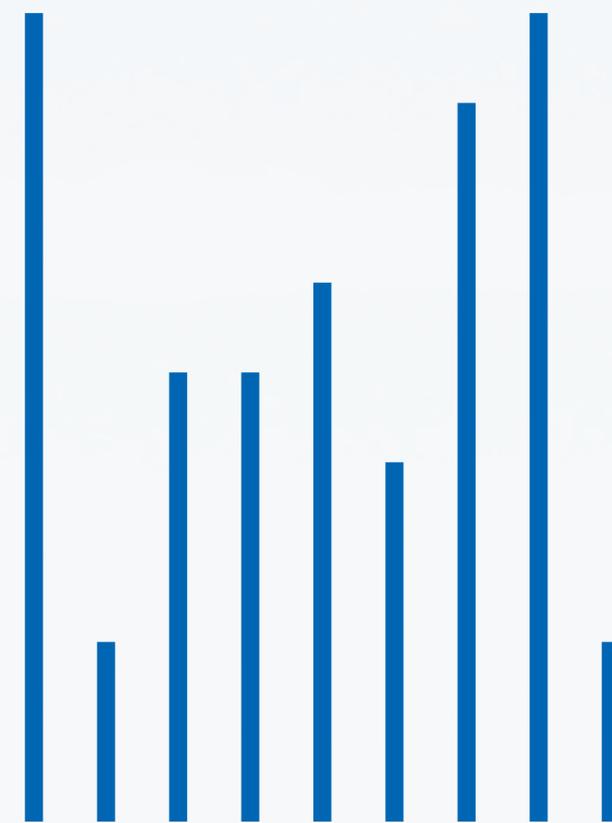
Given Δ , find π with $\pi(i) \leq \min\left(\frac{\Delta_{i-1}}{2}, \frac{\Delta_i}{2}\right)$.

Definition: Constrained Permutation problem

Given $X = \{x_1, \dots, x_n\}$, find $\pi \in S_n$ with $\pi(i) \leq x_i$.



π



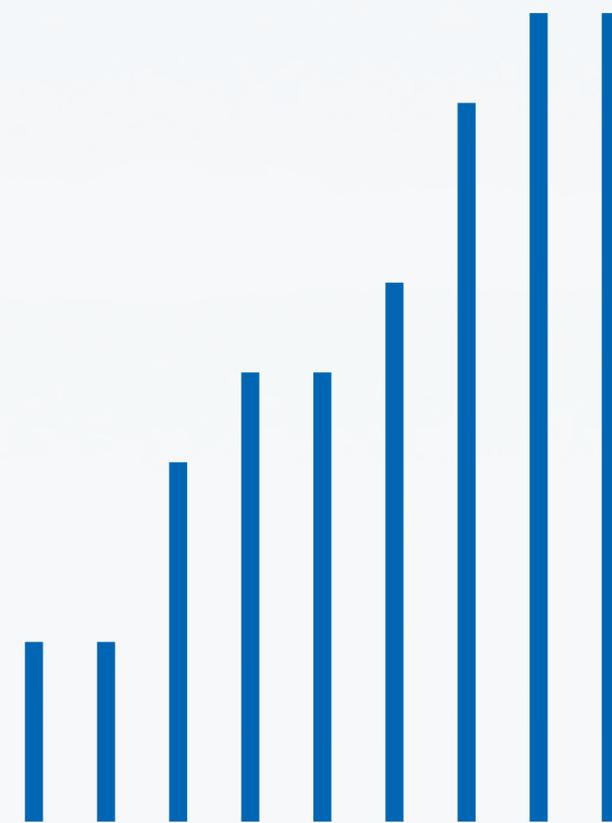
X

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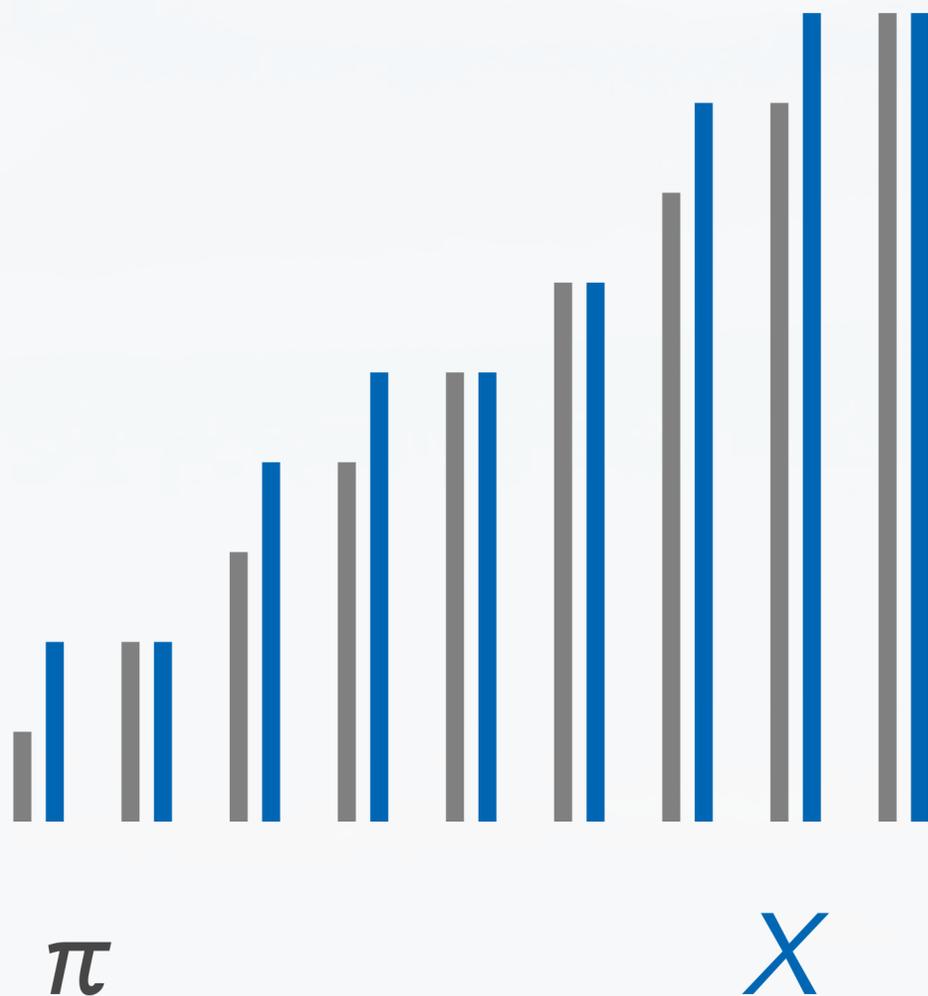
π



X

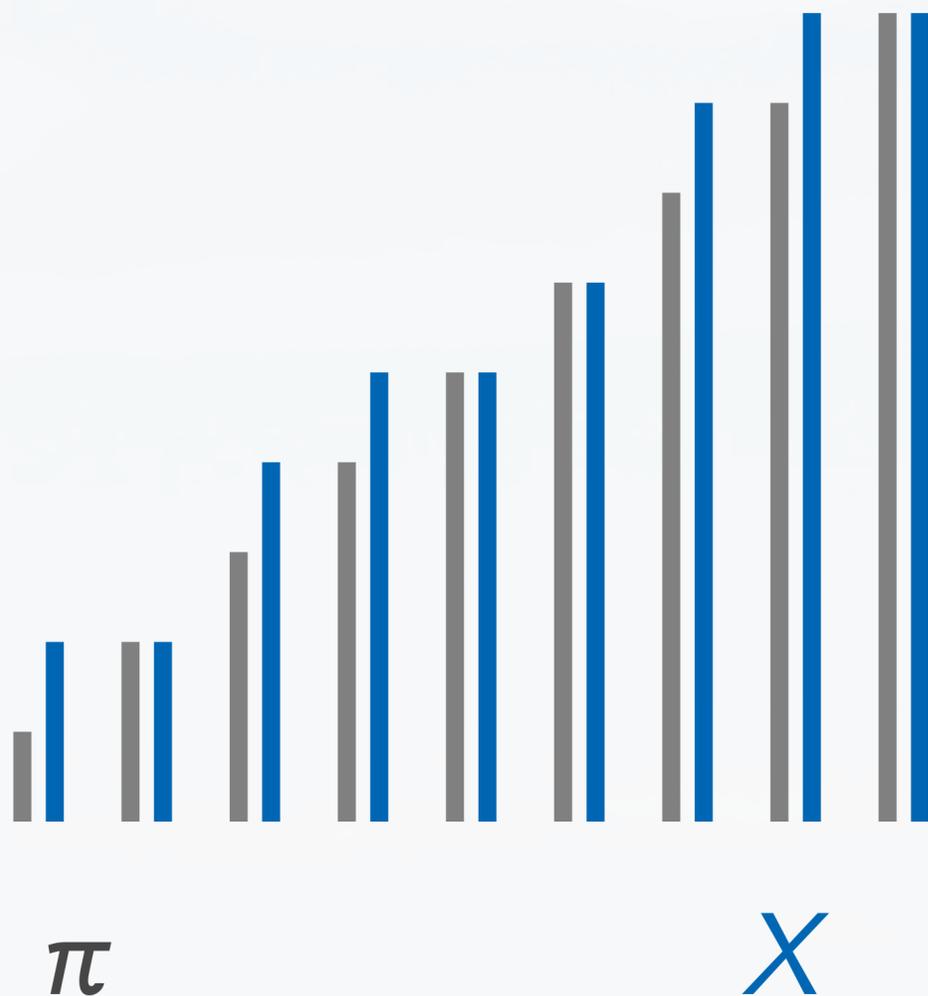
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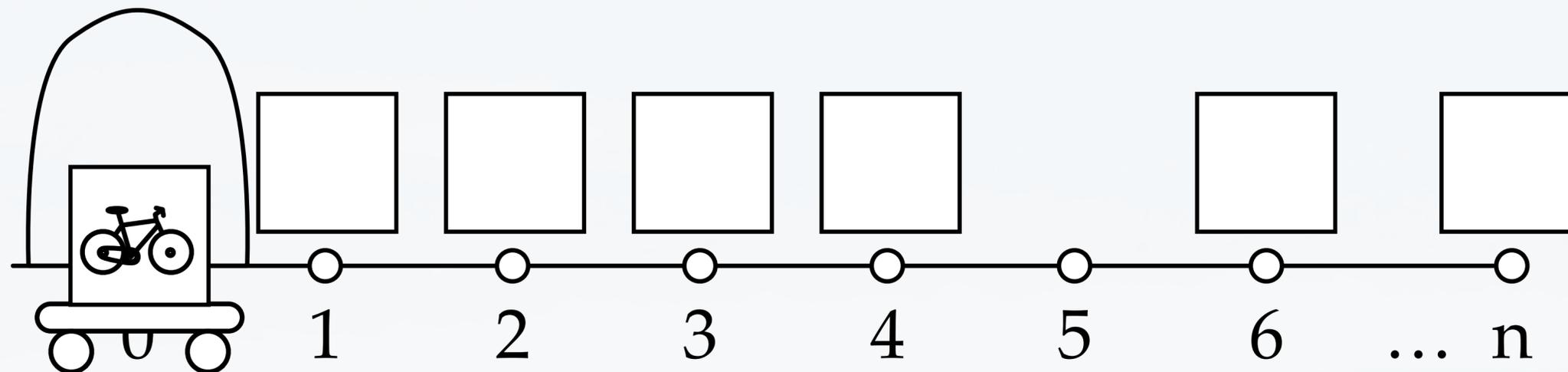
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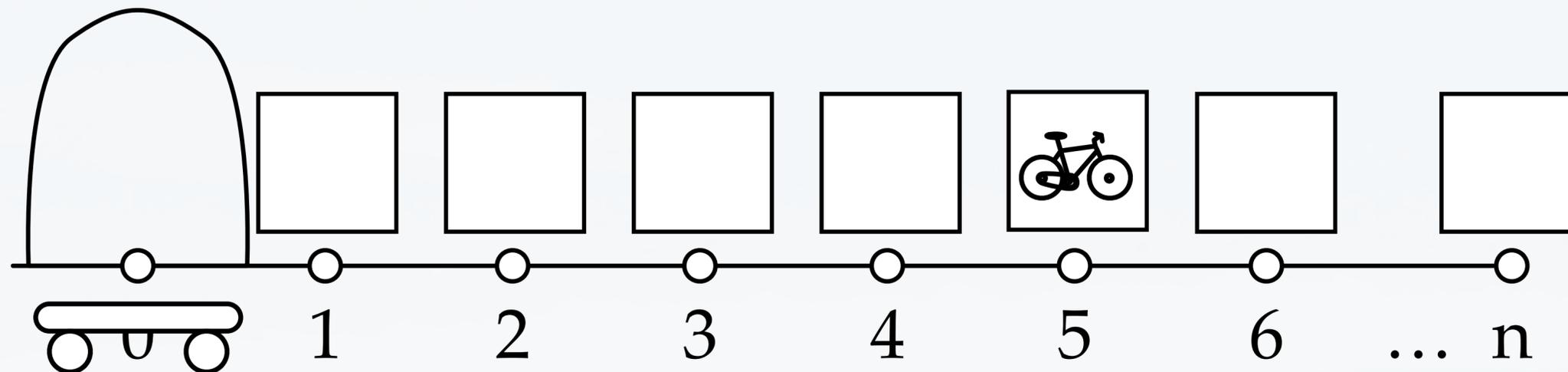
Solution:

Sort-and-compare in linear time using bucket sort.

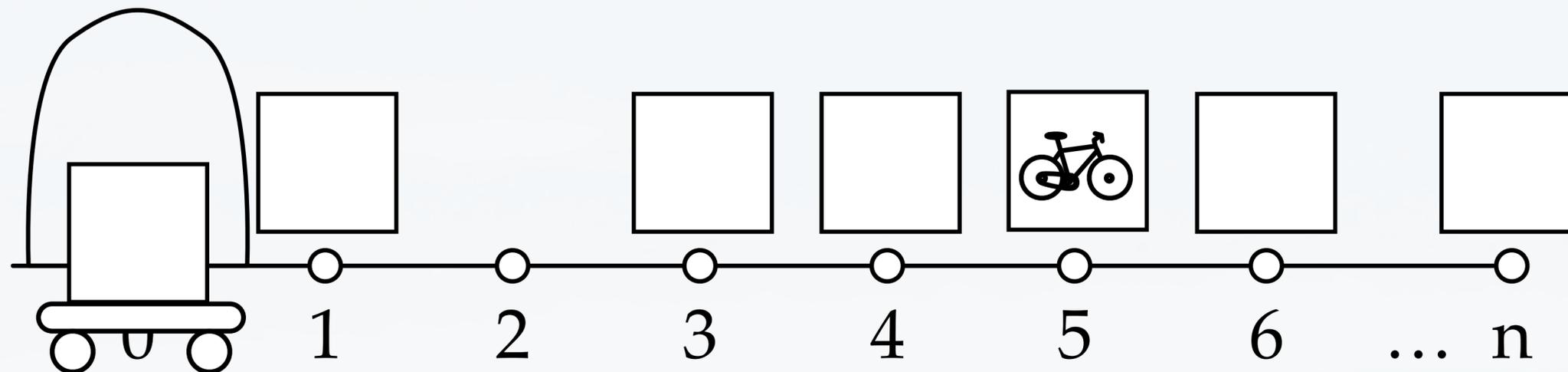
Side note: What if we let the robot always return to the door in order to decouple the requests?



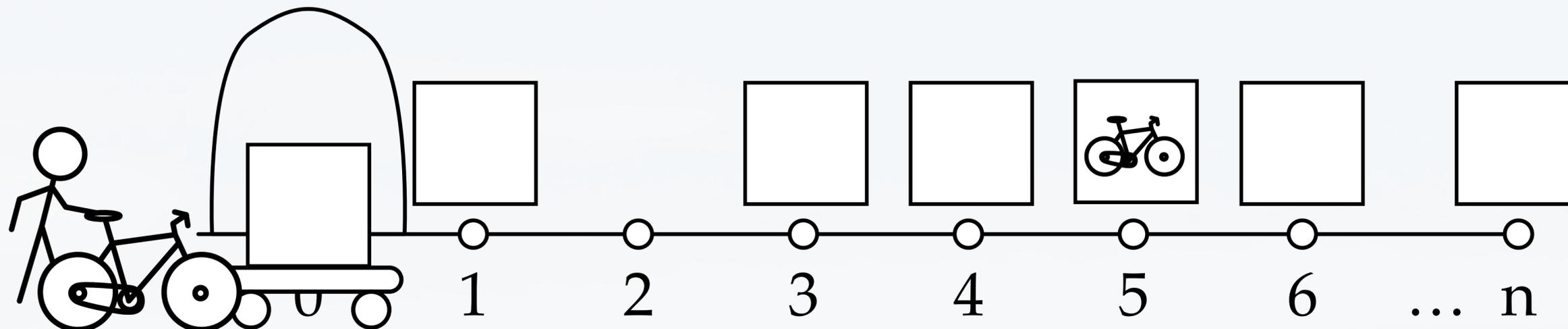
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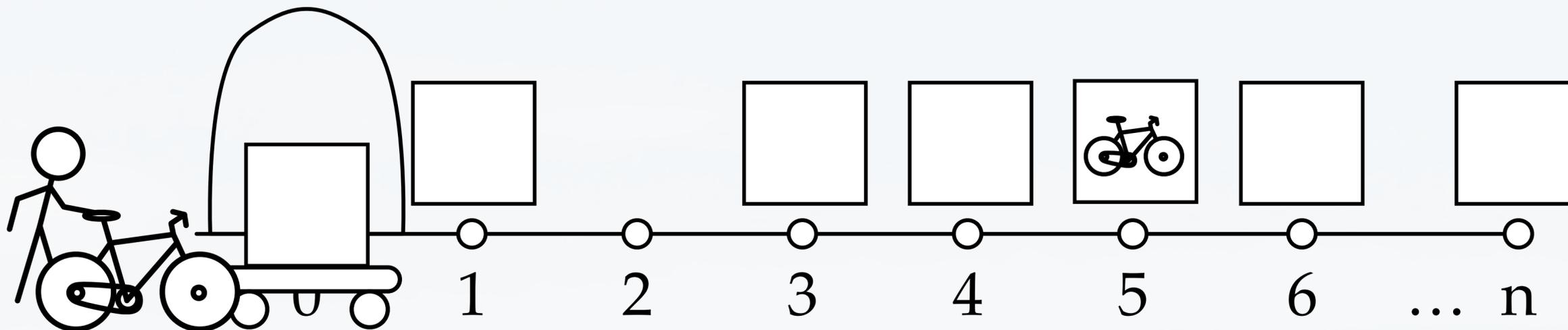
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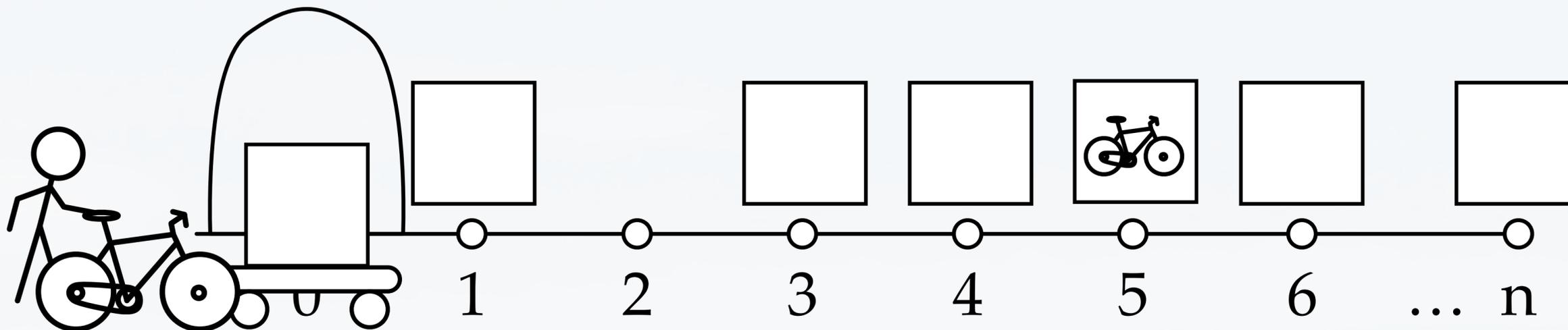
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Definition: Return Arrival-Only problem

Given Δ , find π with $2\pi(i) + 2\pi(i+1) \leq \Delta_i$.

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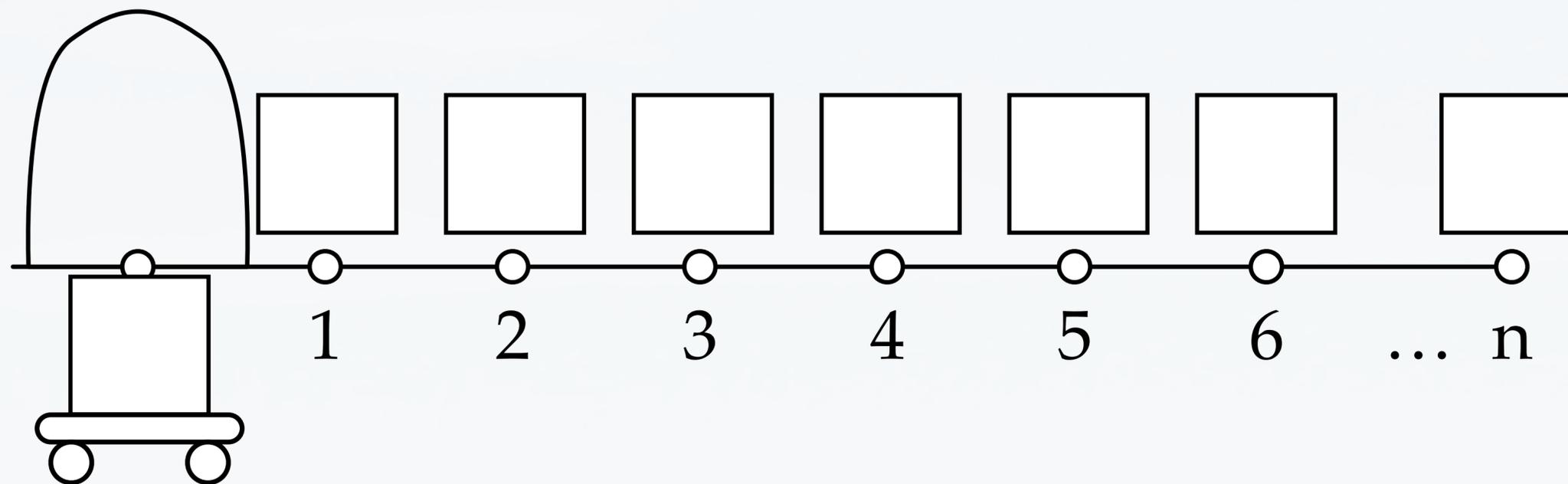


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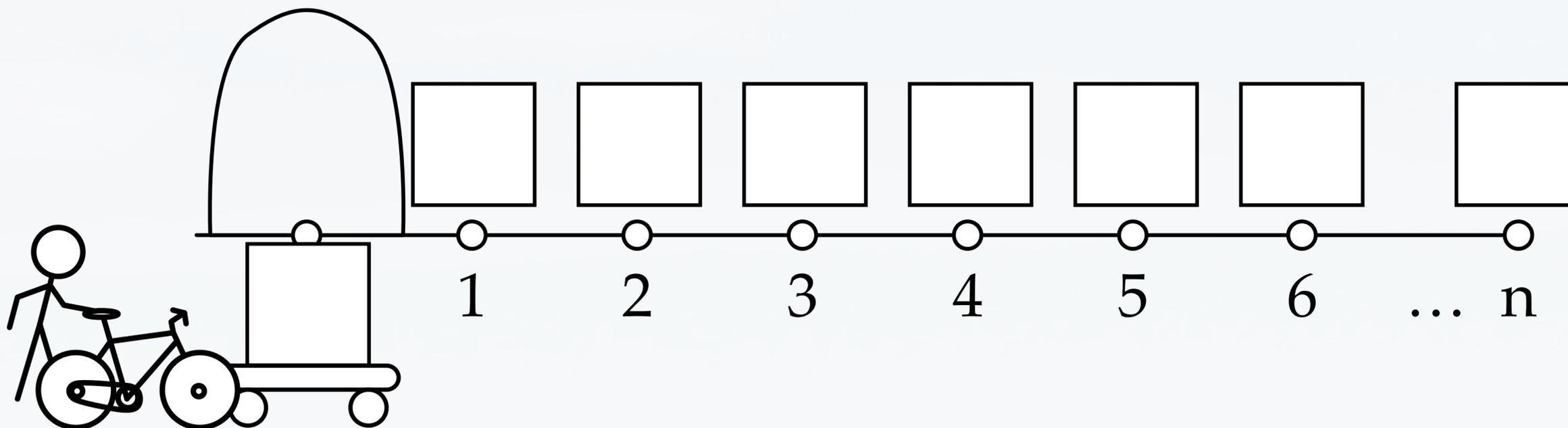
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[2015, Couëtoux, Labourel] Strongly *NP*-complete.

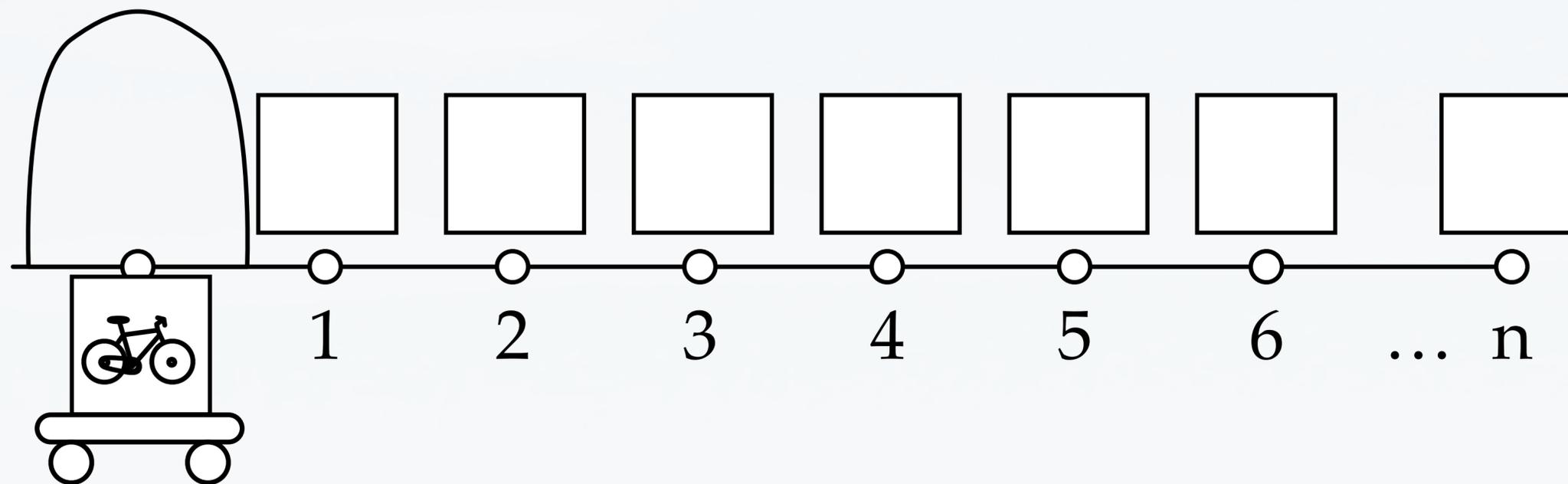
Allow swaps and start with a box on the robot.



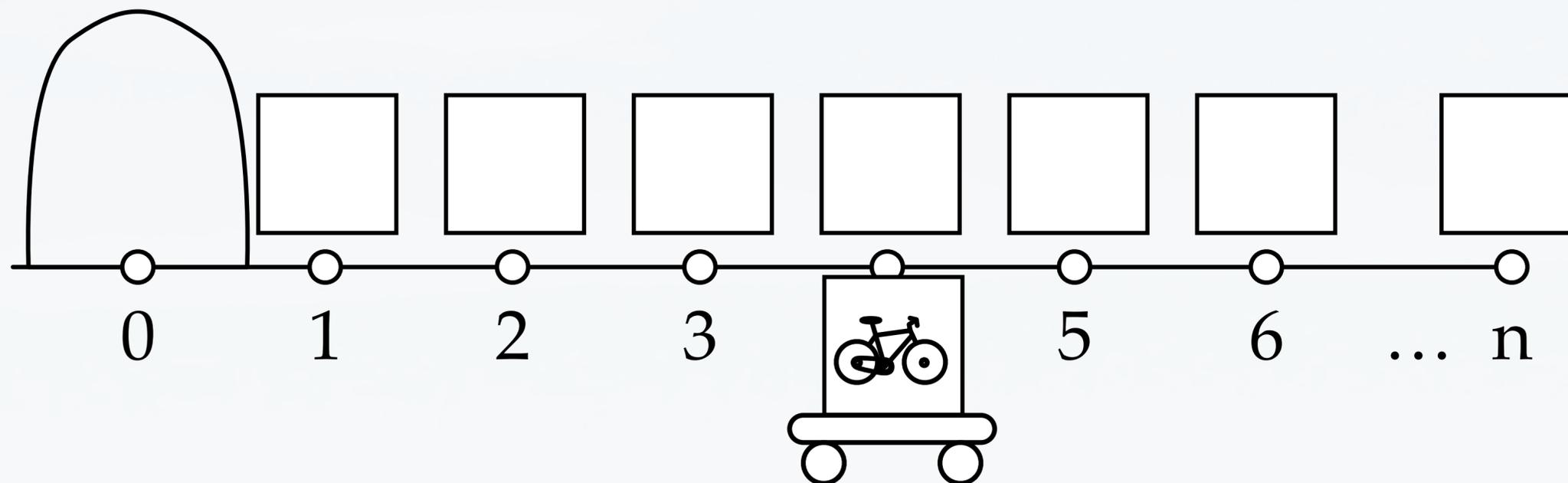
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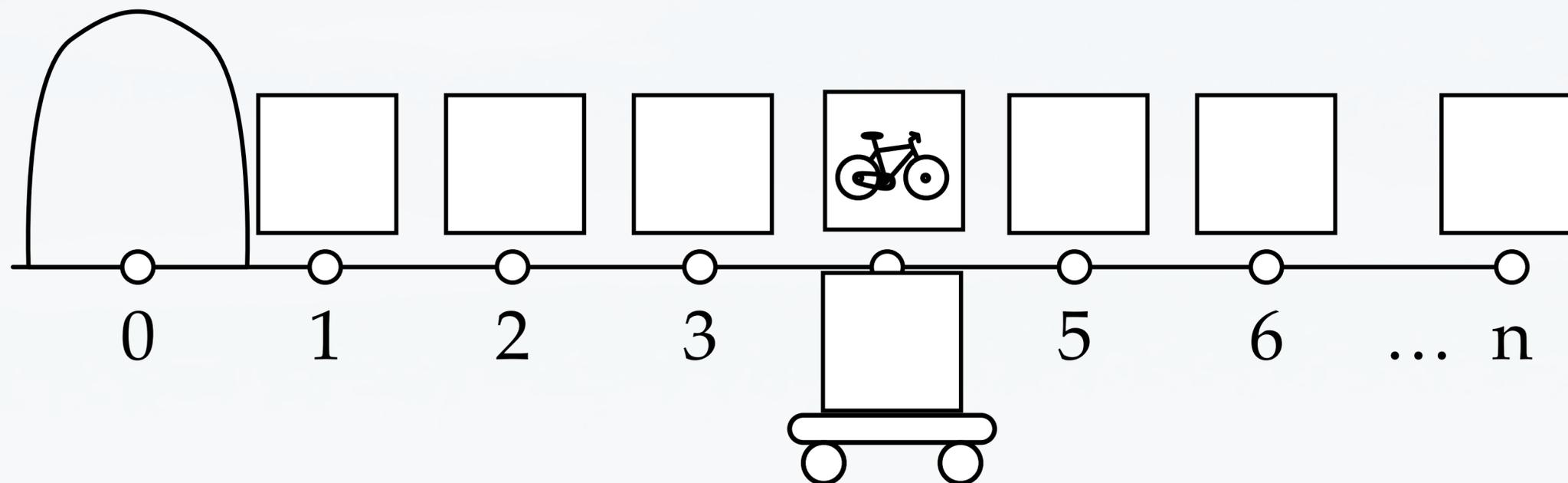
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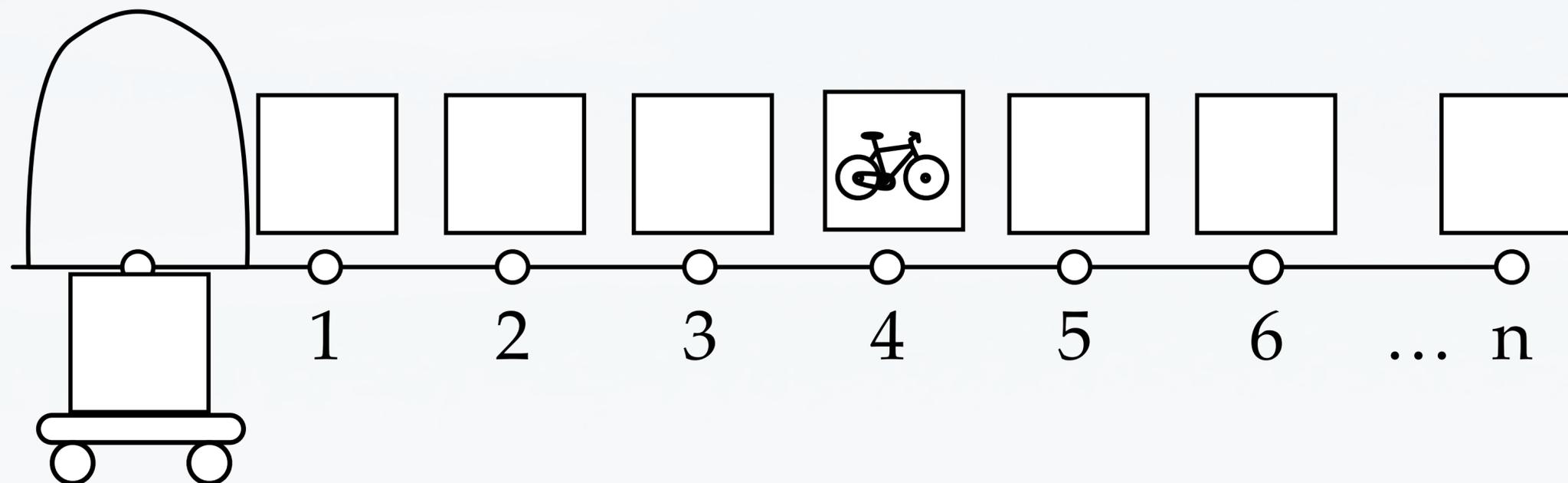
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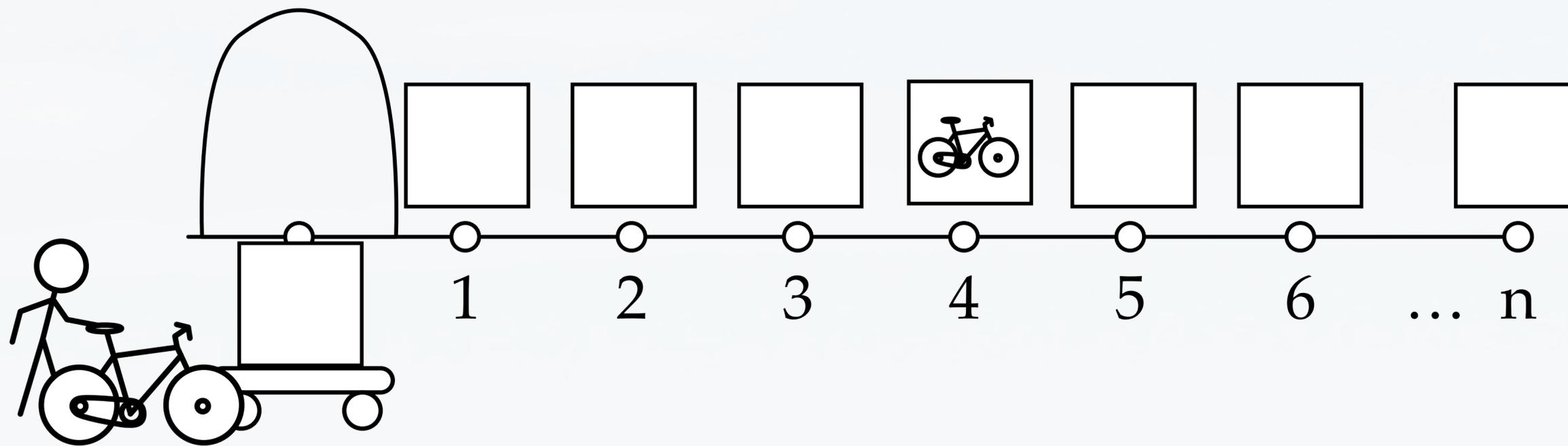
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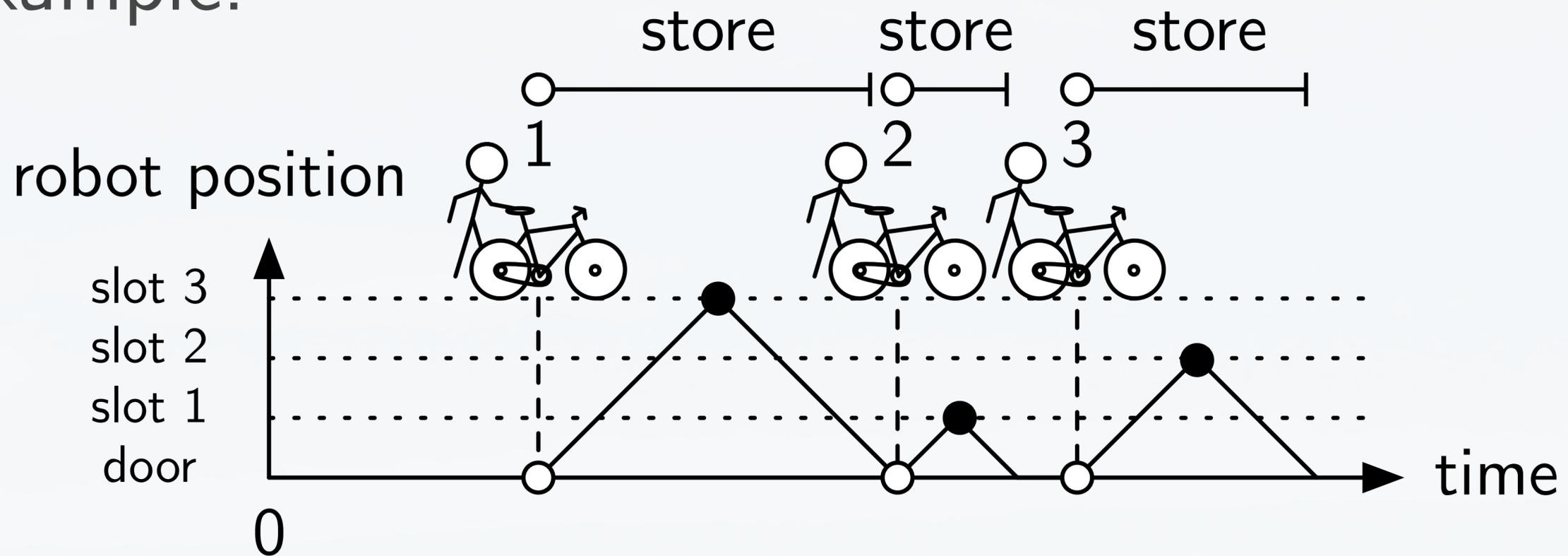
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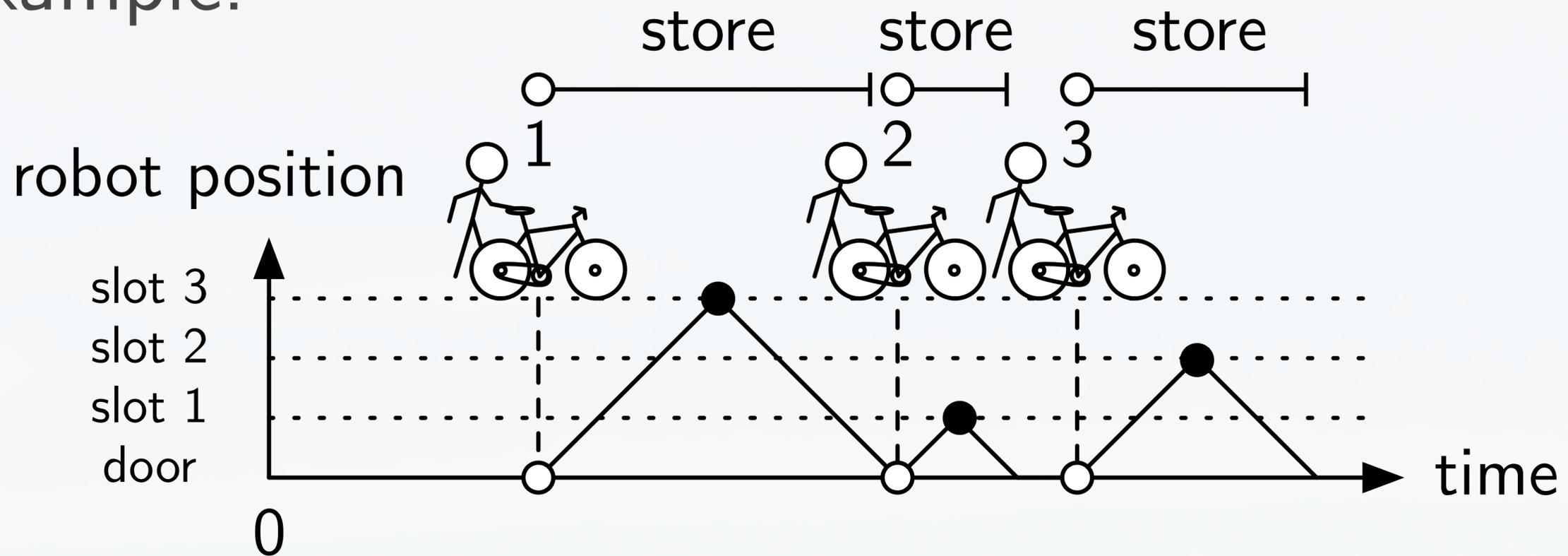
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Example:



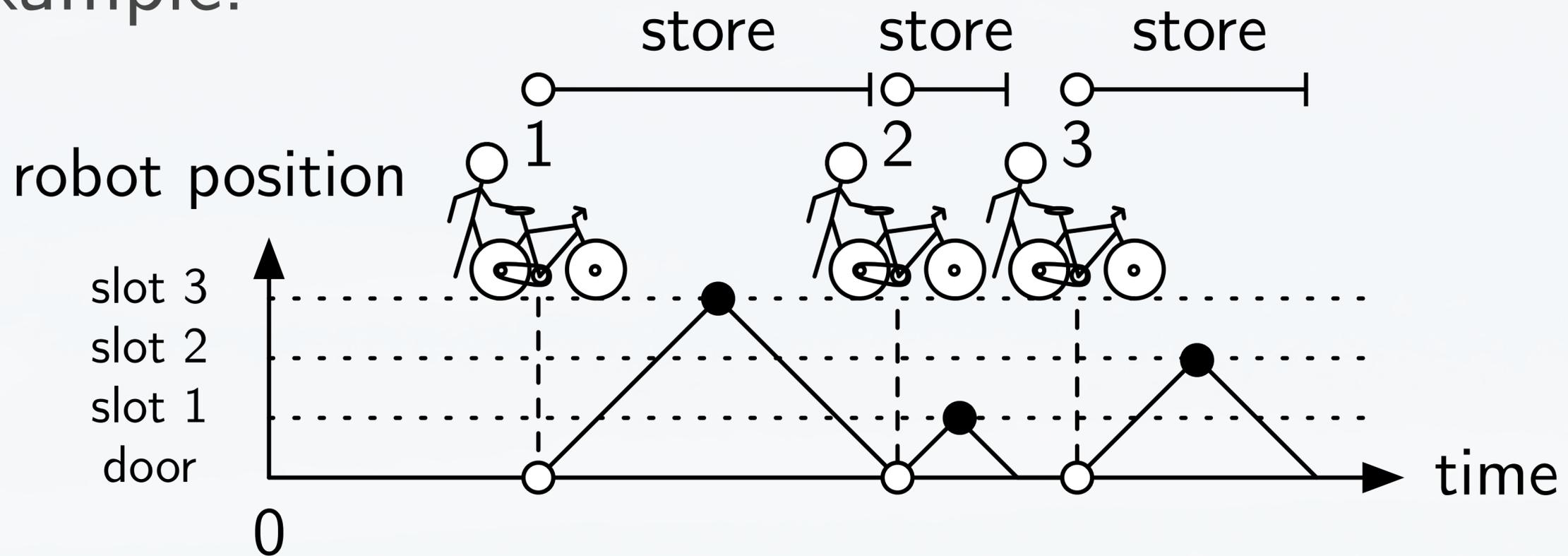
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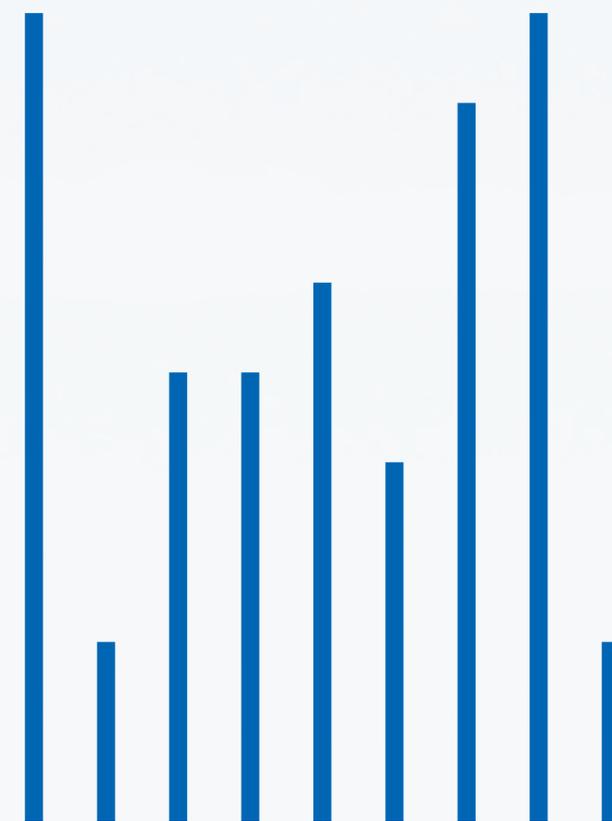
→ *decide with sort-and-compare*

Alternative approach: Greedy assignment

Go through the constraints in order and use the largest possible, unassigned permutation entry.



π



X

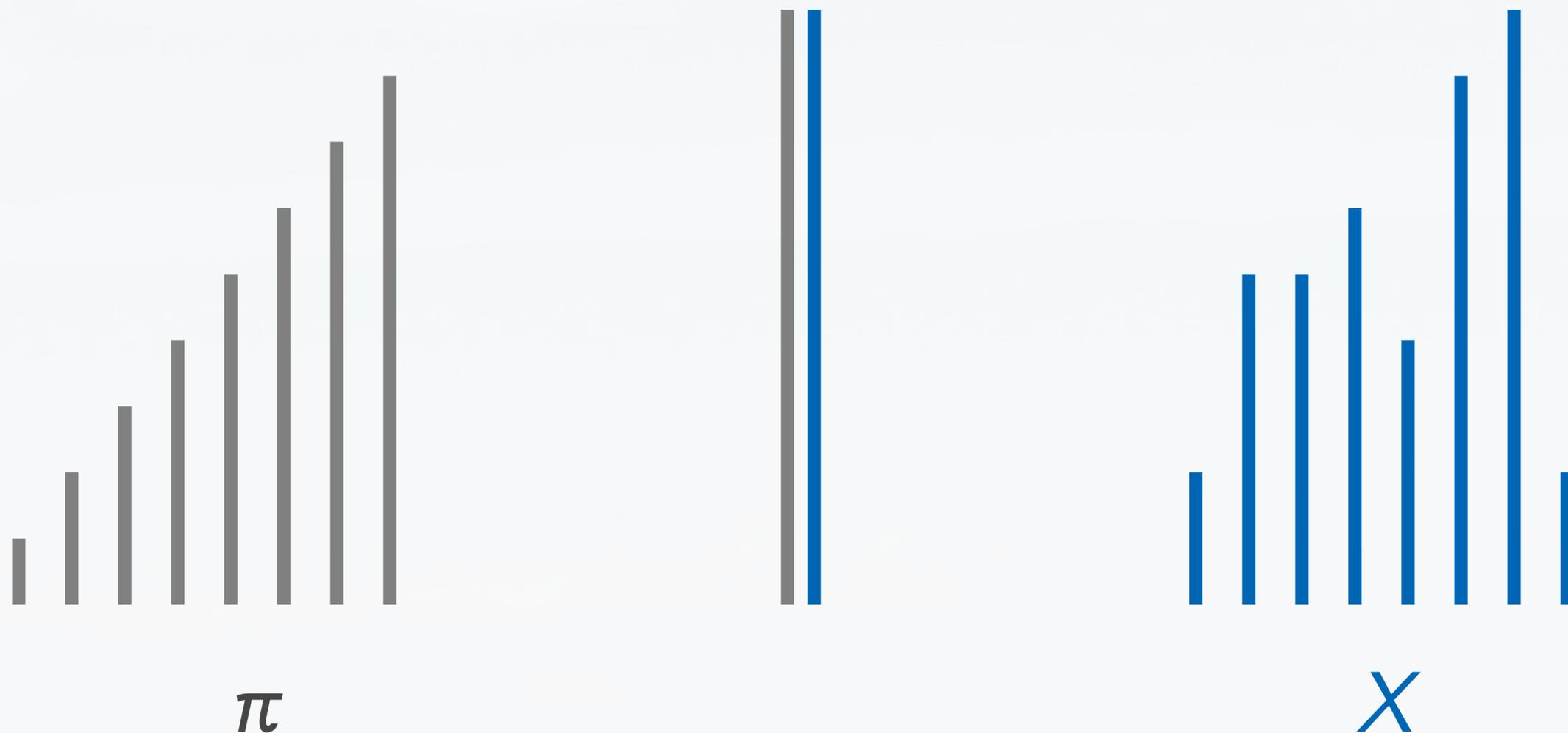
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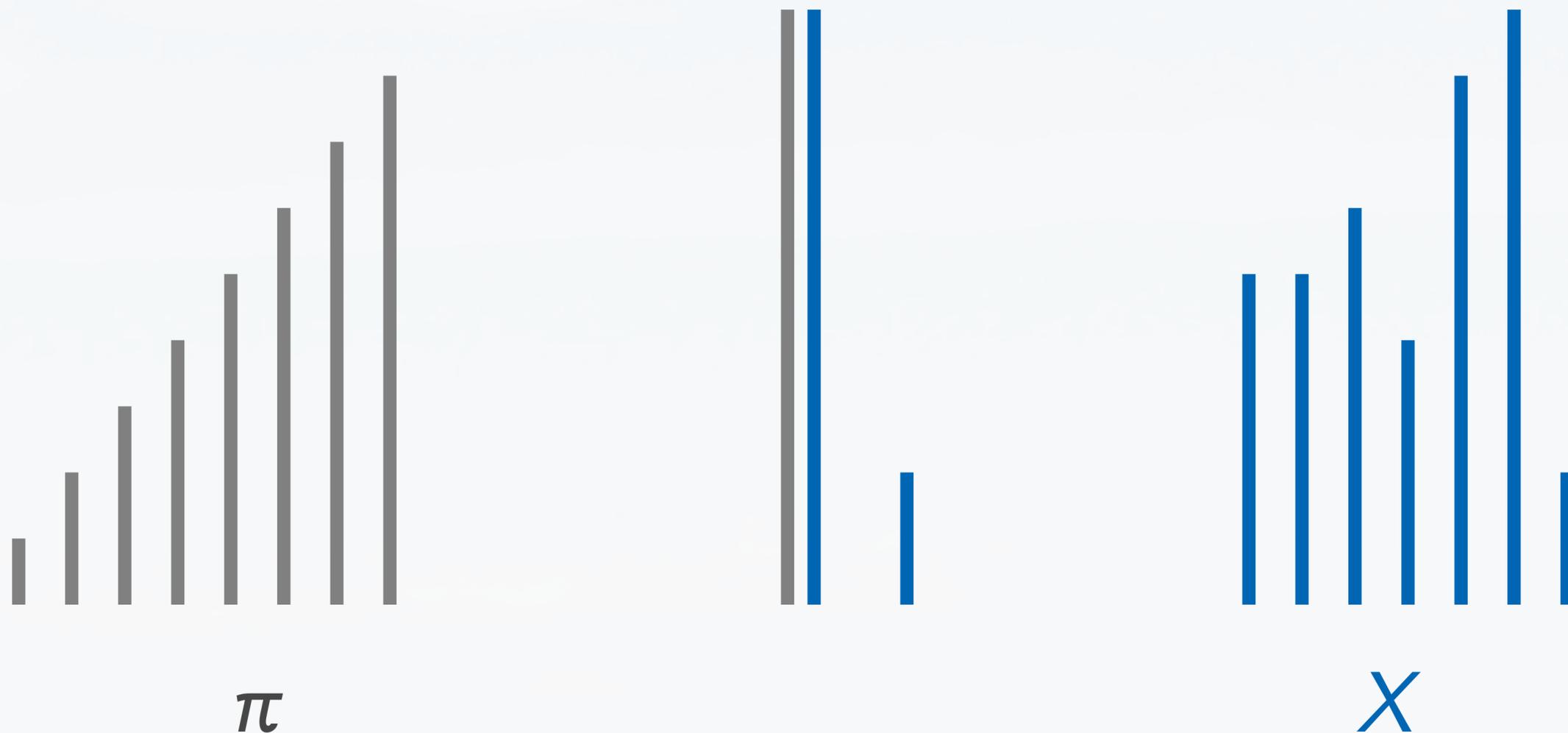
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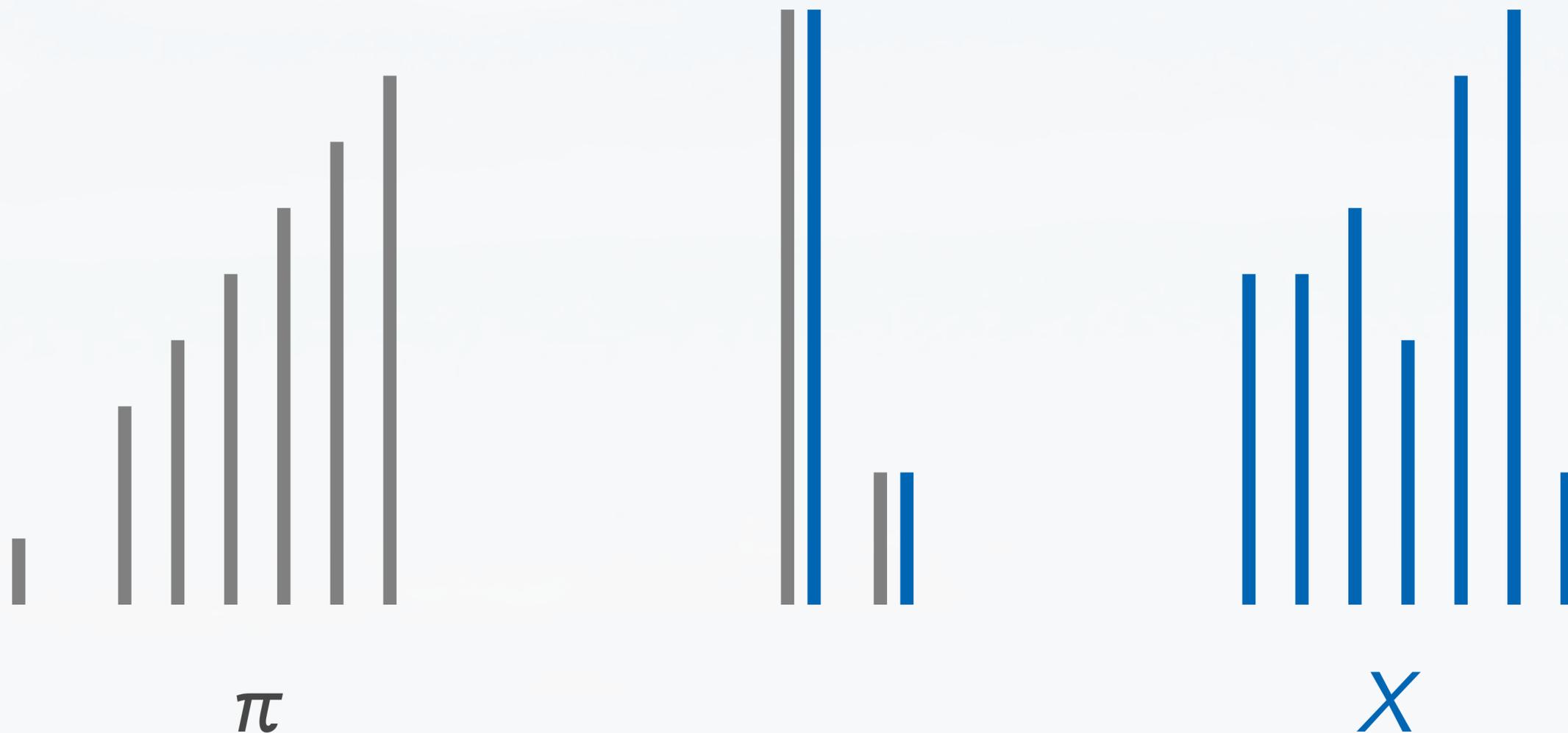
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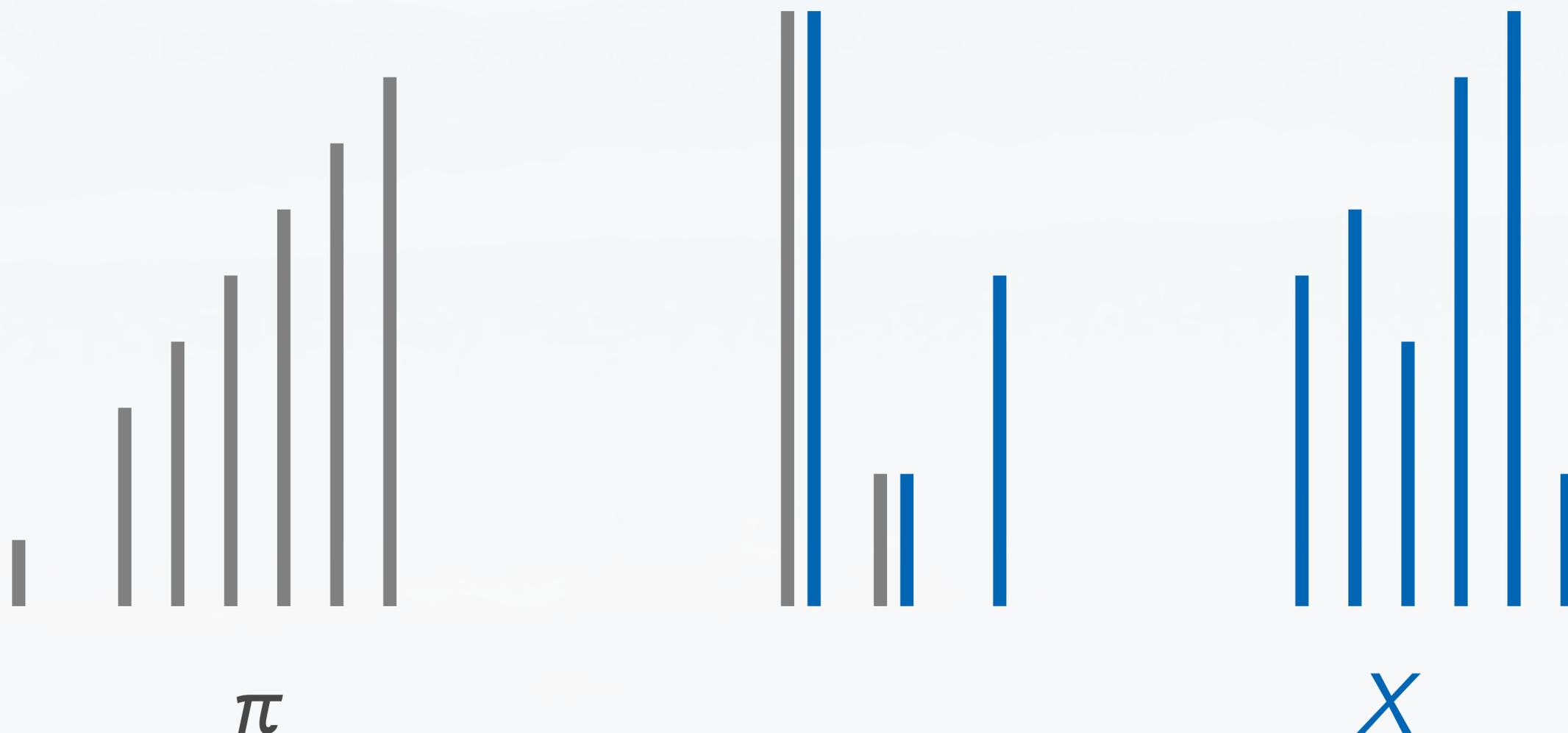
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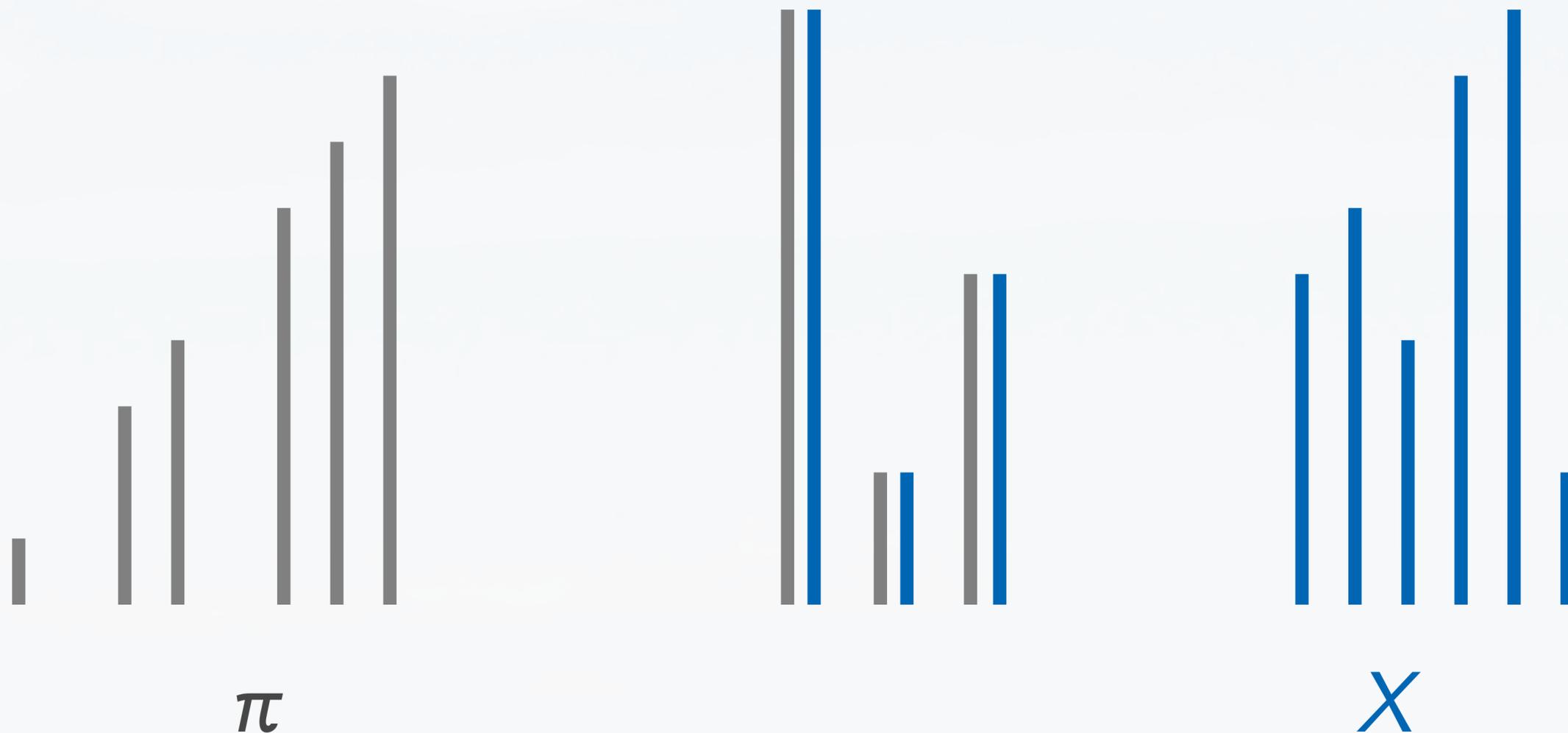
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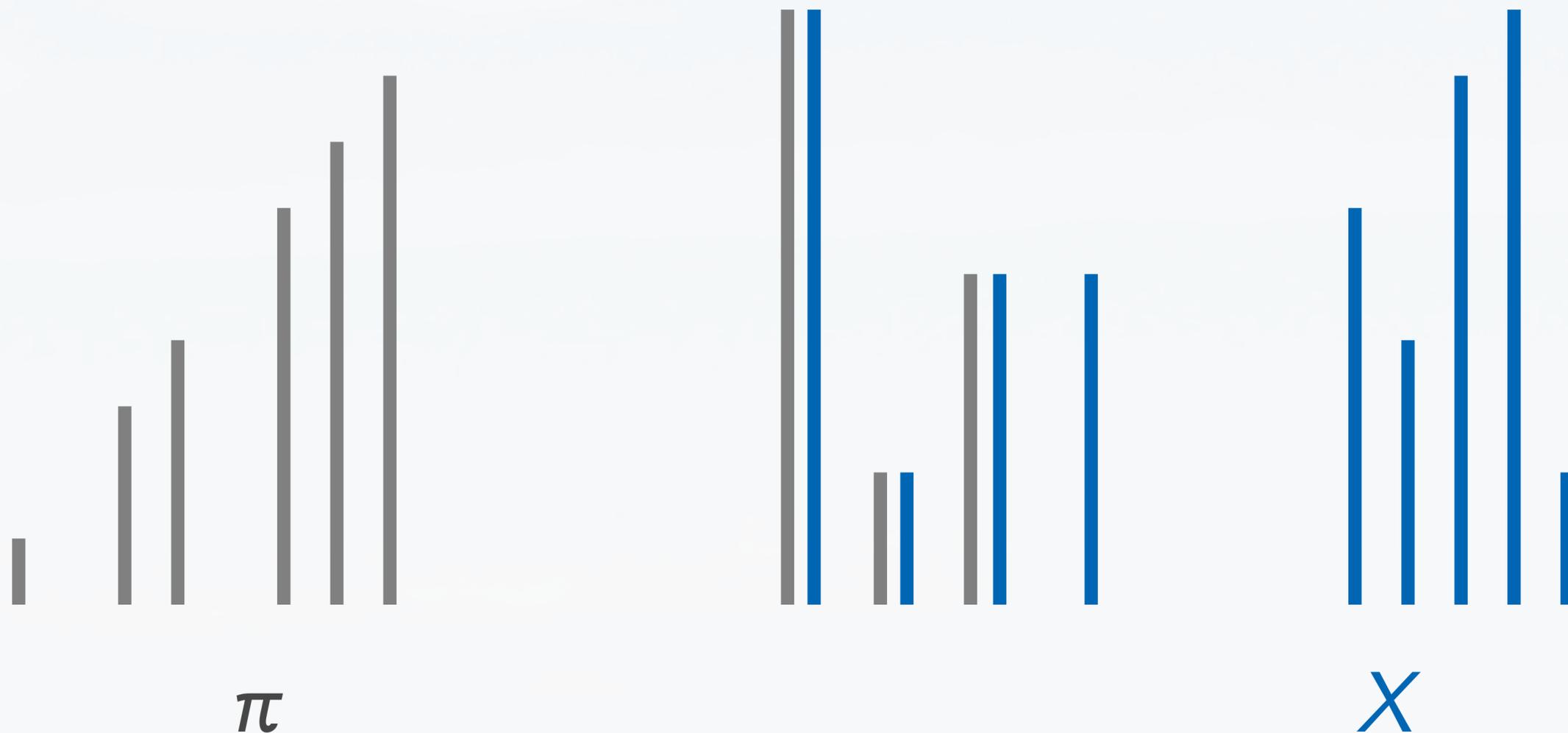
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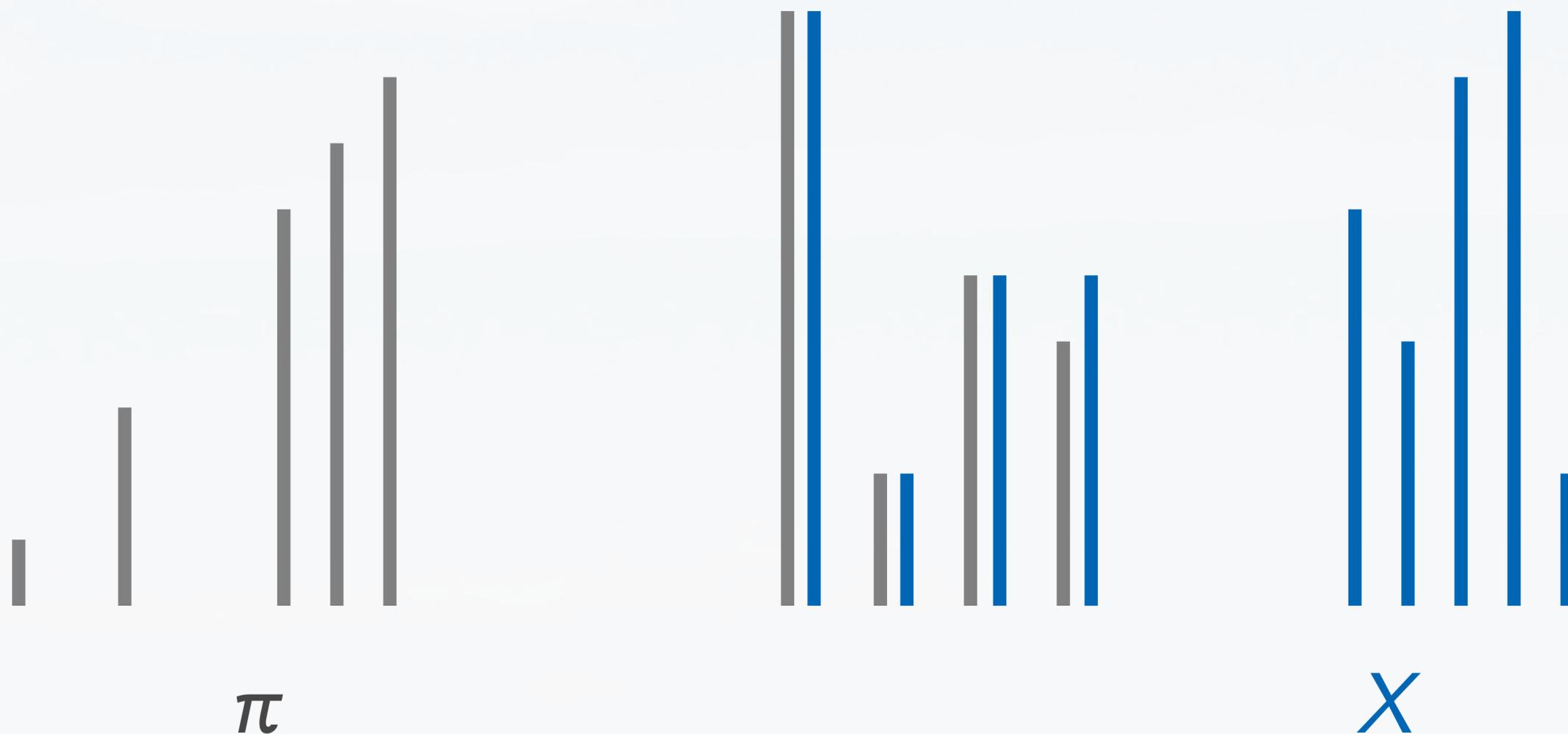
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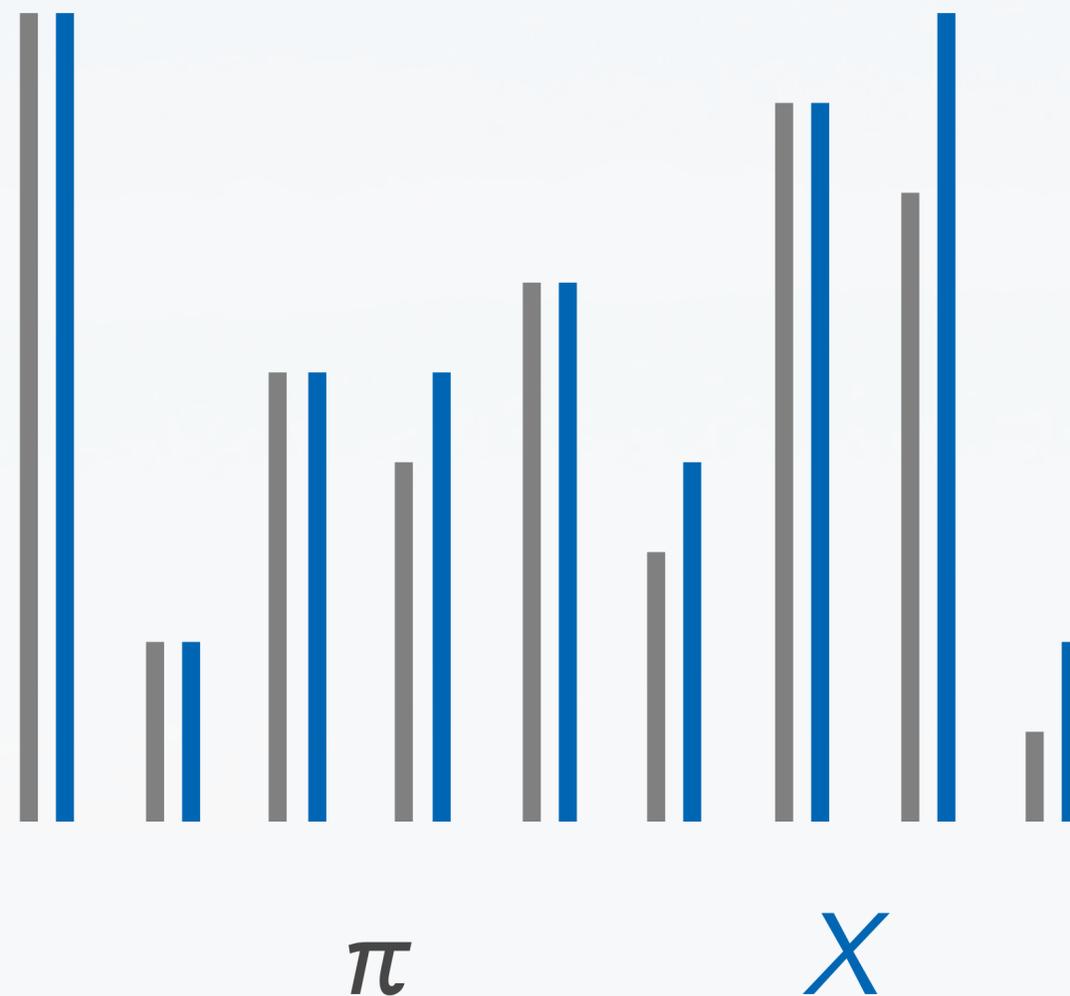
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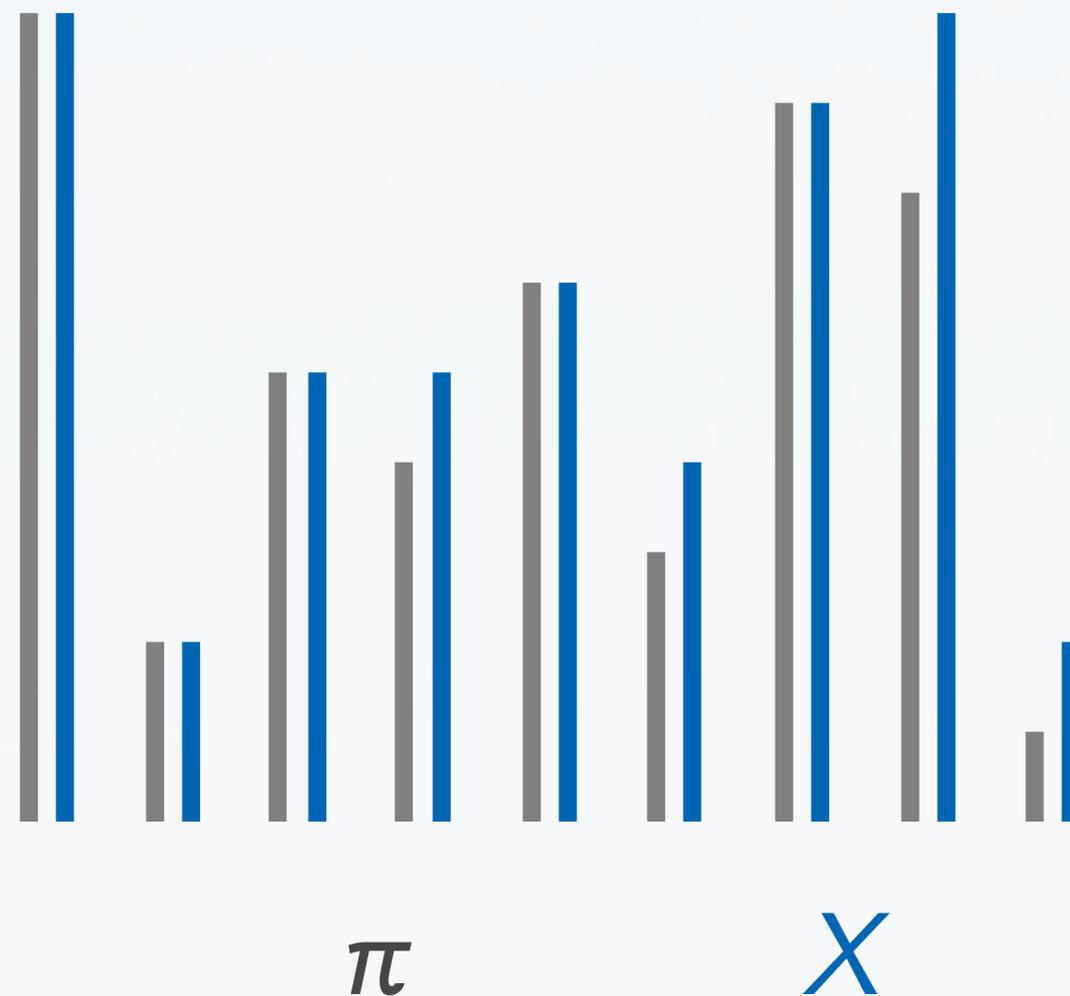
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Implementation
using union find
in $\mathcal{O}(n \cdot \alpha(n))$.



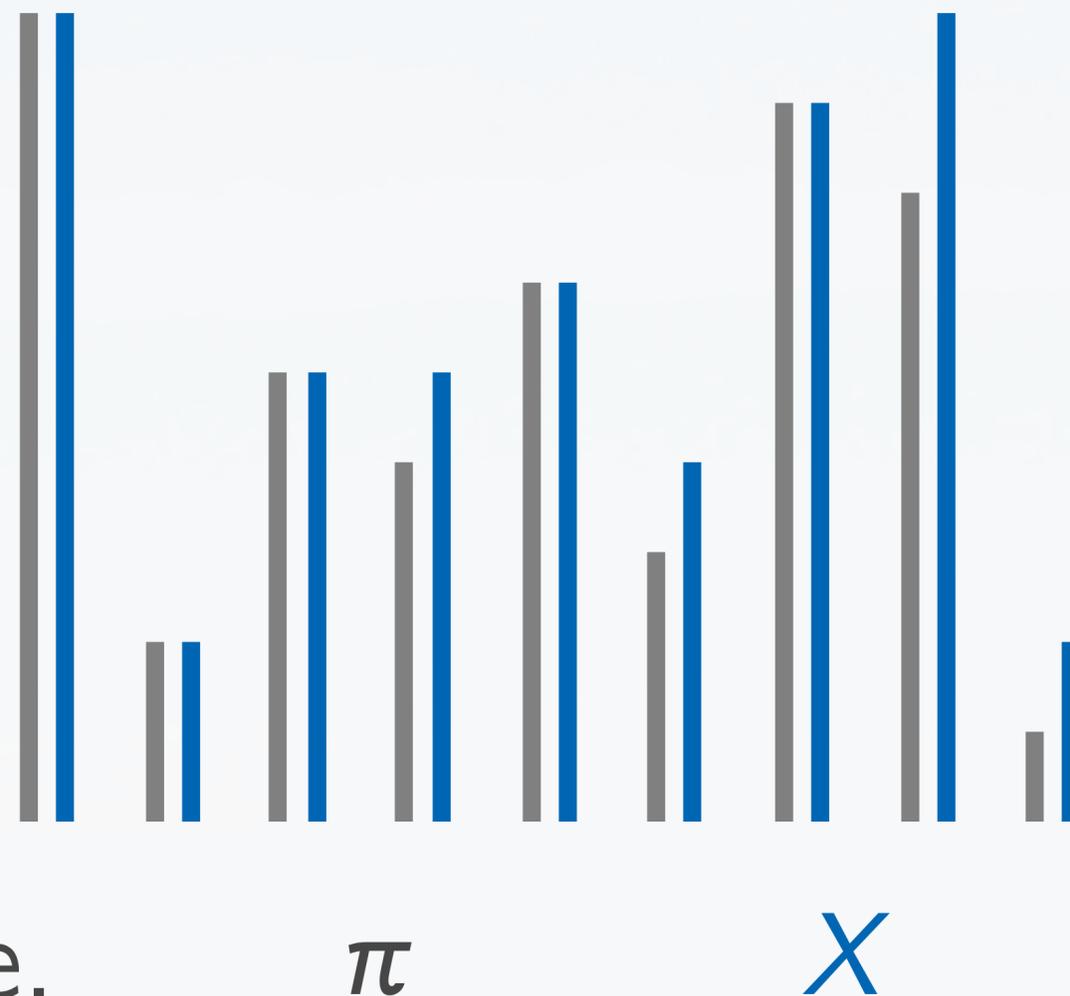
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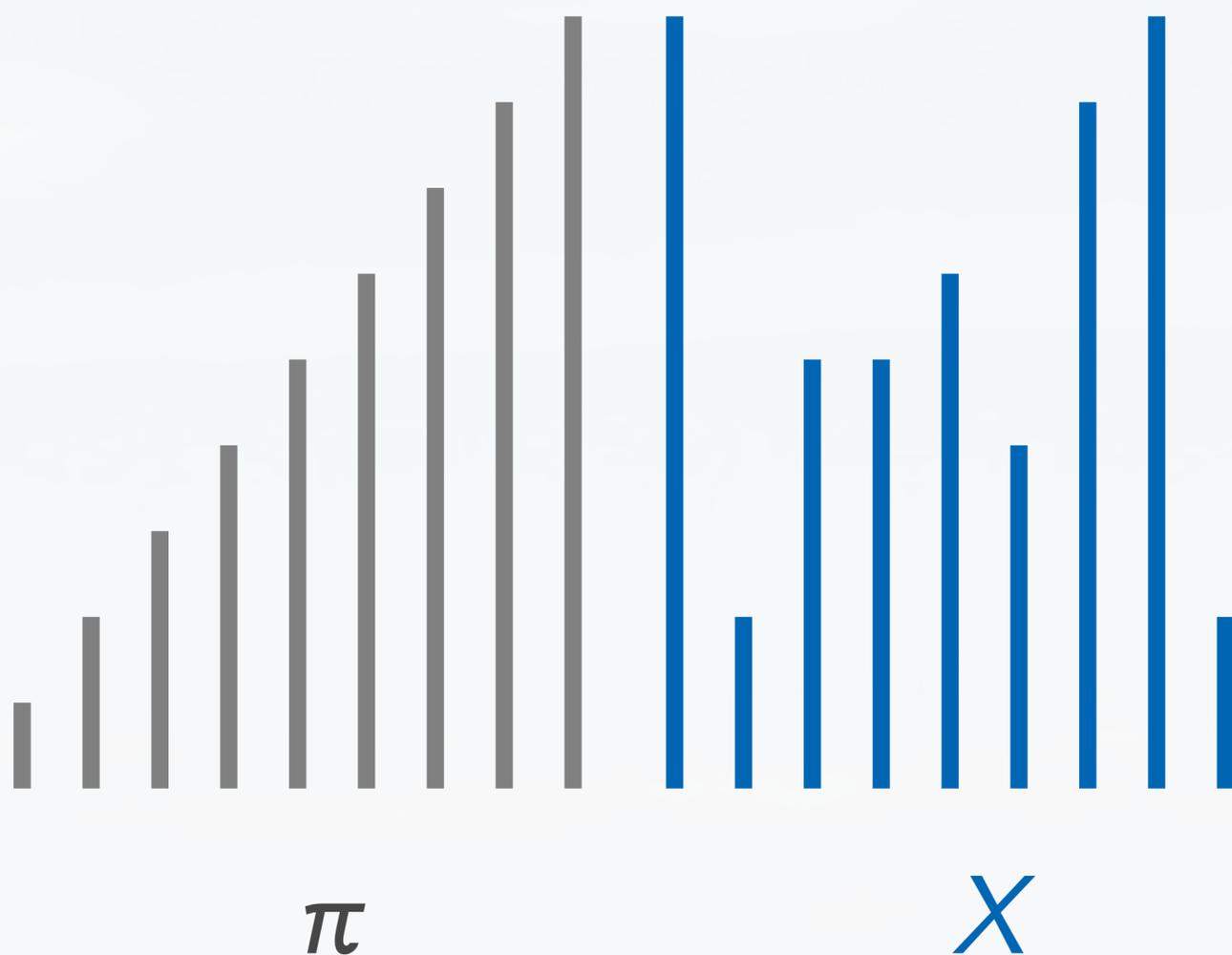
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Main advantage:

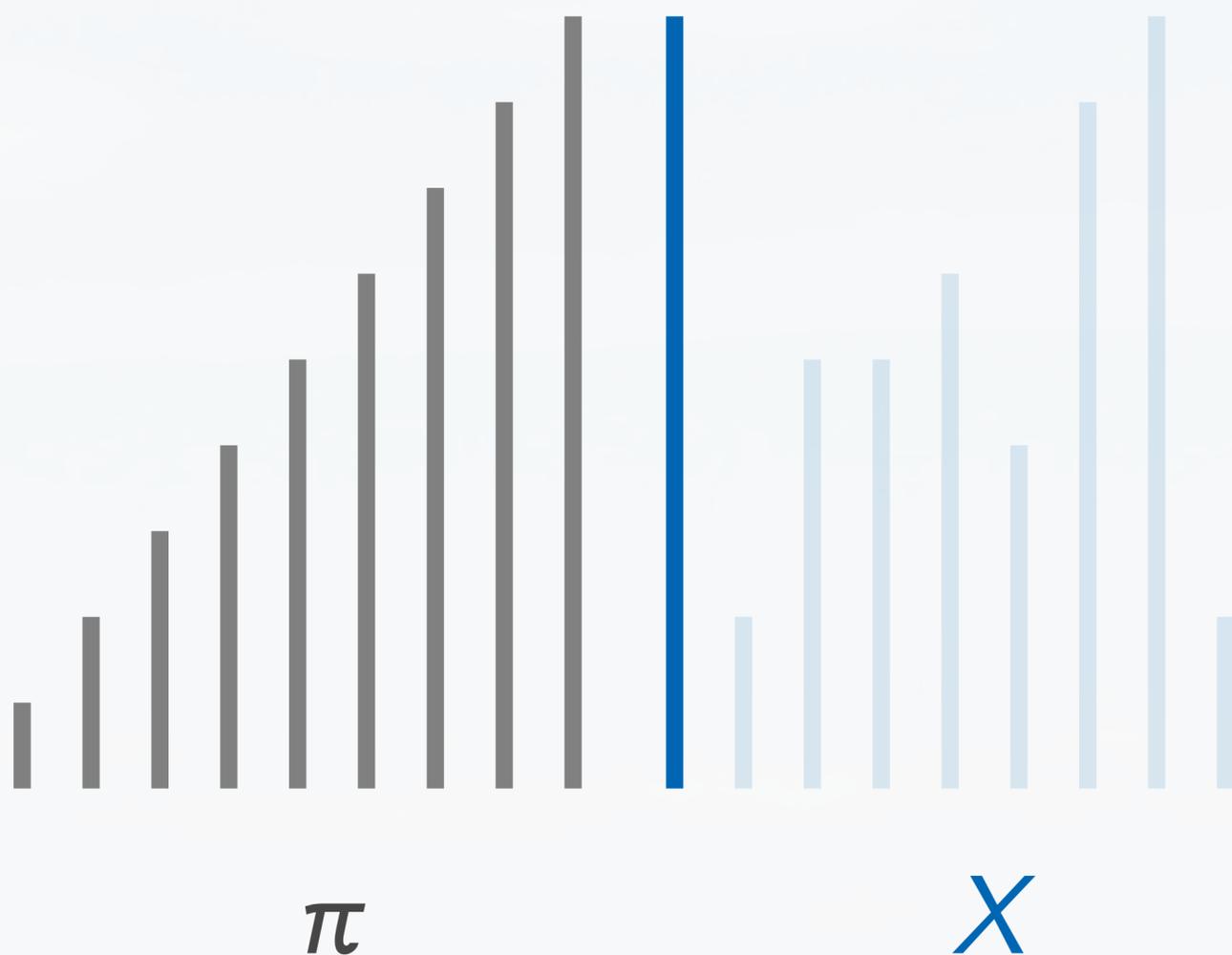
Also works if the
constraints arrive online.



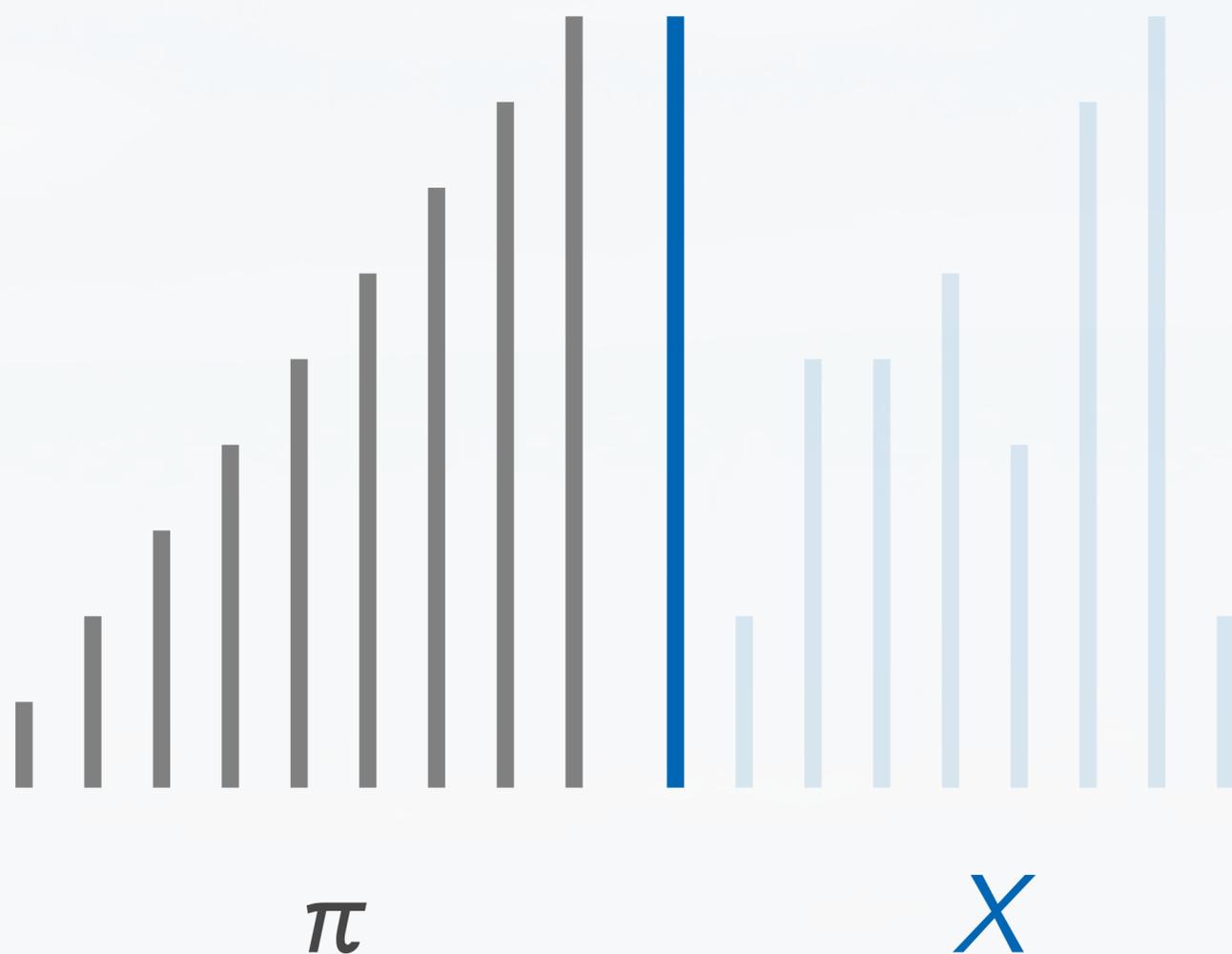
How much information about the future is needed to fill the slots optimally?



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In our setting:

No-swap model:

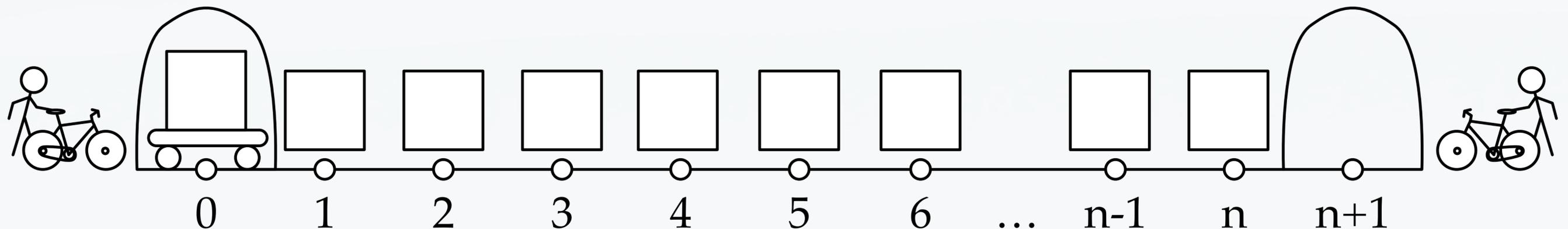
→ next 2 arrivals

Swap model:

→ only next arrival

New setting:

- second door at the other end
- swap-robot, carrying a box initially
- still arrival-only and no rearrangement



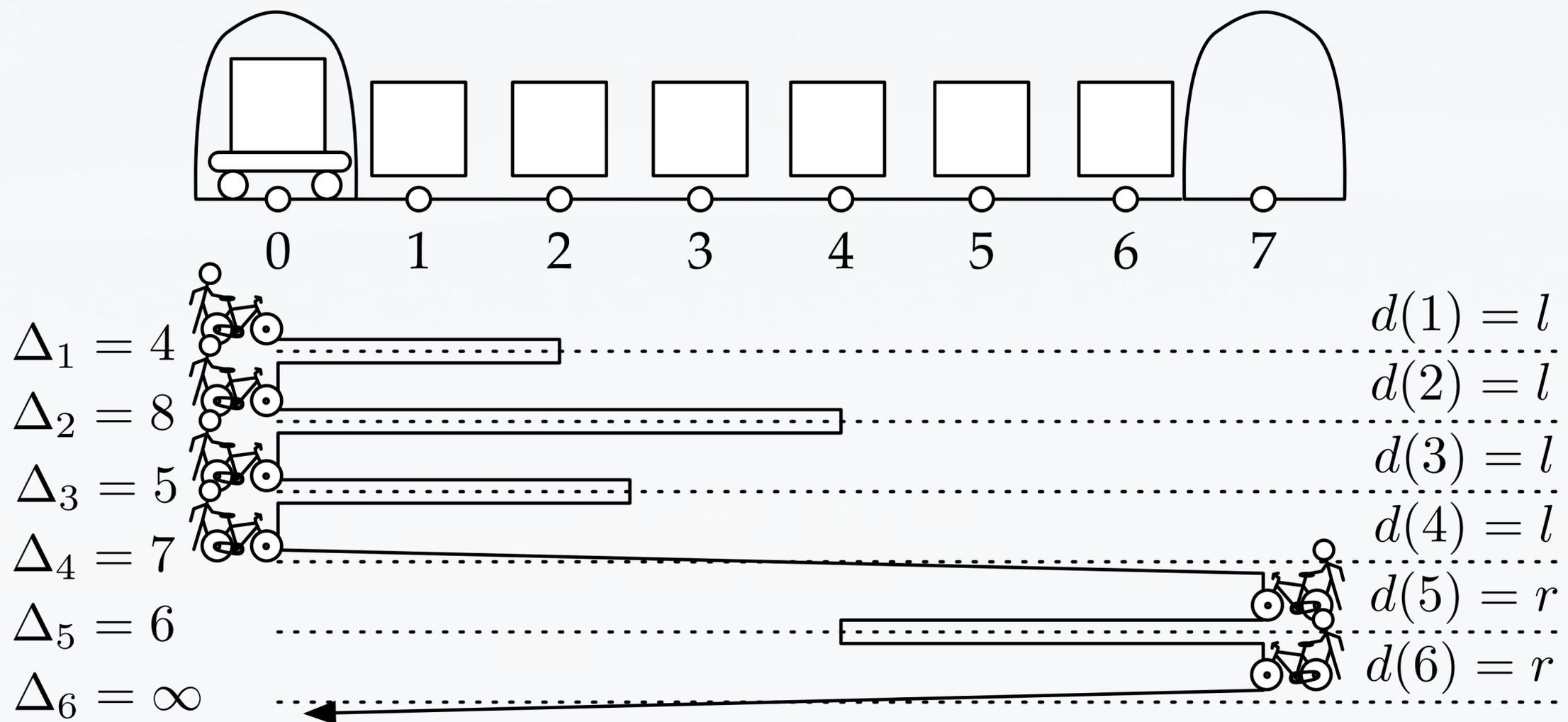
Who picks the door for each customer?

Given:

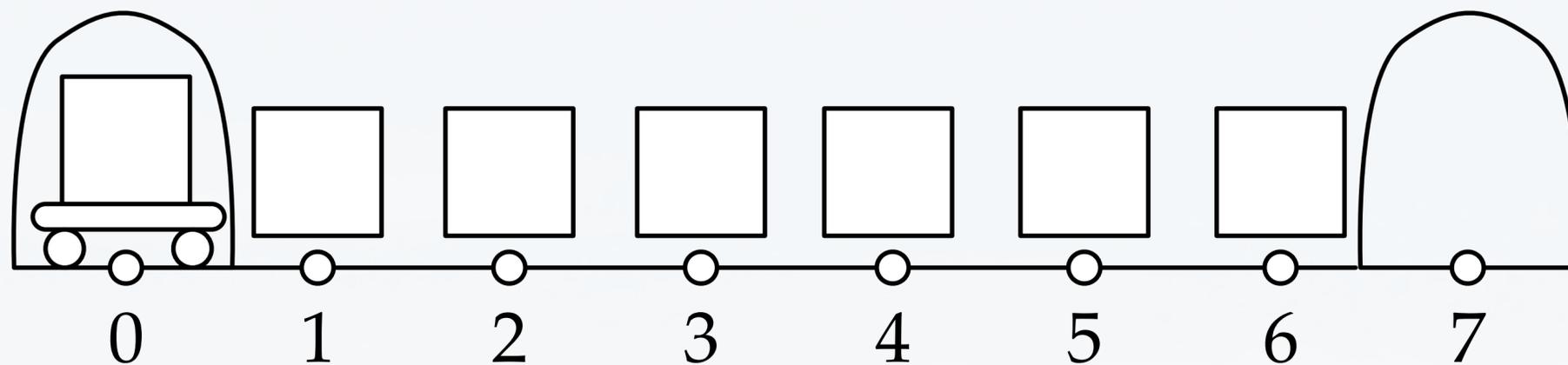
- inter arrival times Δ
- door assignment d

Wanted:

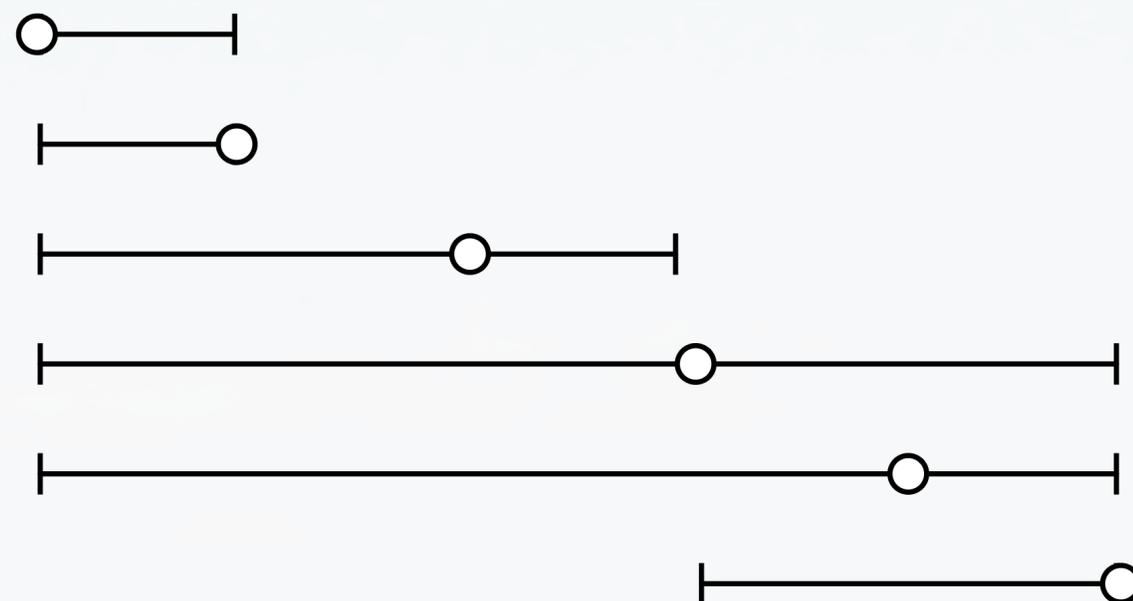
- slot assignment π



Solution: earliest deadline first scheduling



$$\sigma = (1, 3, 2, 4, 6, 5)$$



Given:

- inter arrival times Δ

Wanted:

- slot assignment π
- door assignment d

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Wanted:

- slot assignment π
- door assignment d

Theorem: For a given Δ , it is *NP*-complete to decide whether feasible π and d exist.

Proof: Reduction from *3SAT*.

Definition: 3SAT

- input: CNF-formula F with
 - M clauses C_1, C_2, \dots, C_M with $C_i = \{l_{i_1}, l_{i_2}, l_{i_3}\}$
 - N variables x_1, \dots, x_N
- output: can we satisfy all the clauses?

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Example: $F = \{\{x_1, x_3, \bar{x}_4\}, \{x_2, \bar{x}_3, x_4\}, \{\bar{x}_1, x_2, \bar{x}_4\}\}$

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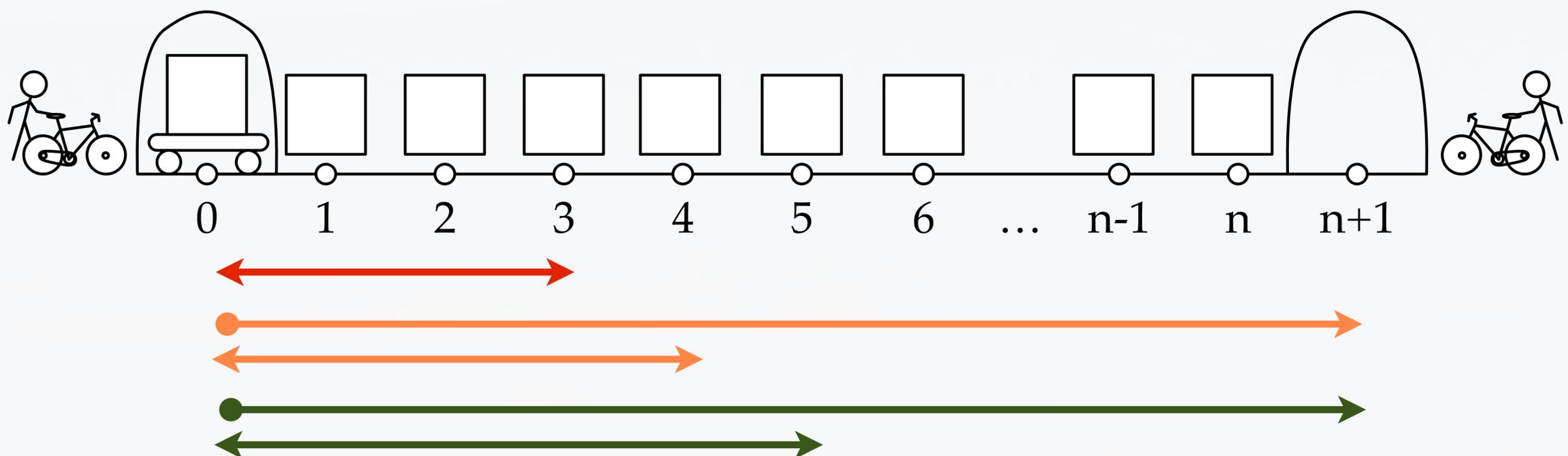
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Theorem [1971, Cook], [1973, Levin]:

3SAT is NP-complete.

We classify inter request times Δ_i by duration:

- **short:** $\Delta_i \leq n$: the other door is unreachable
- **medium:** $n < \Delta_i < 2n$: in between
- **long:** $2n < \Delta_i$: switch or not and reach any slot



Consecutive short requests have to be assigned to the same door *en bloc*.

Transform a given *3SAT* formula into a sequence of blocks and interleave them with long requests.

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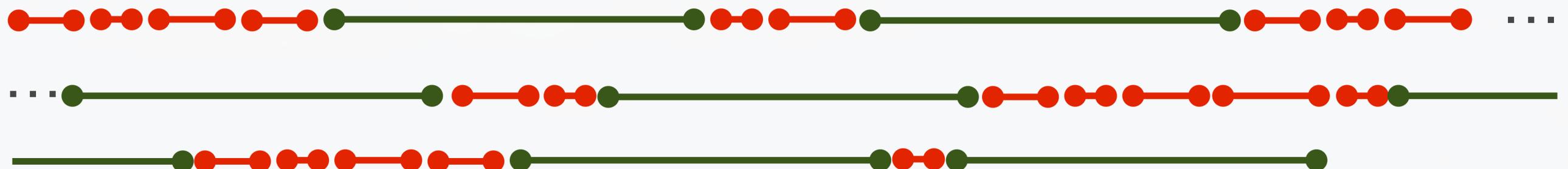
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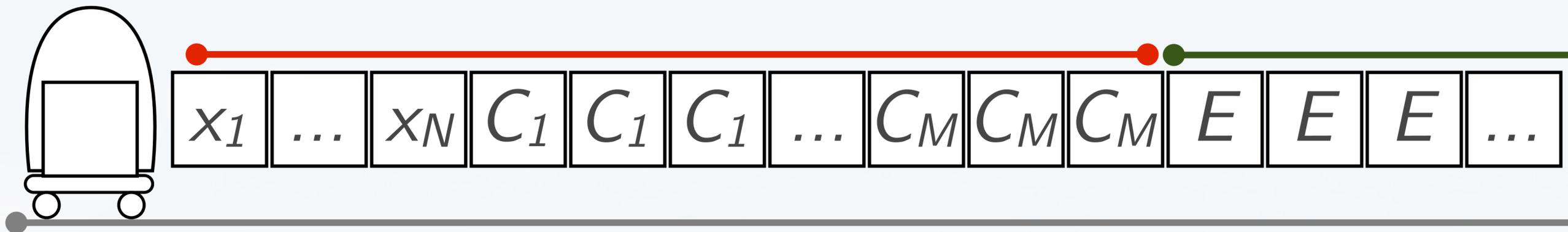
Consecutive short requests have to be assigned to the same door *en bloc*.

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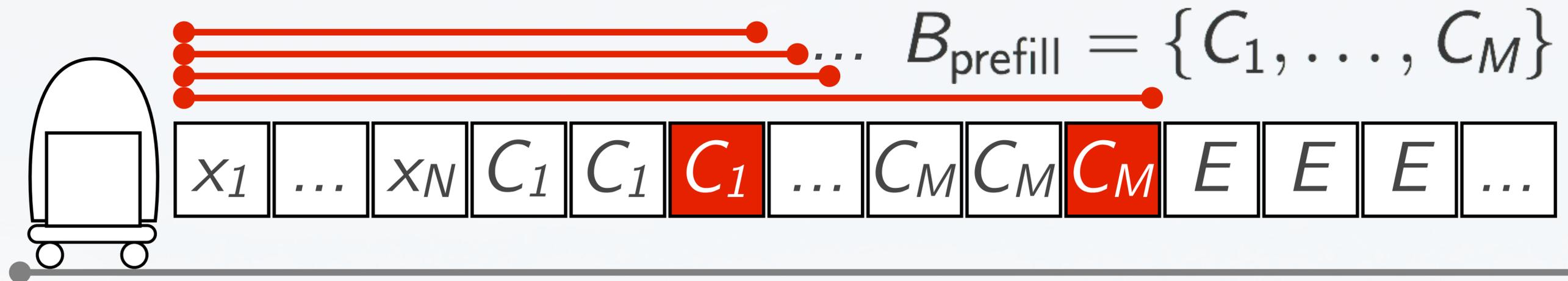
false door



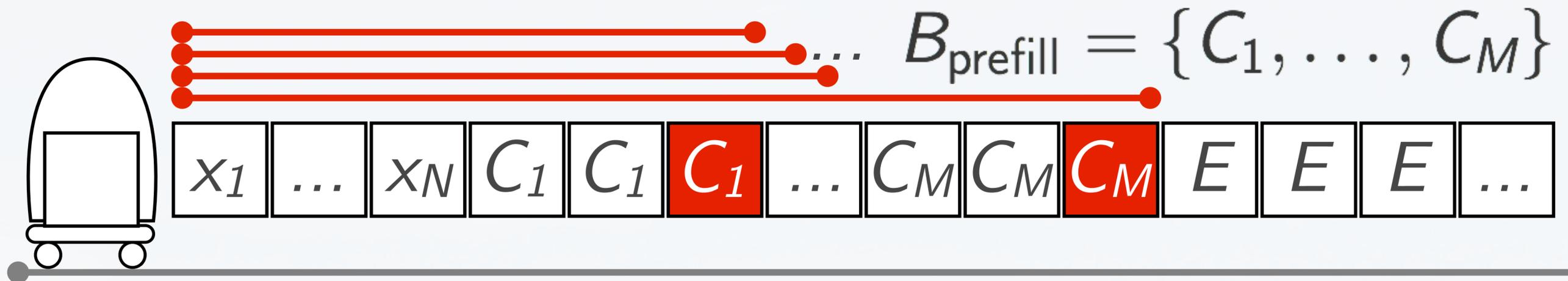
true door



Prefill block: fill one slot per clause on the false side



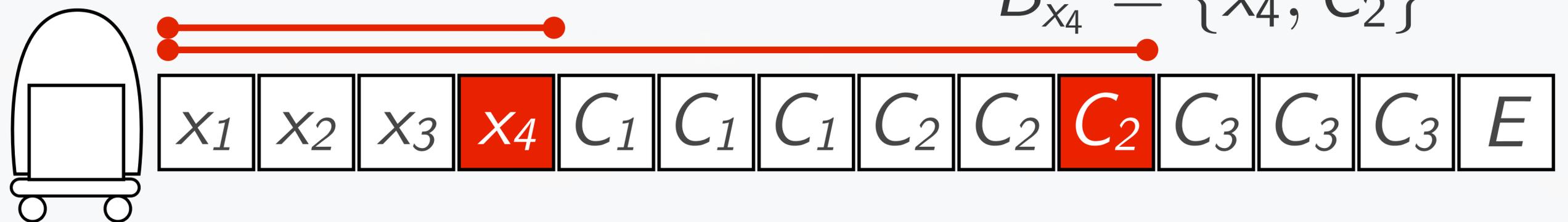
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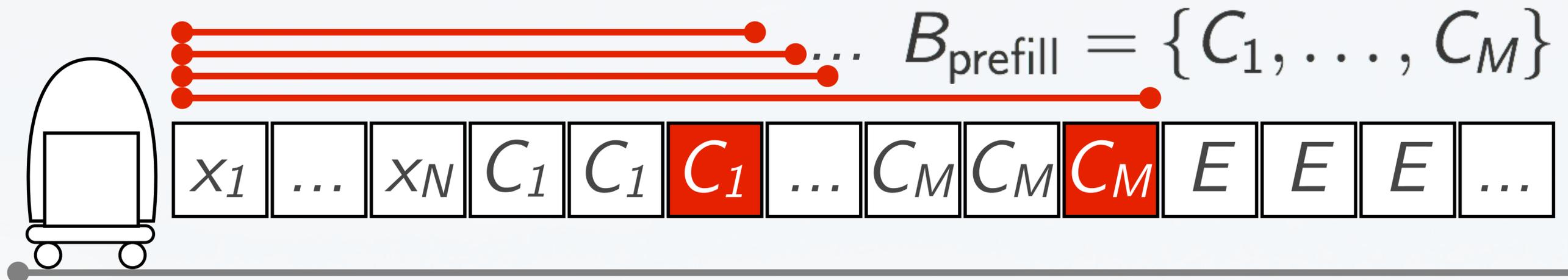
Literal blocks: variable and all clauses containing it

Example: $F = \{\{x_1, x_3, \bar{x}_4\}, \{x_2, \bar{x}_3, x_4\}, \{\bar{x}_1, x_2, \bar{x}_4\}\}$

$$B_{x_4} = \{x_4, C_2\}$$

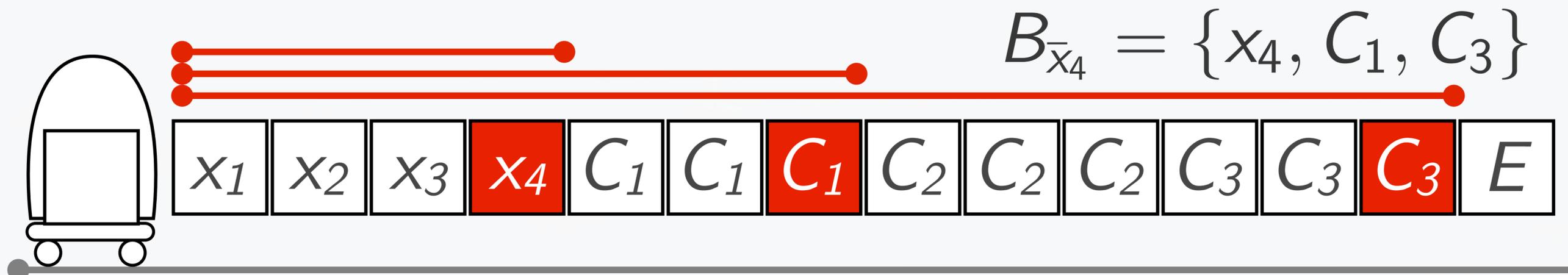


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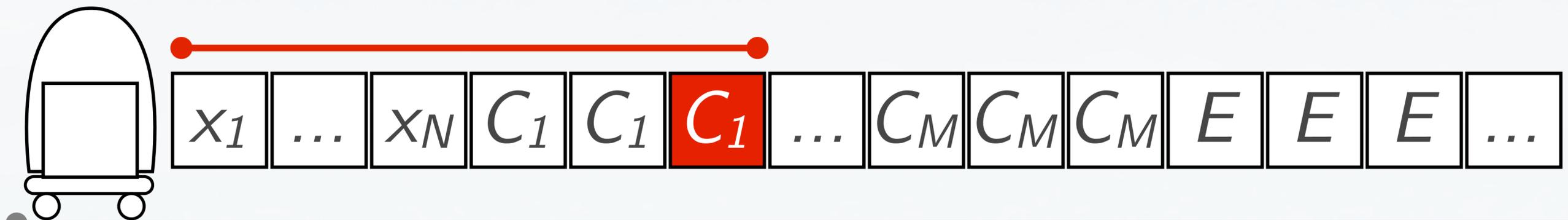
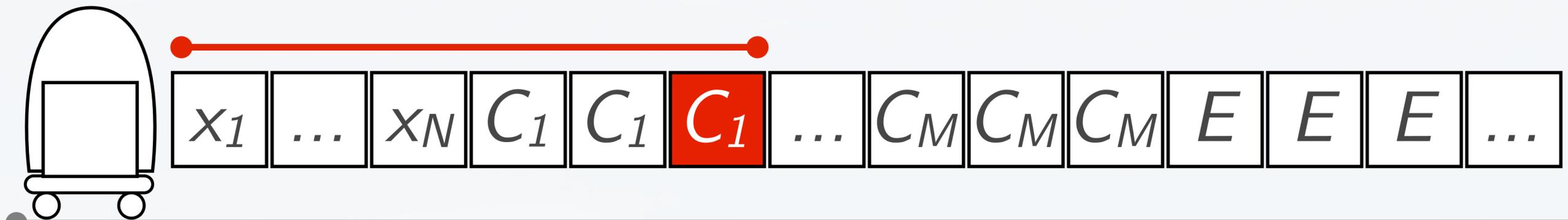


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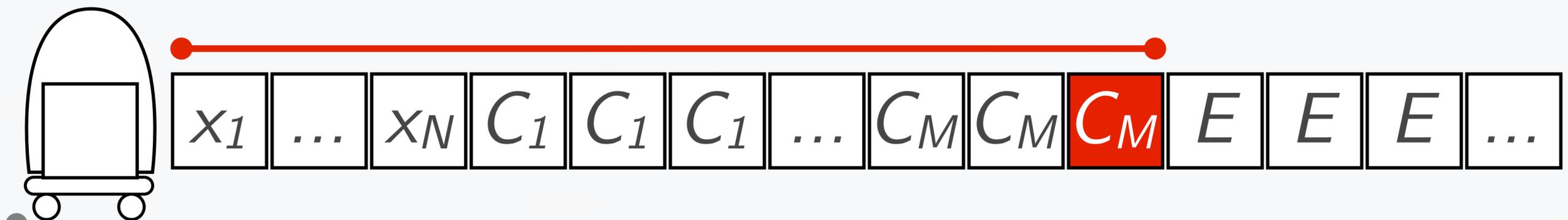
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Fillup blocks: two single request blocks per clause



...



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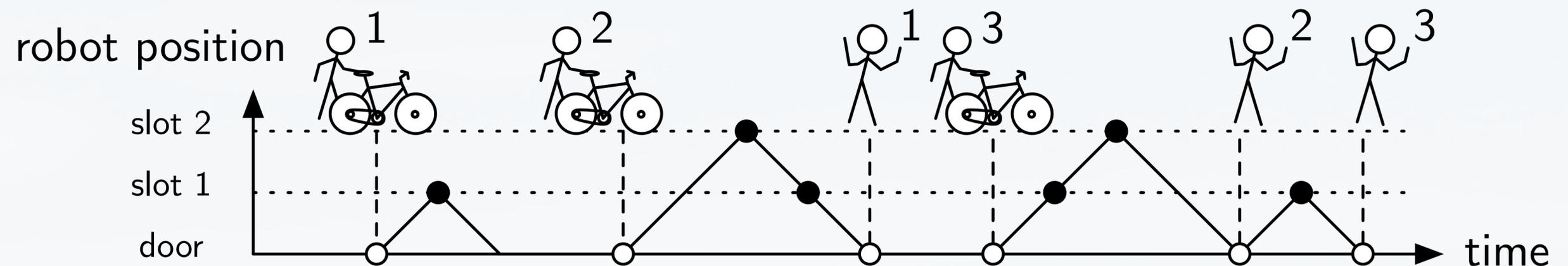
Proof:

- Per label there are as many slots as requests.
- The long requests fill up the E slots.
- Opposite literals get assigned to opposite doors.
- Per clause at least one literal block has to get assigned to the true door as one slot on the false side is already taken by the prefill block.

Back to a single door, but also with departures:

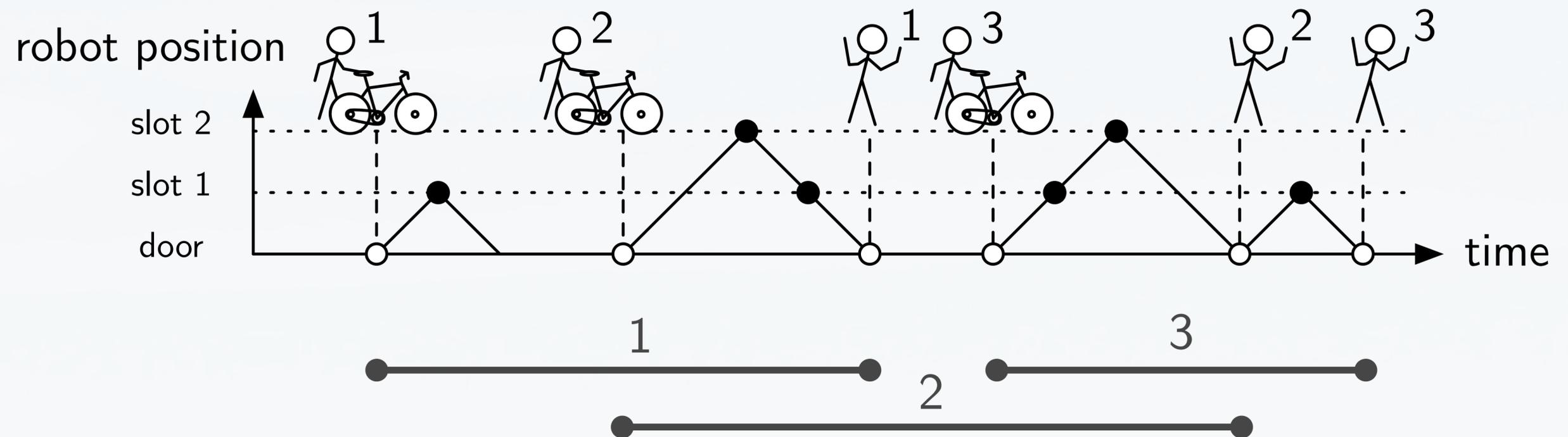
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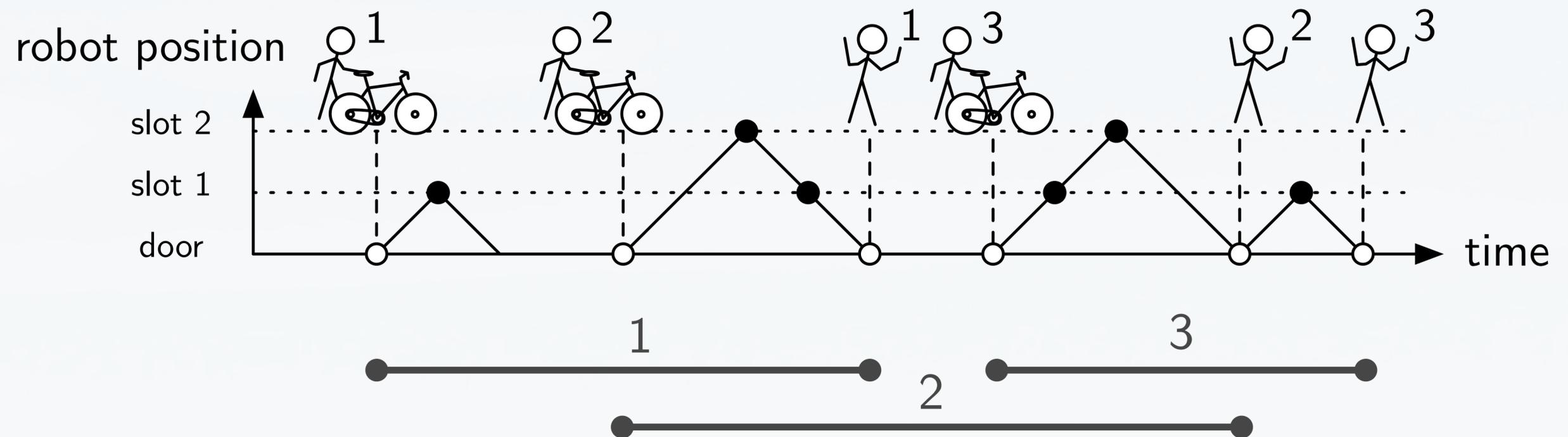
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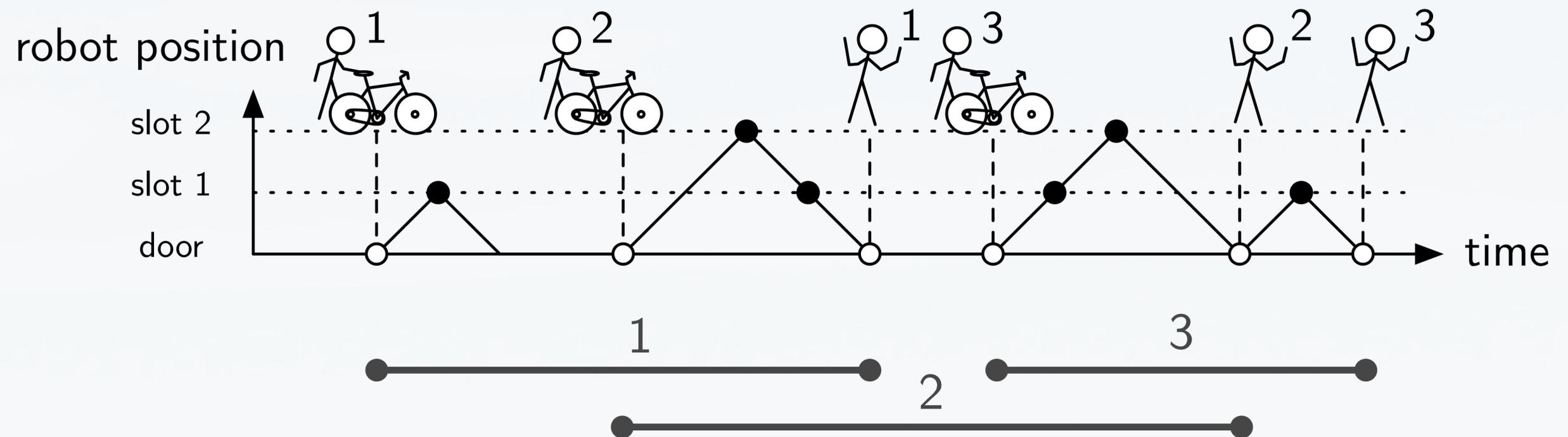
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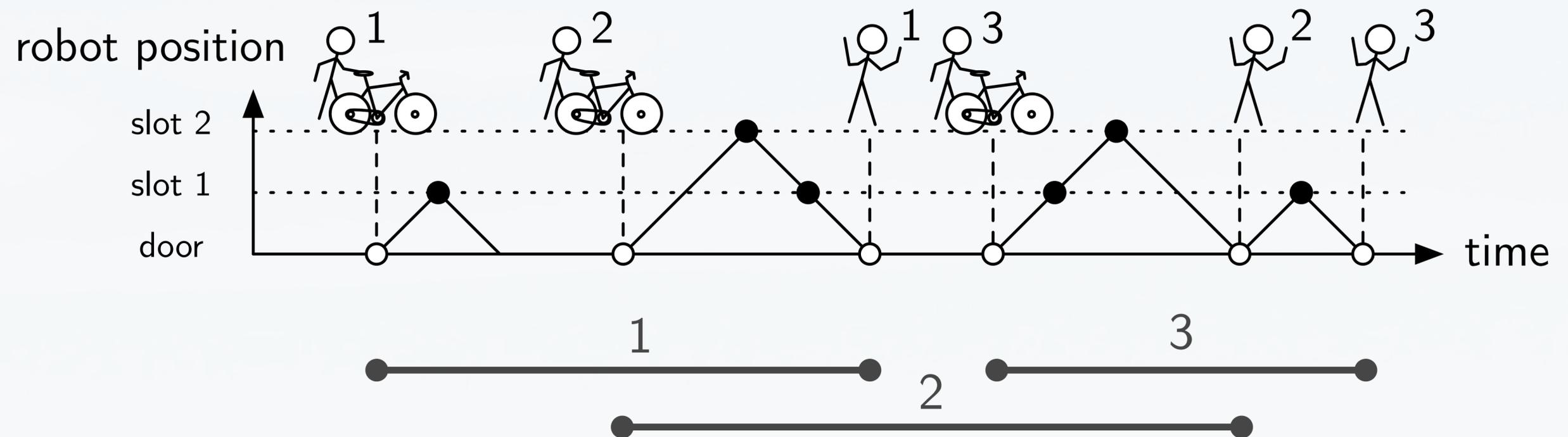
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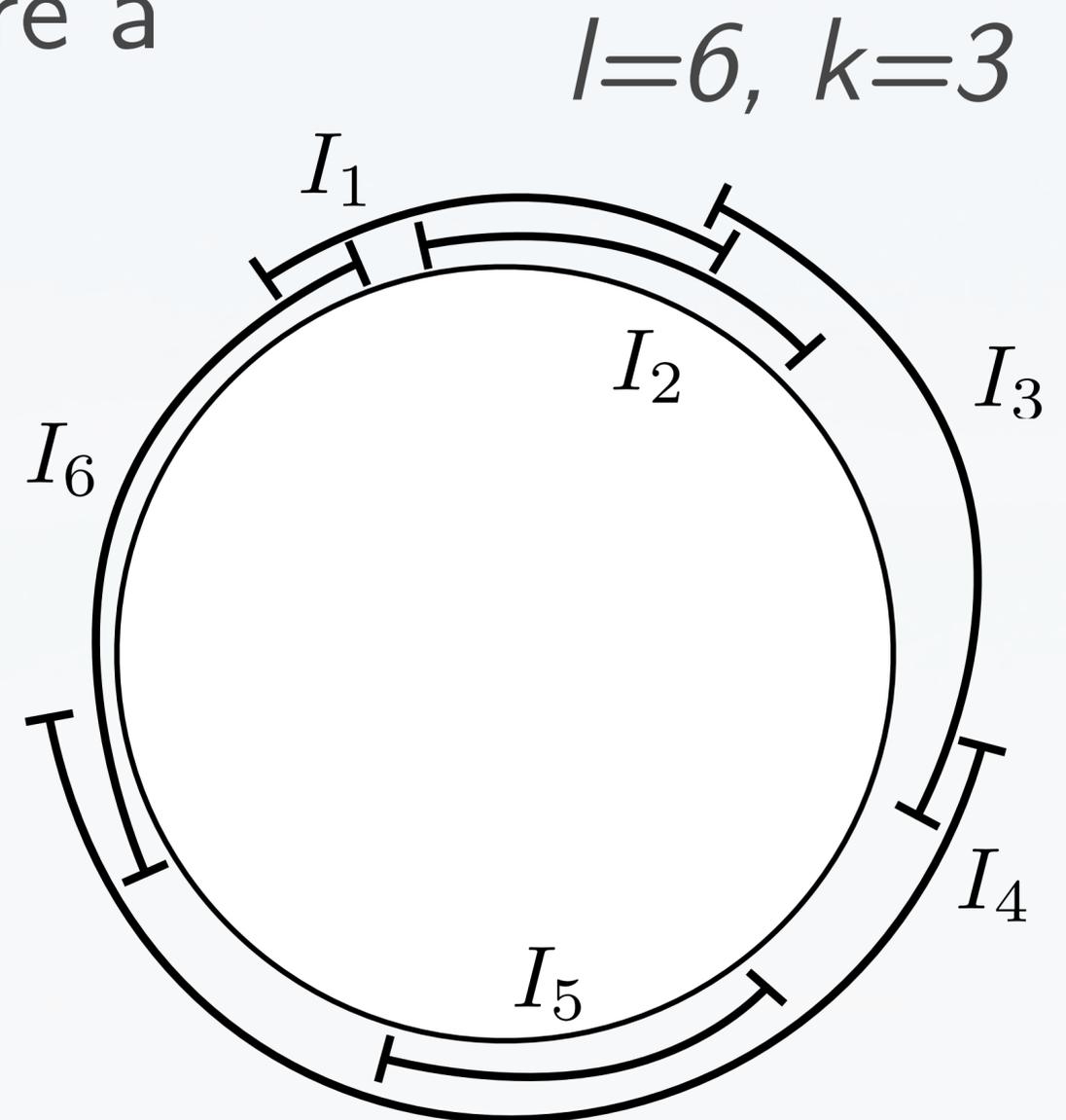


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Proof: Reduction from *Circular Arc Coloring*.

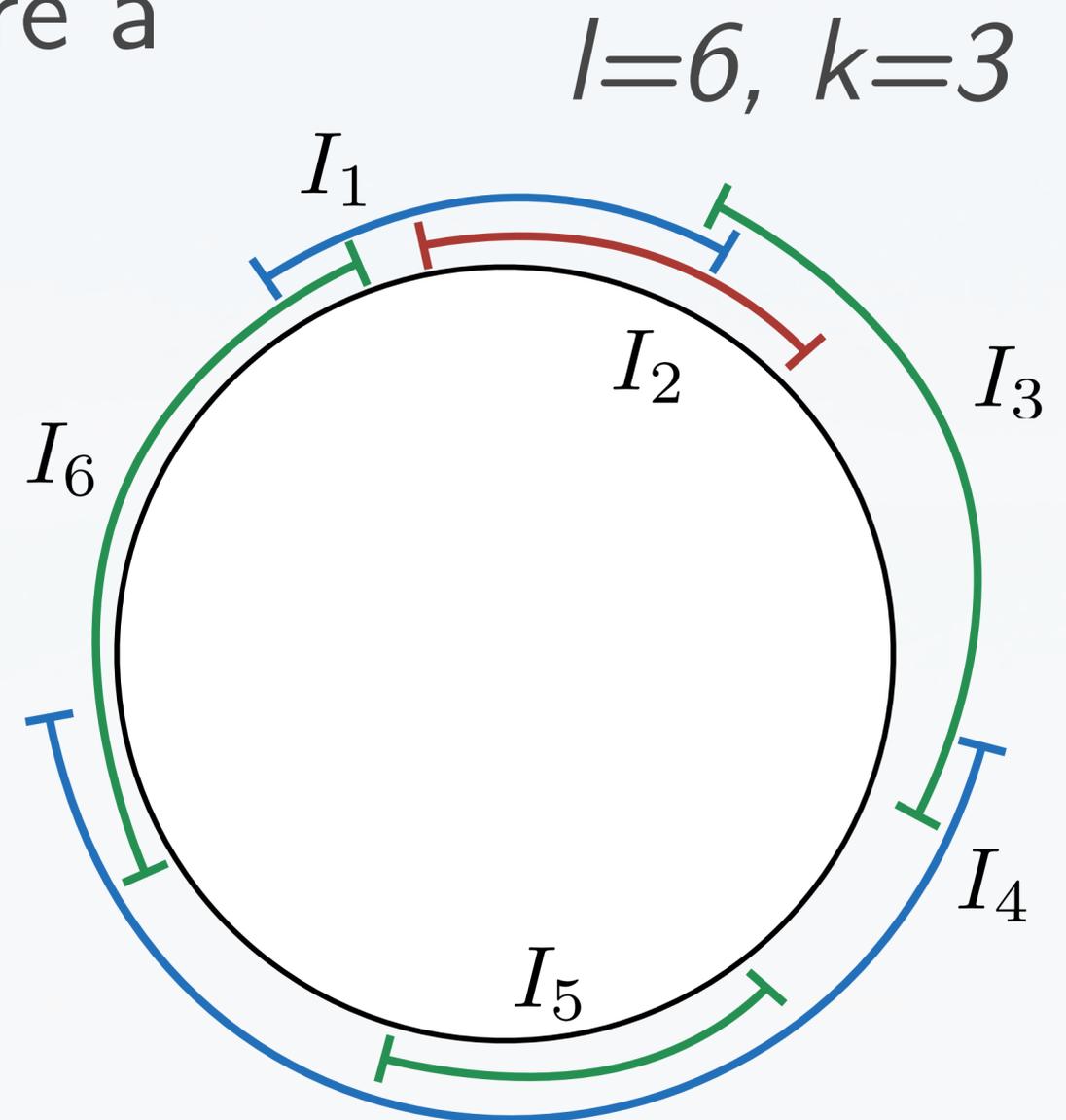
Definition: Circular Arc Coloring

Given l arcs on a circle, is there a k -coloring of their intersection graph?



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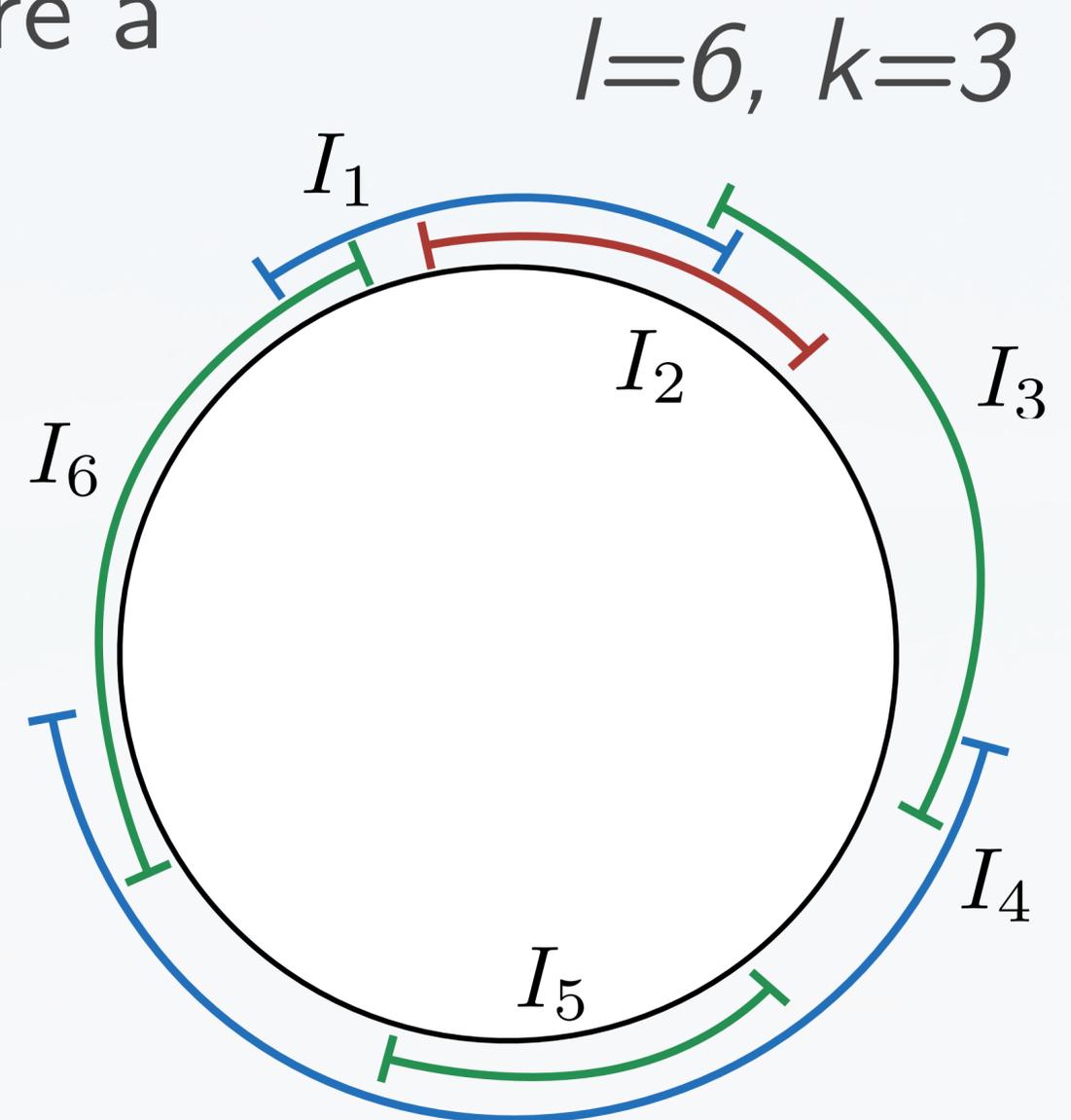
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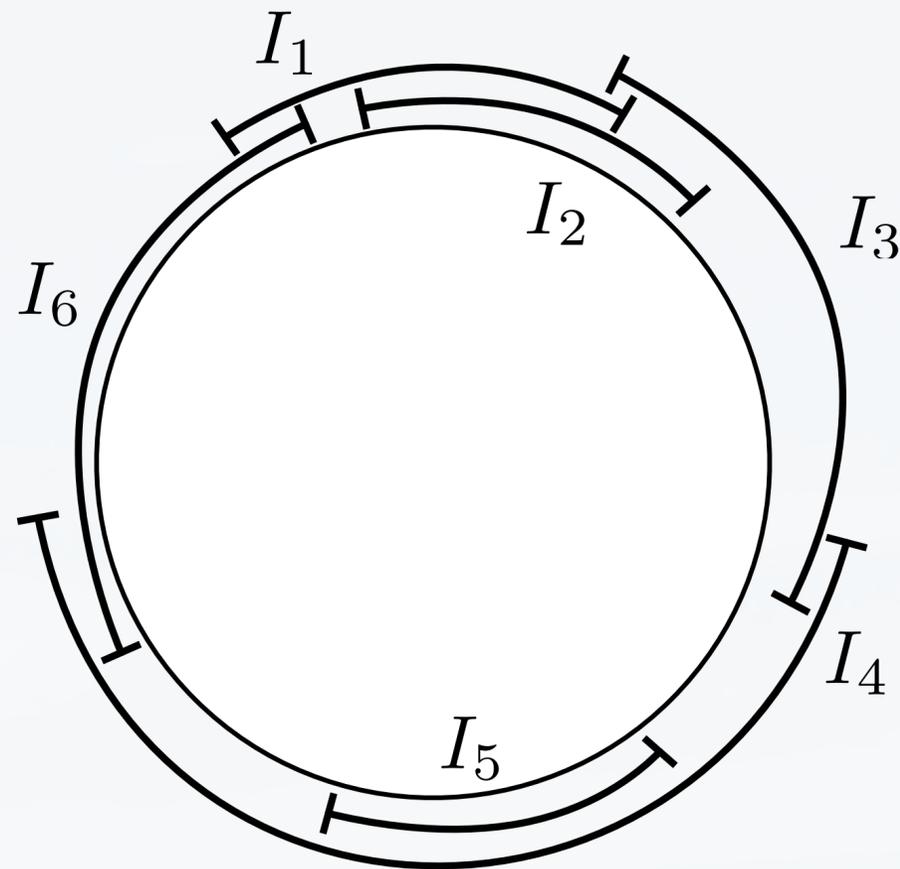


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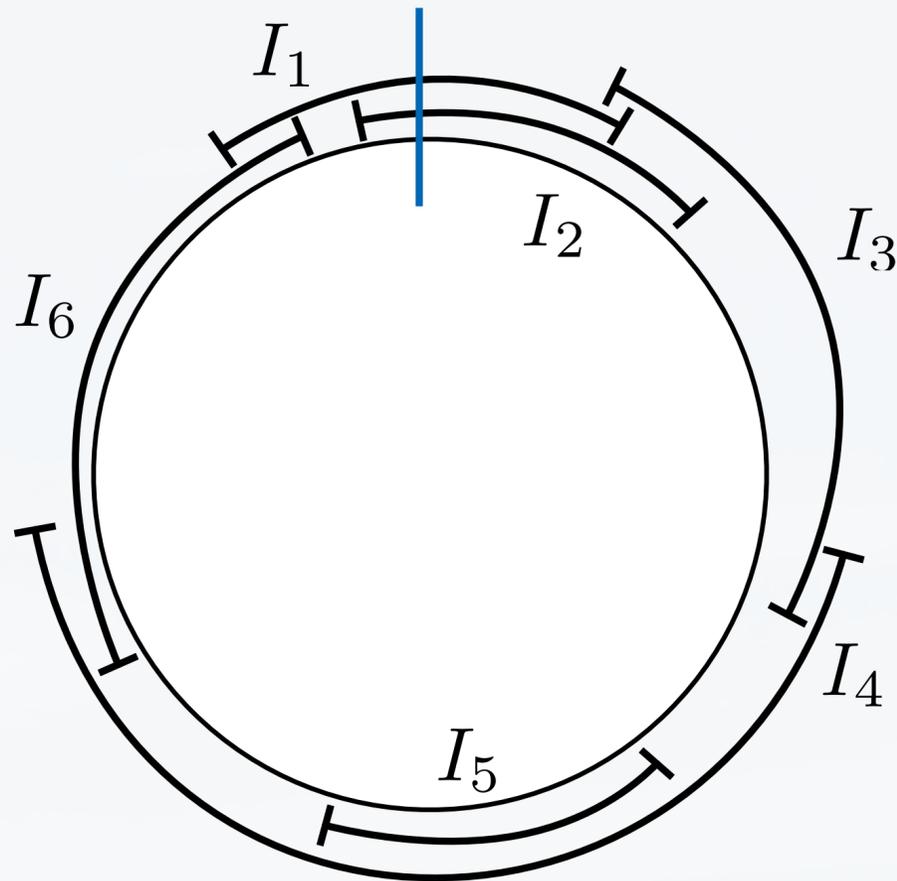
Theorem [1980, Garey et al.]:
Circular Arc Coloring is
NP-complete.





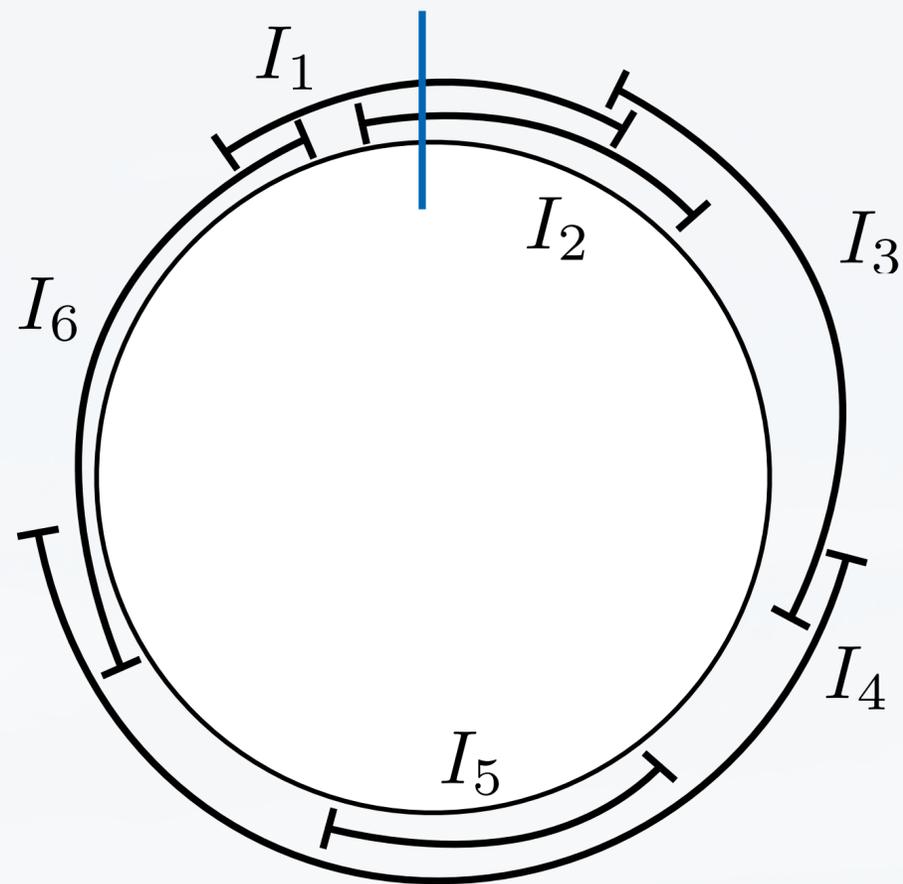
Outline of the reduction

- split the arcs at position 0
- arbitrarily, but consistently color the arcs across this cut
- transform it into an all-day instance with k slots



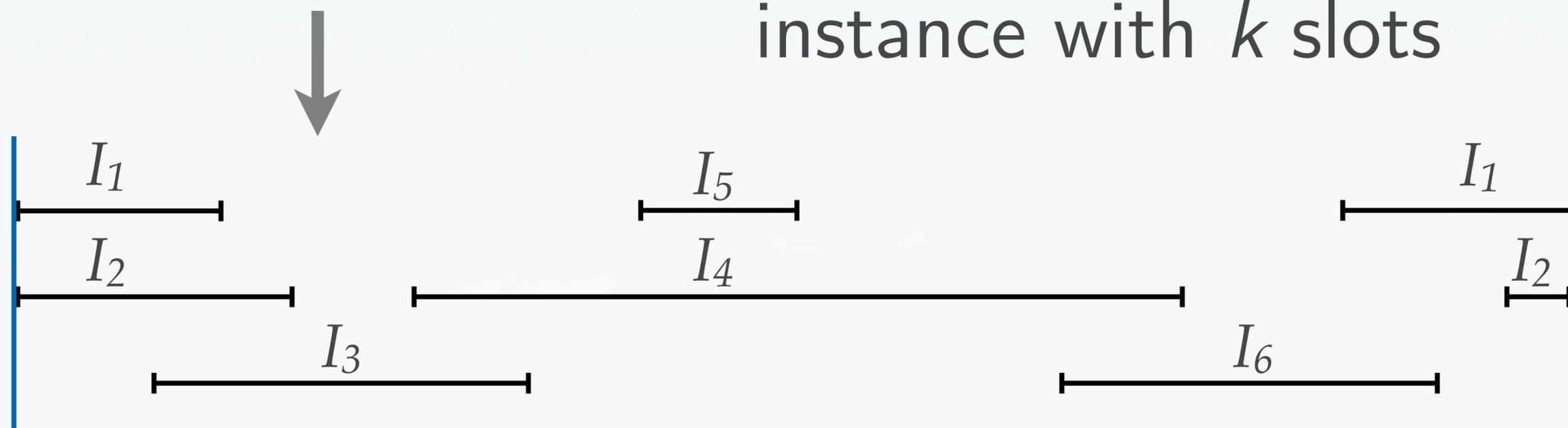
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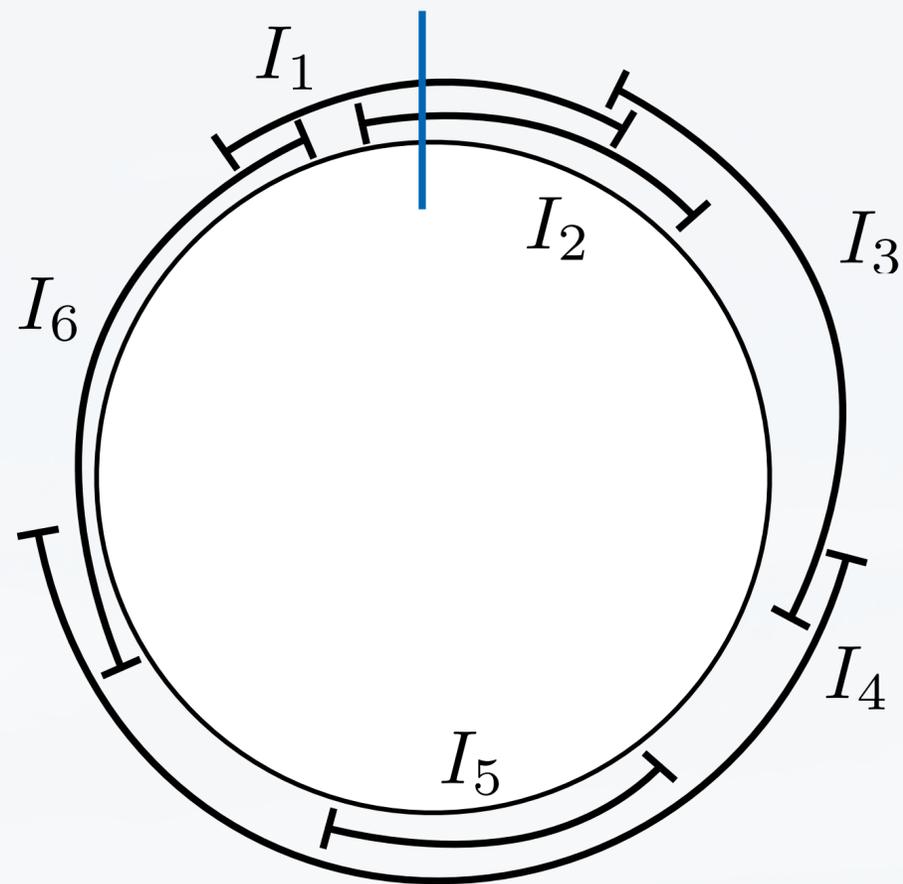
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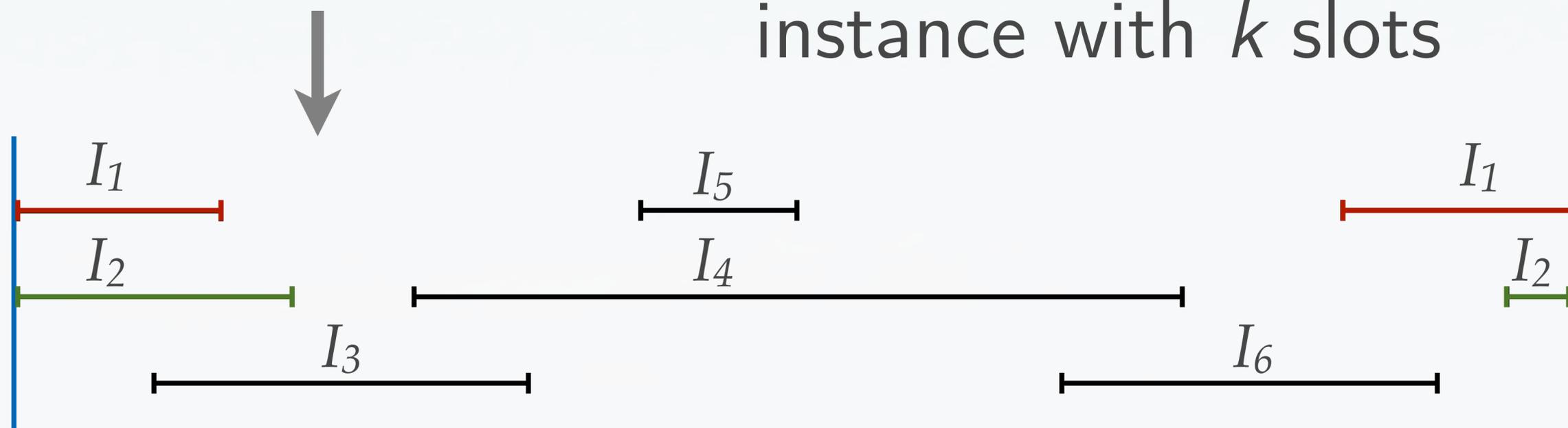
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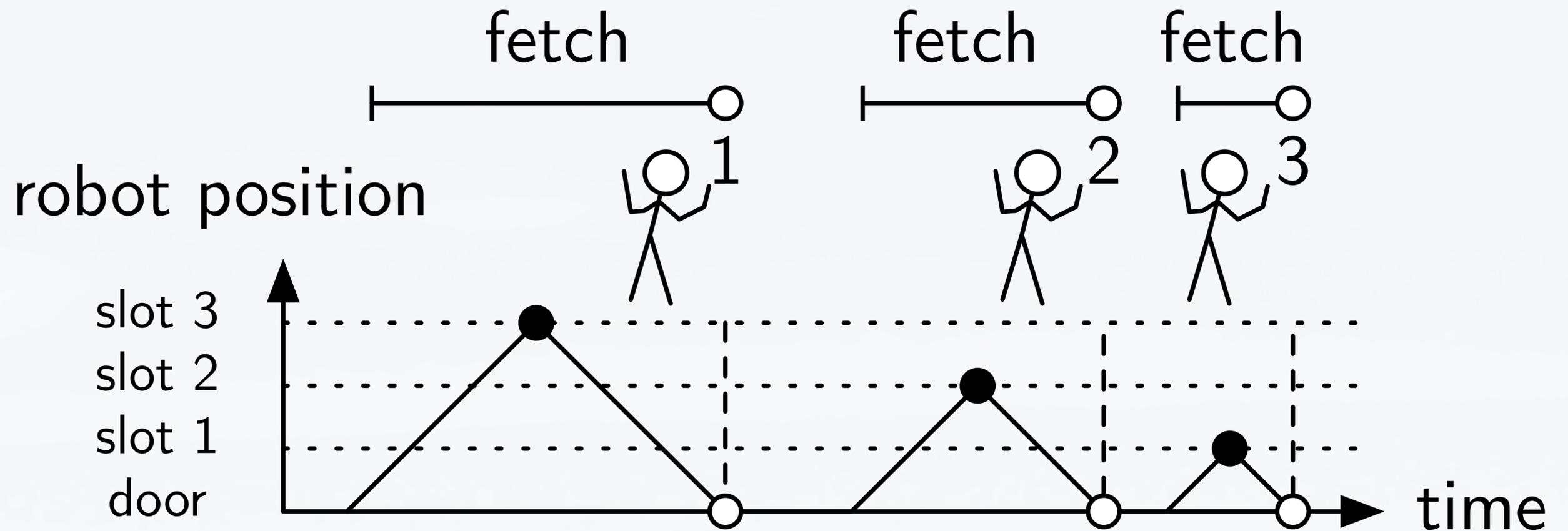




What if all the customers arrive in the morning and depart only in the evening?

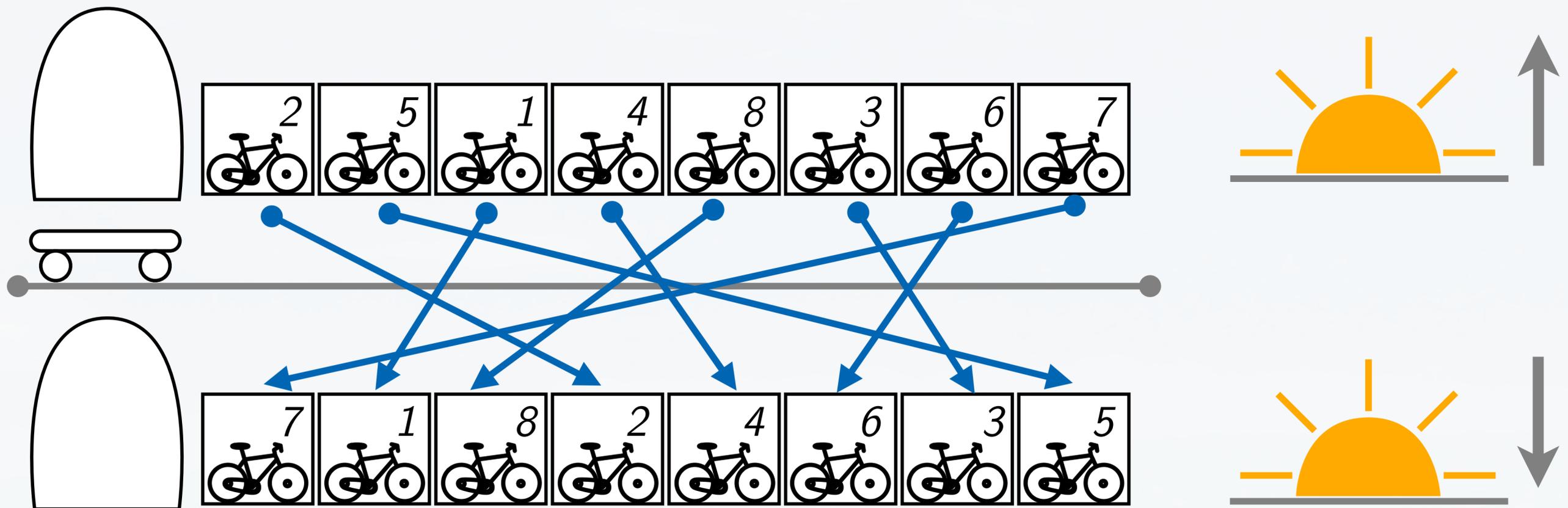
- Every slot used only for a single customer
- Arrival-only problem in the morning
- Sorting problem during lunchtime
- Departure-only problem in the afternoon

Example:



Solving another instance of the constrained permutation problem.

Lunch Break

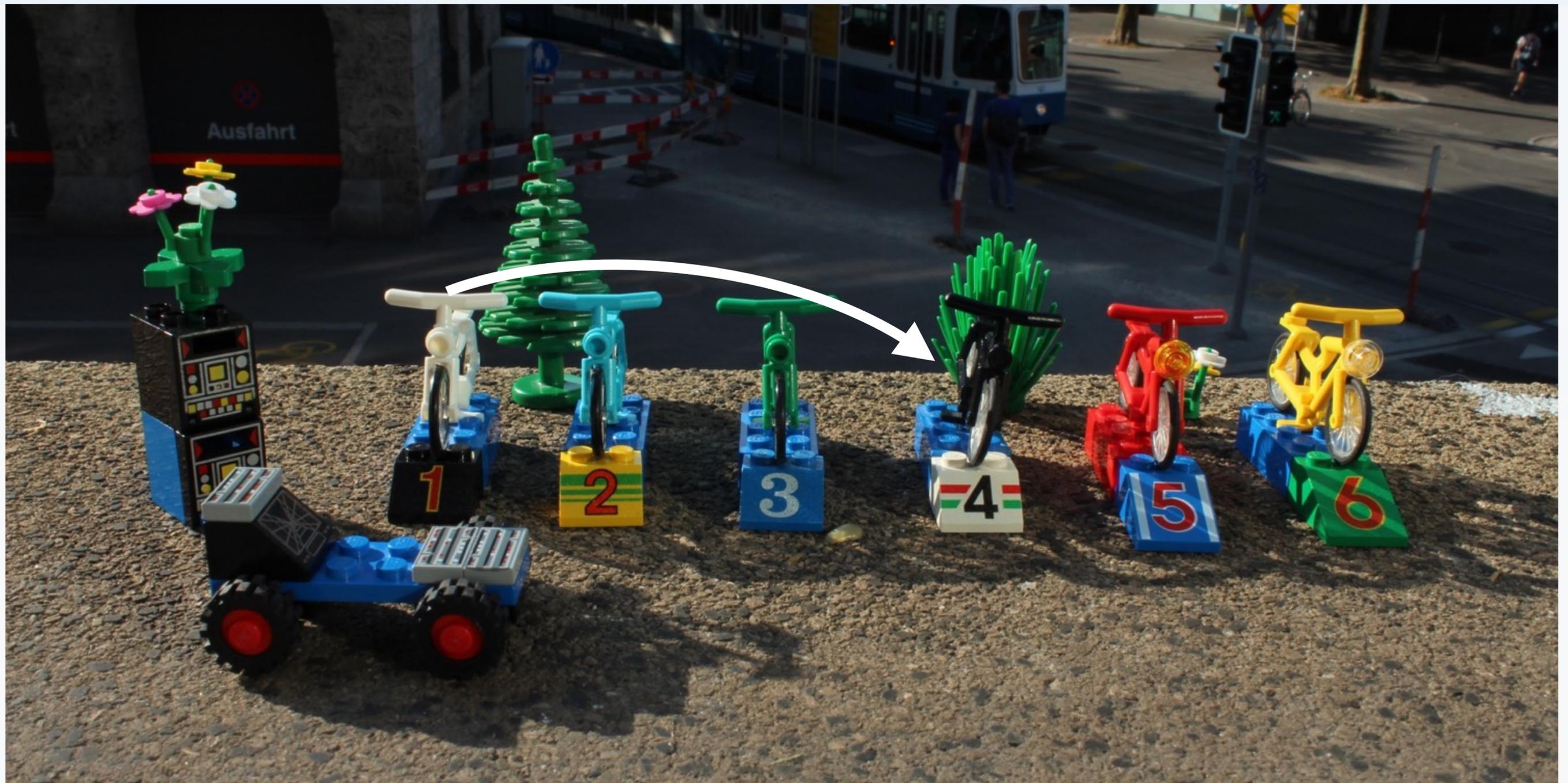


How do we sort this as quickly as possible?

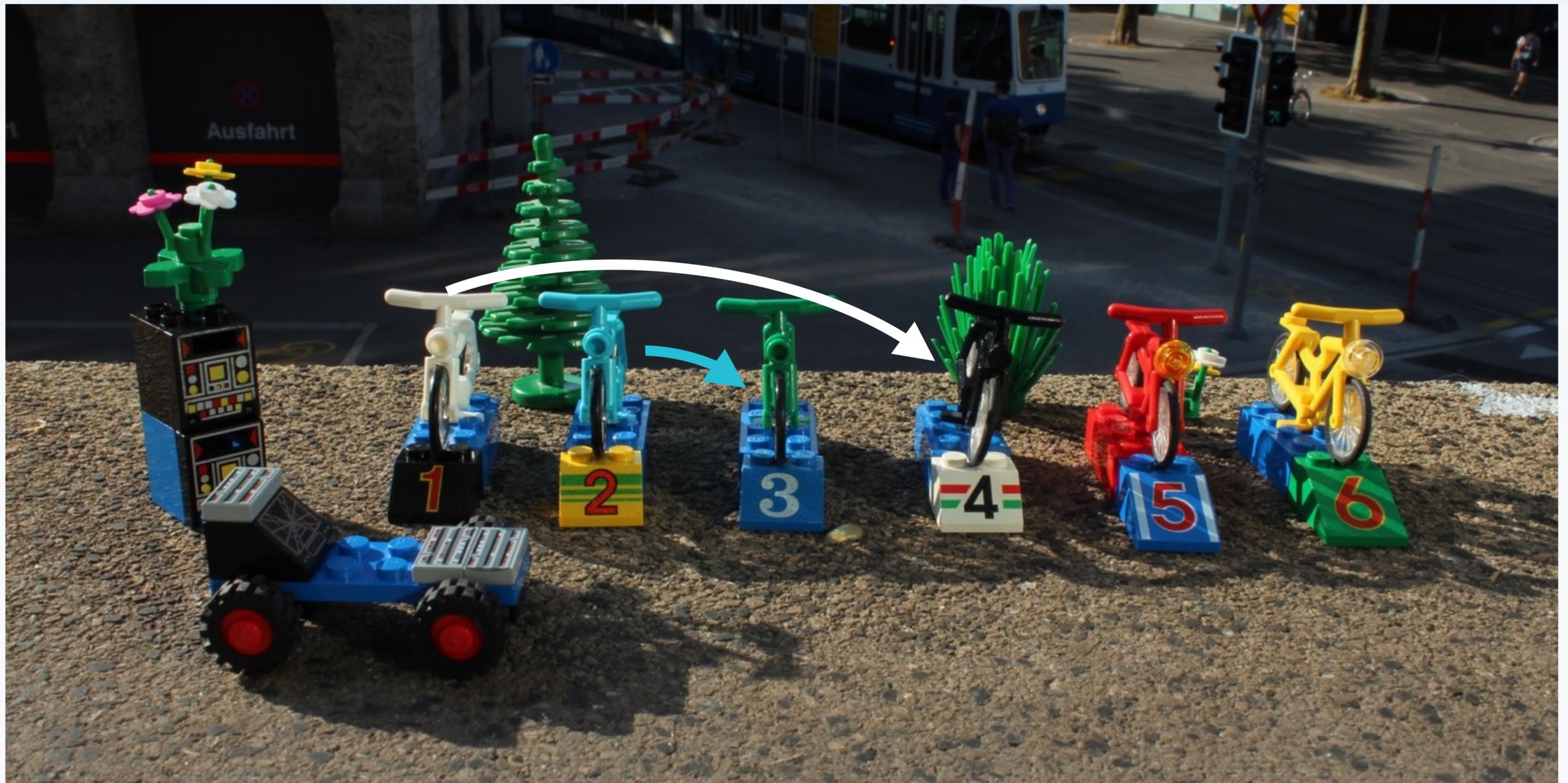
Sorting Problem



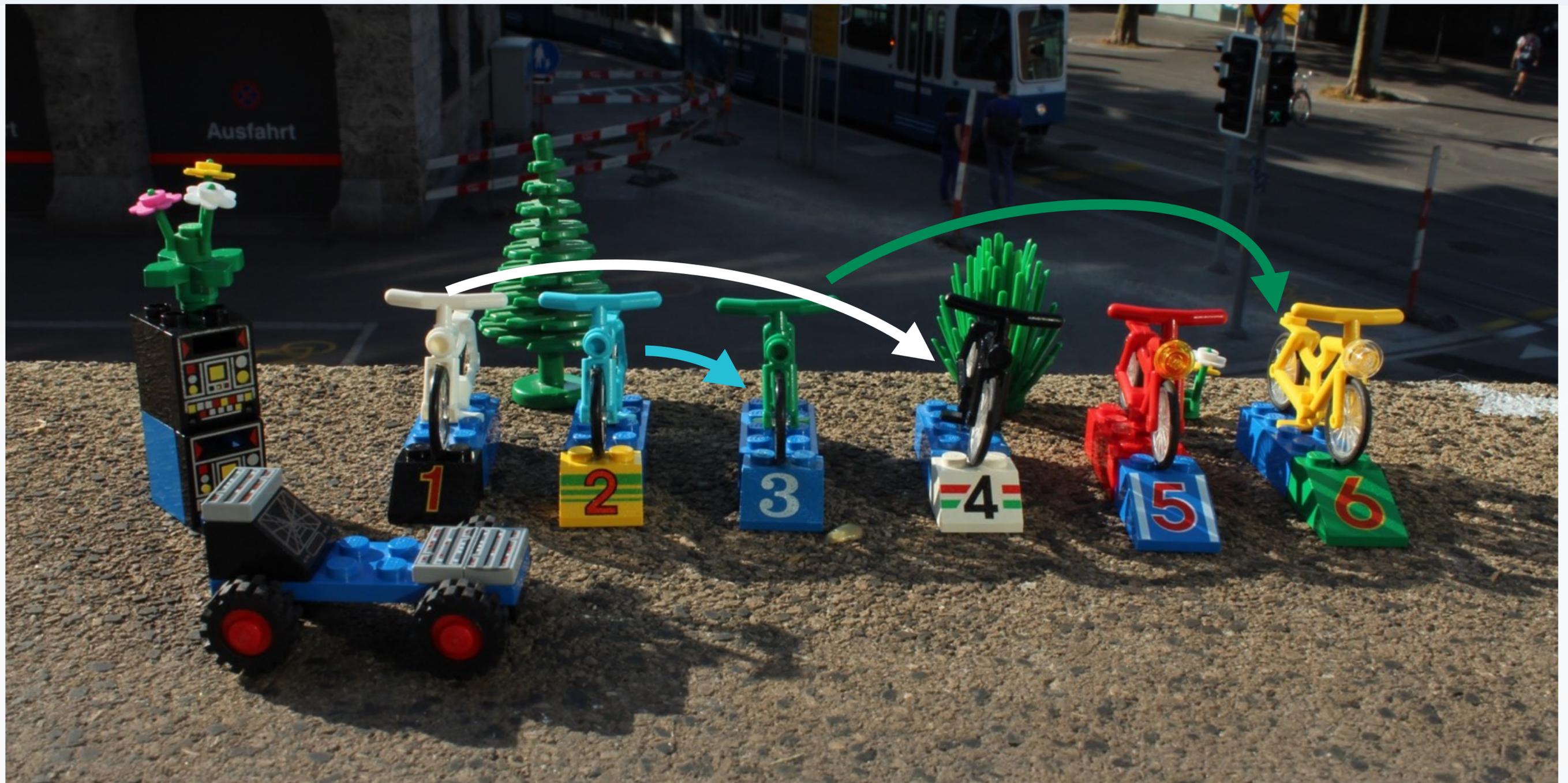
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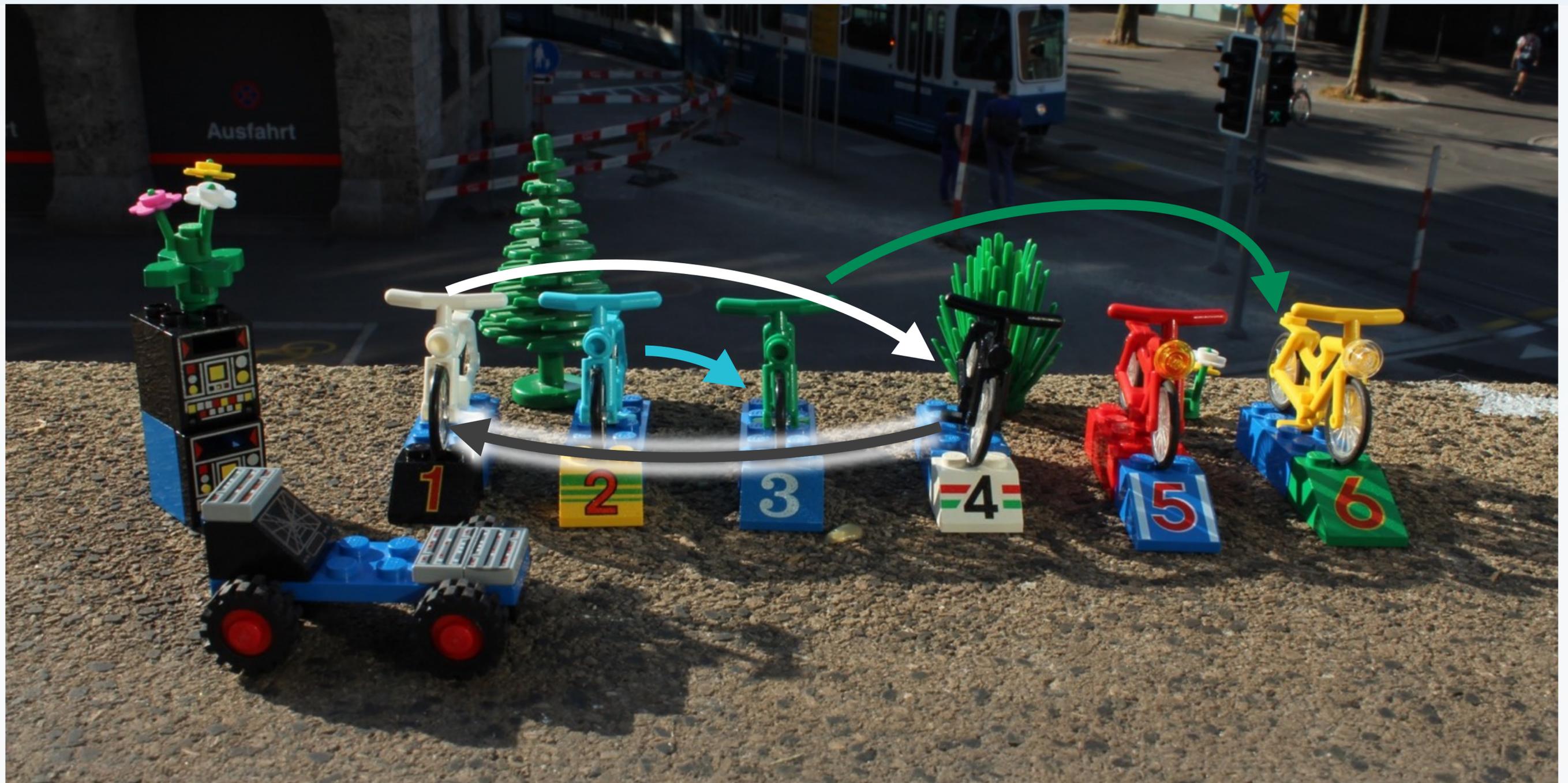
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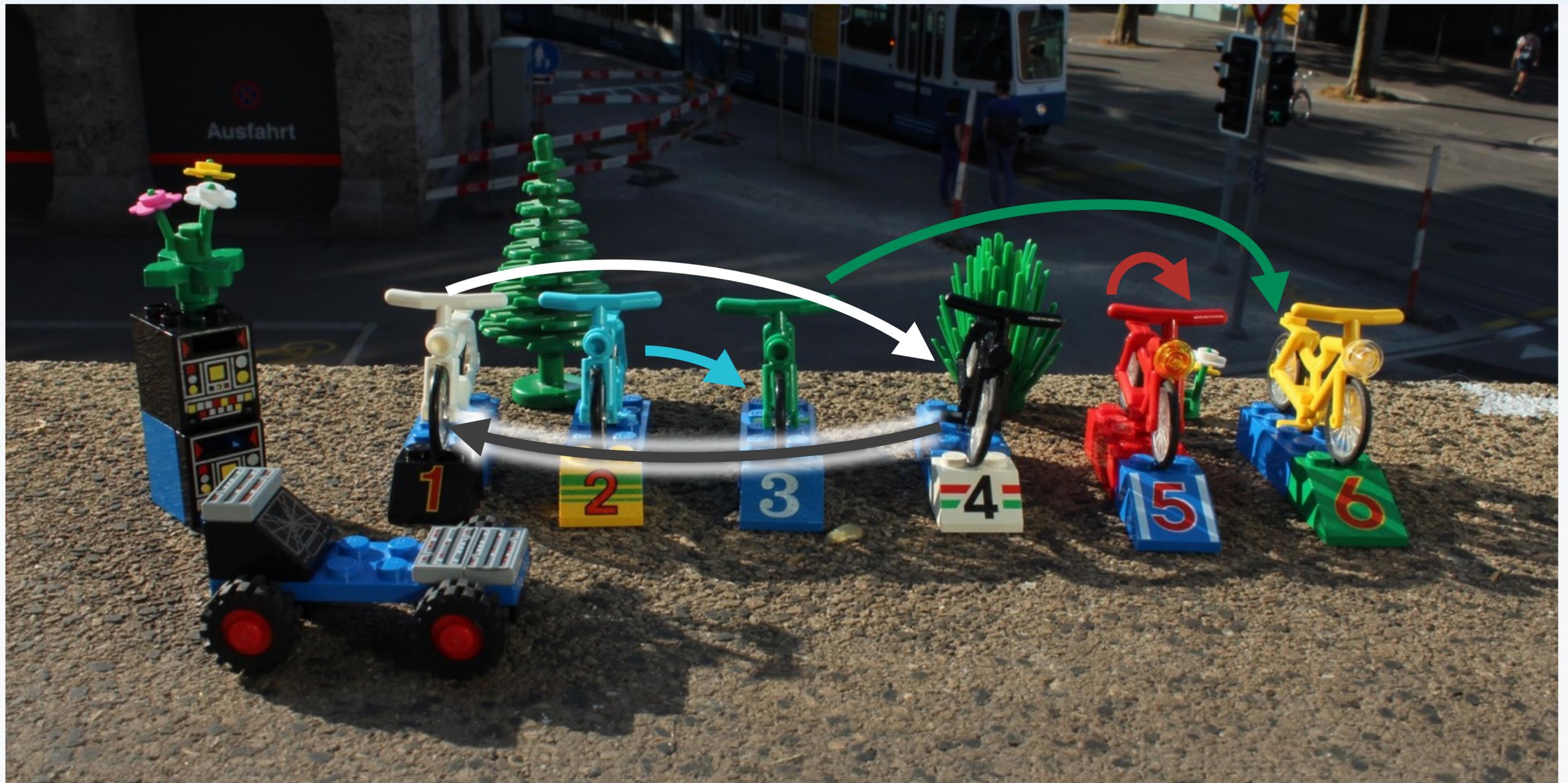
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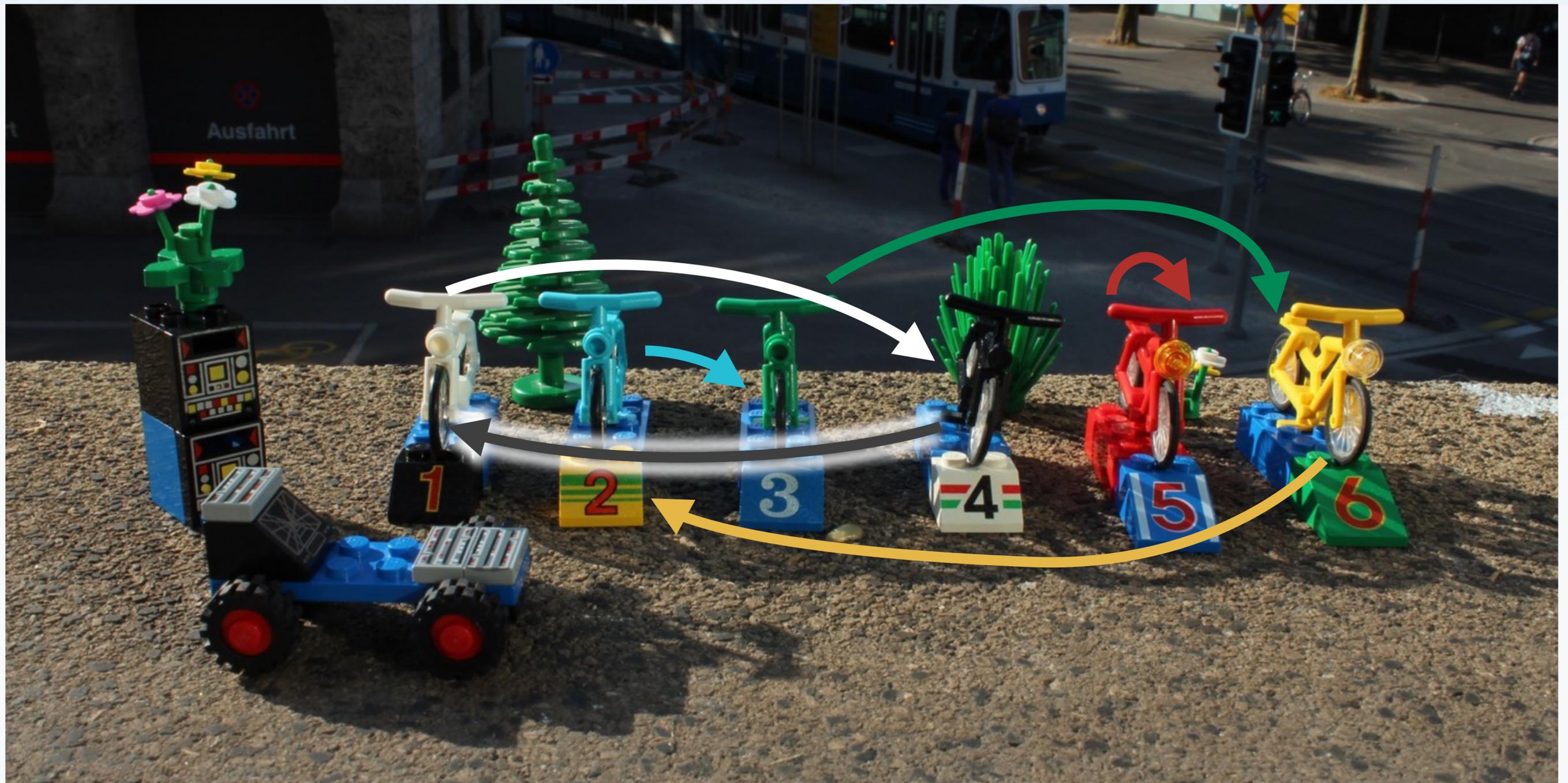
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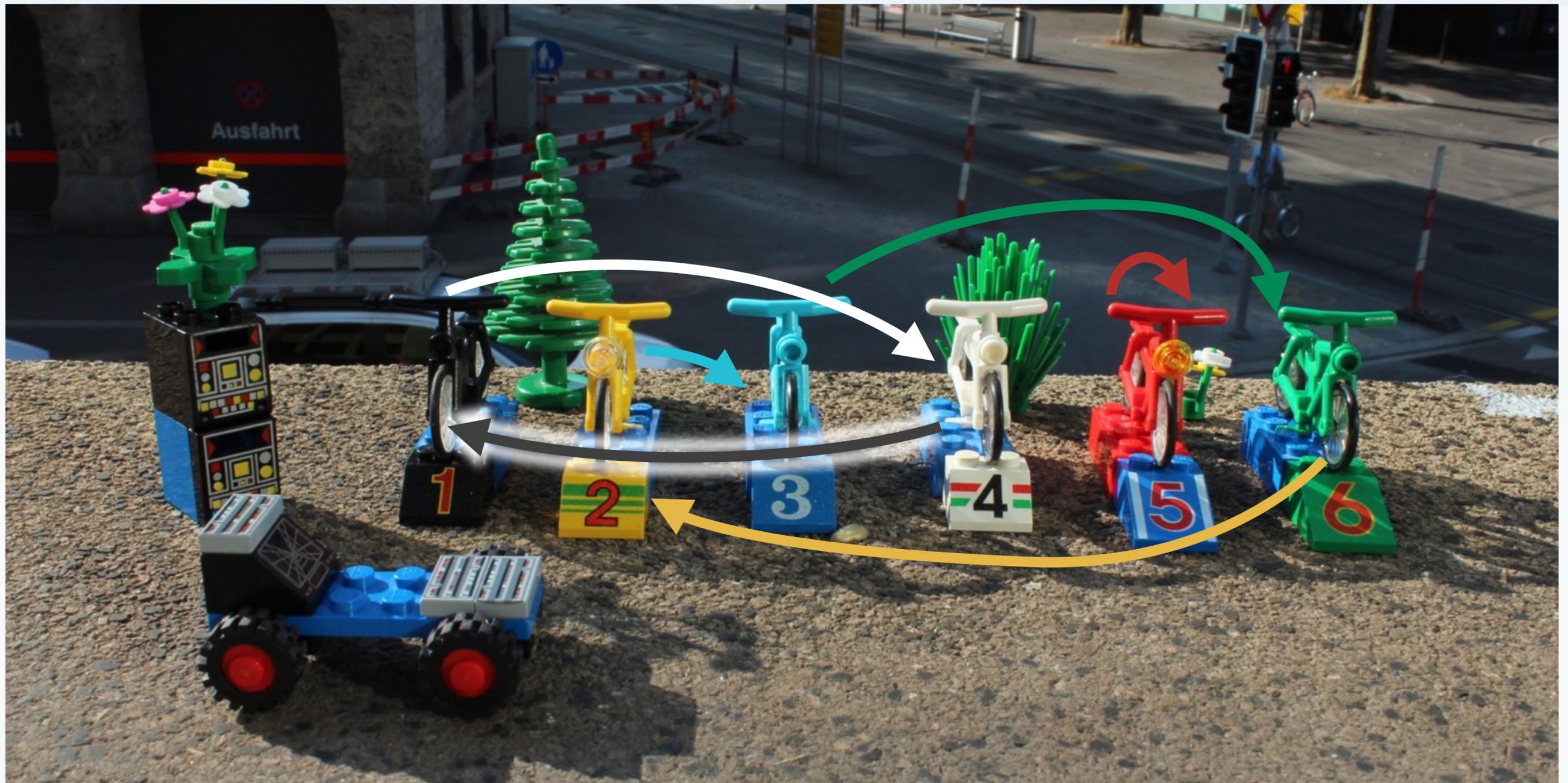
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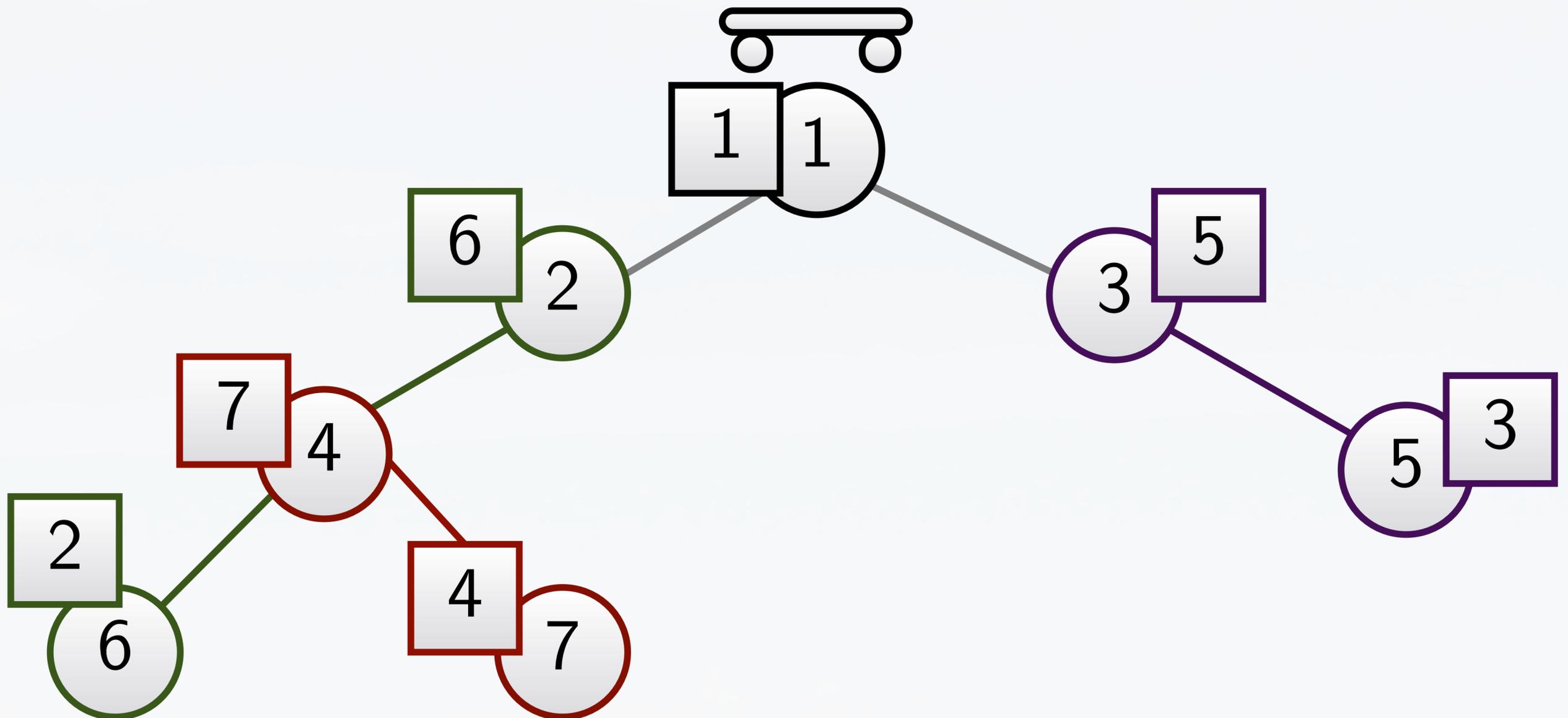
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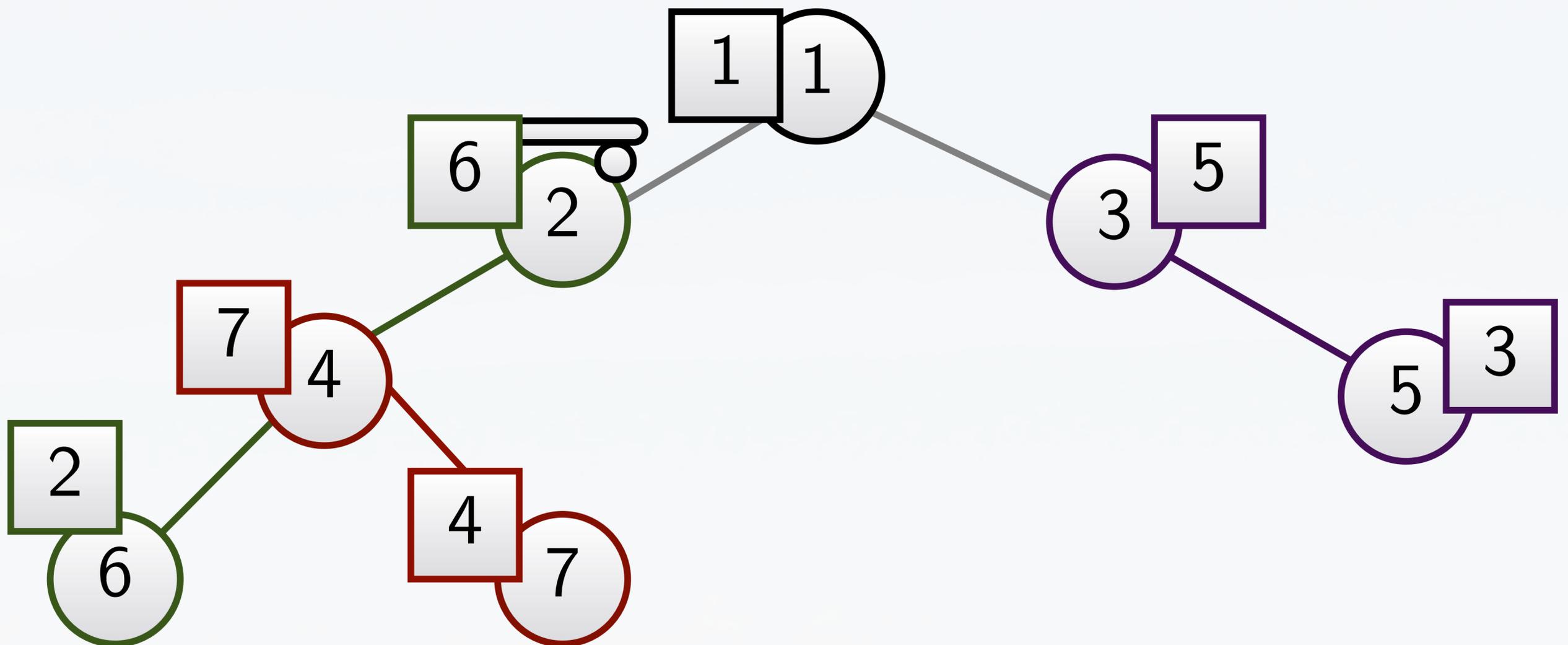
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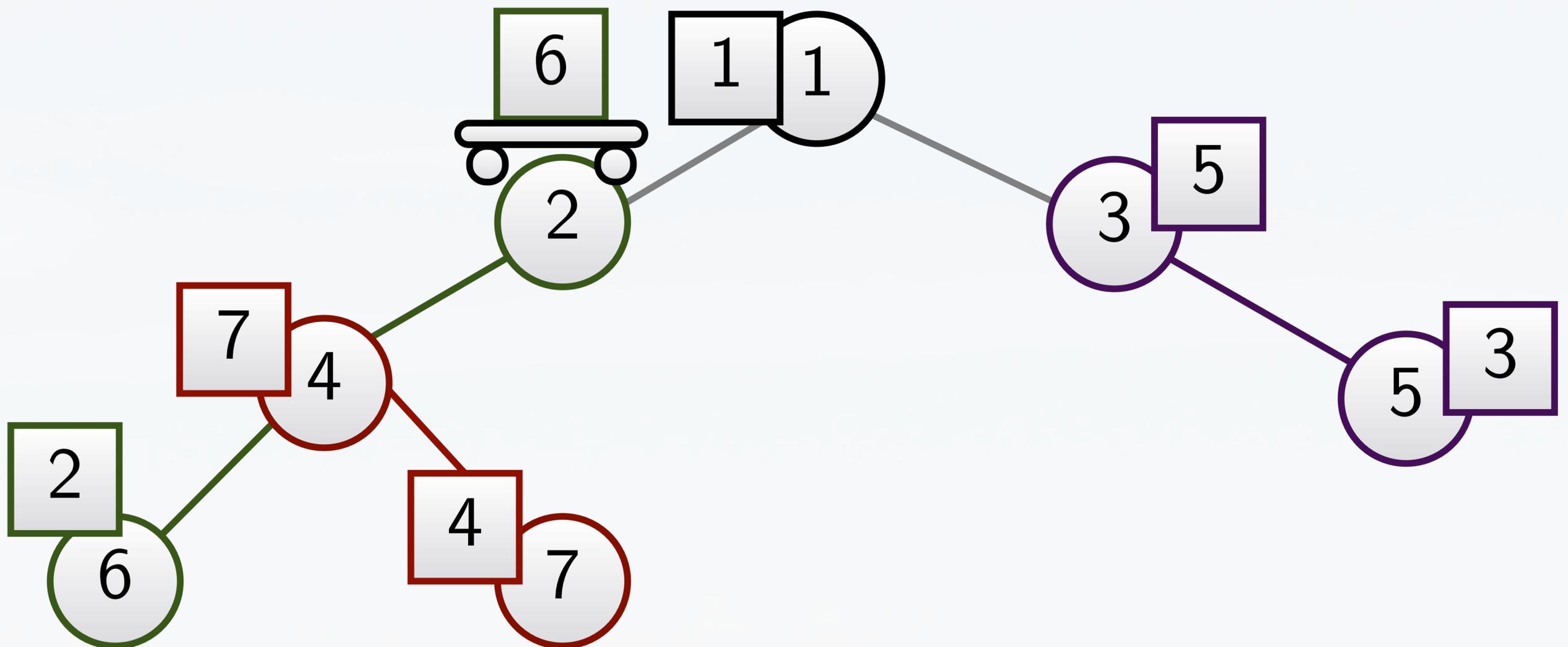
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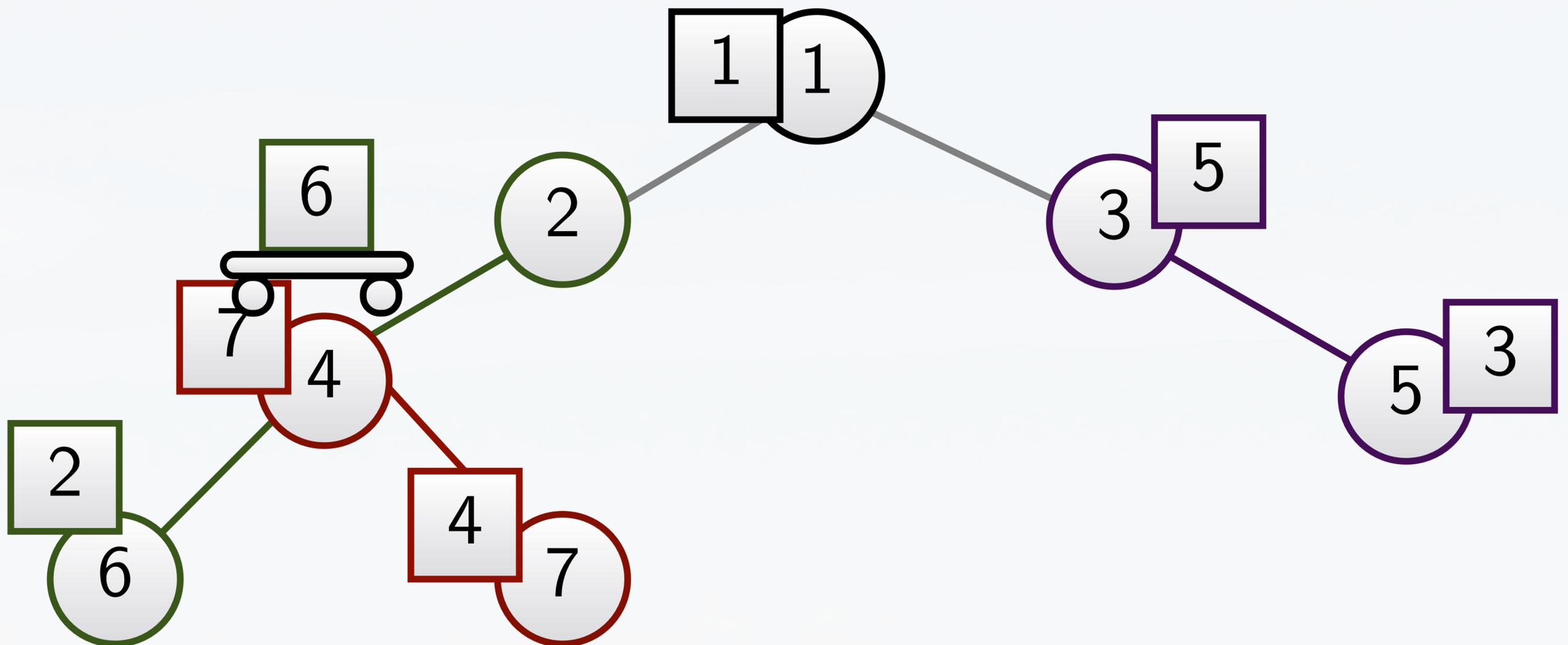
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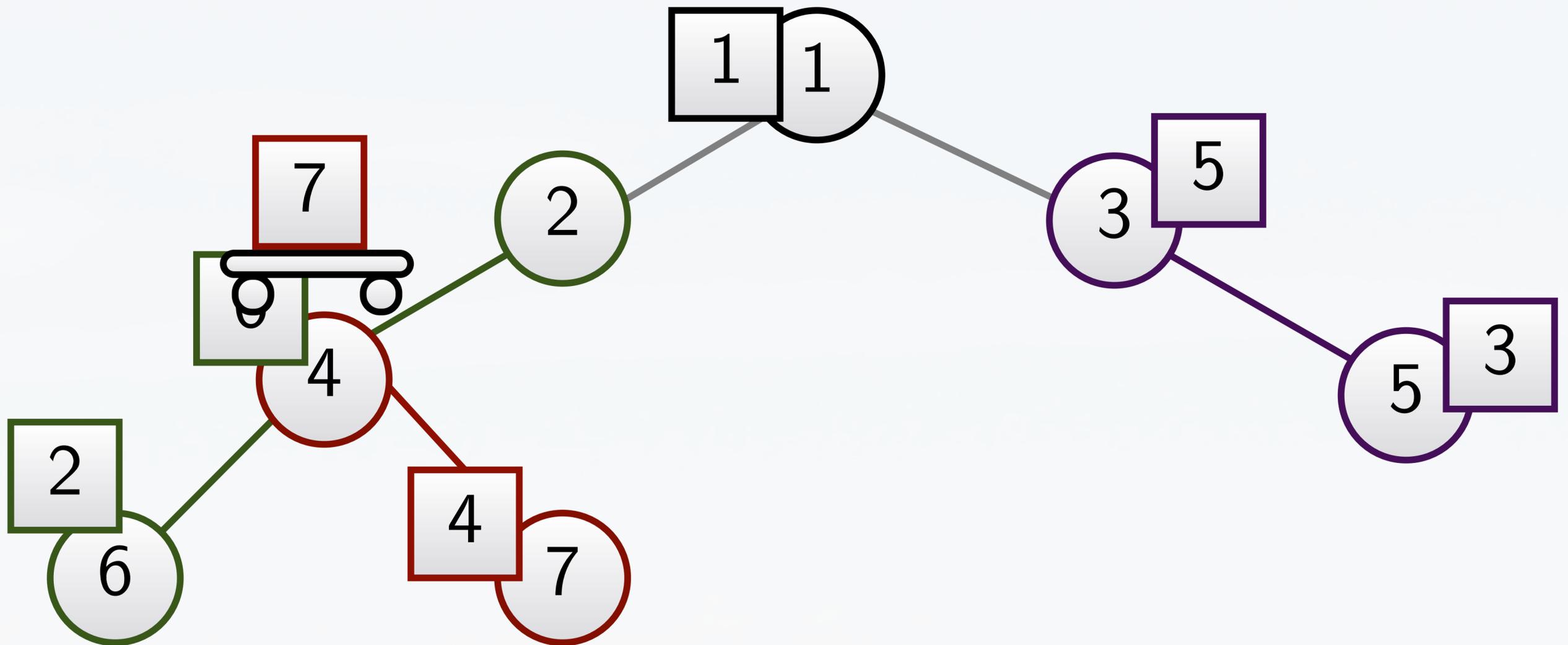
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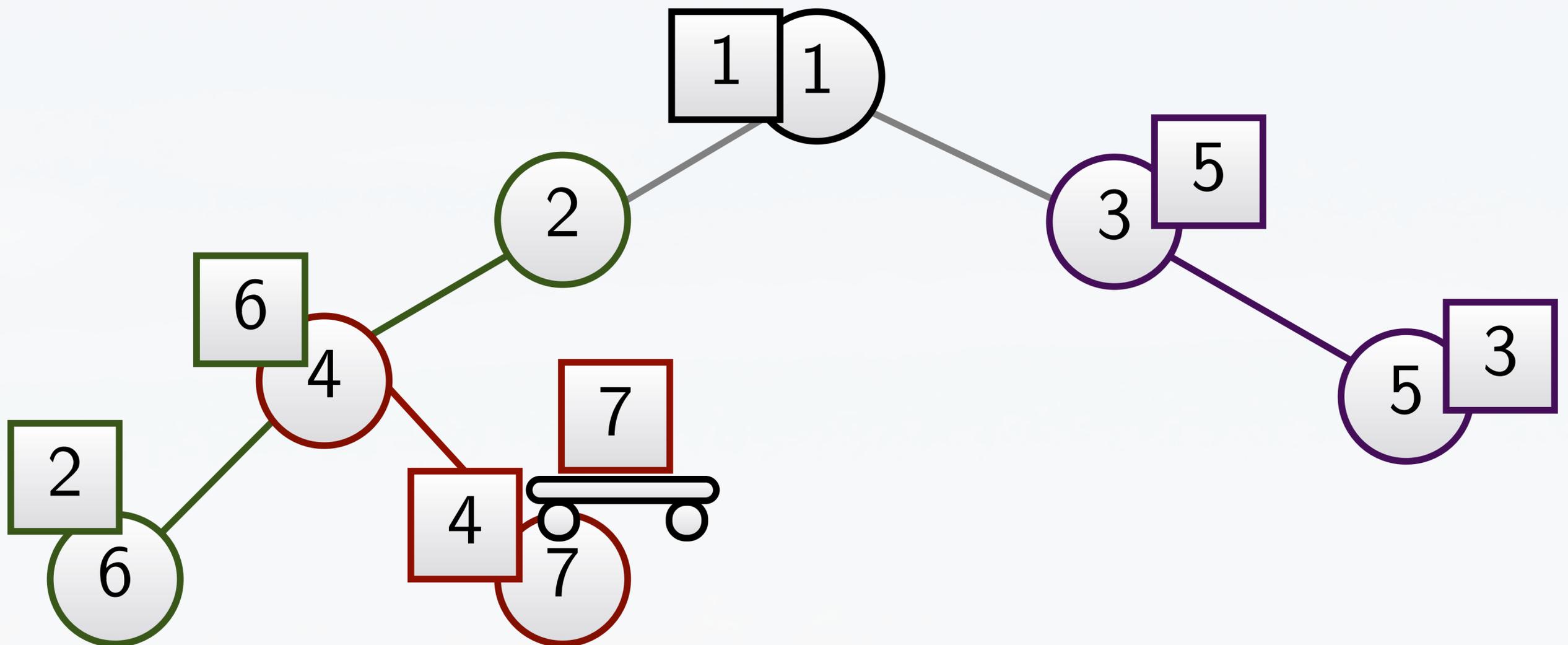
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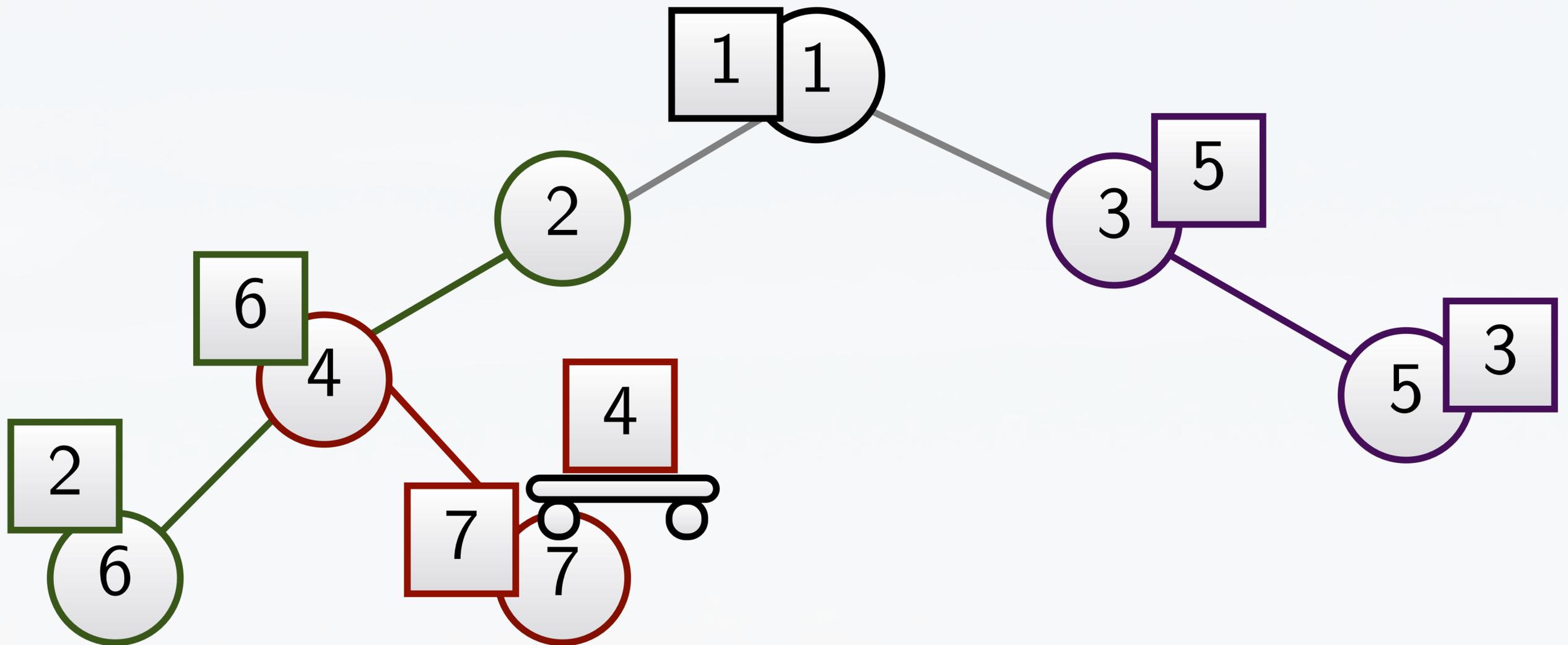
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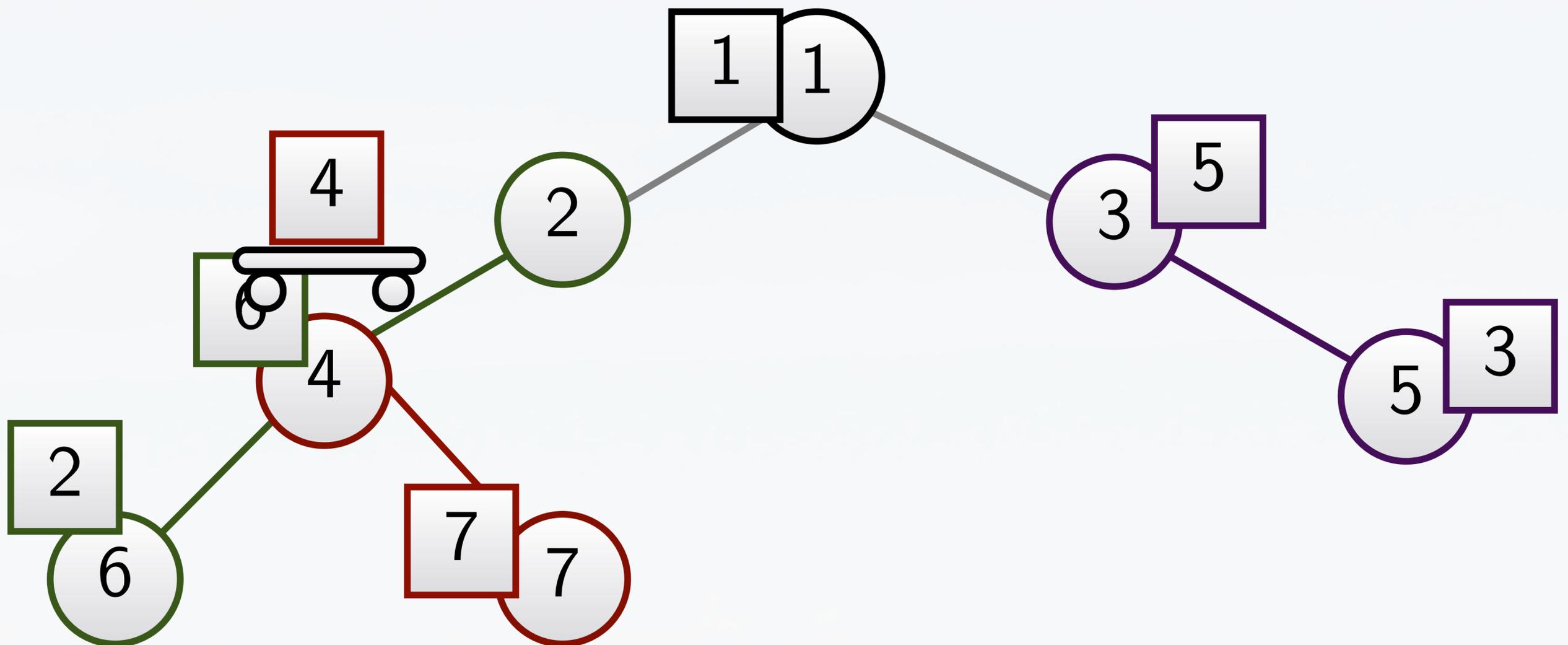
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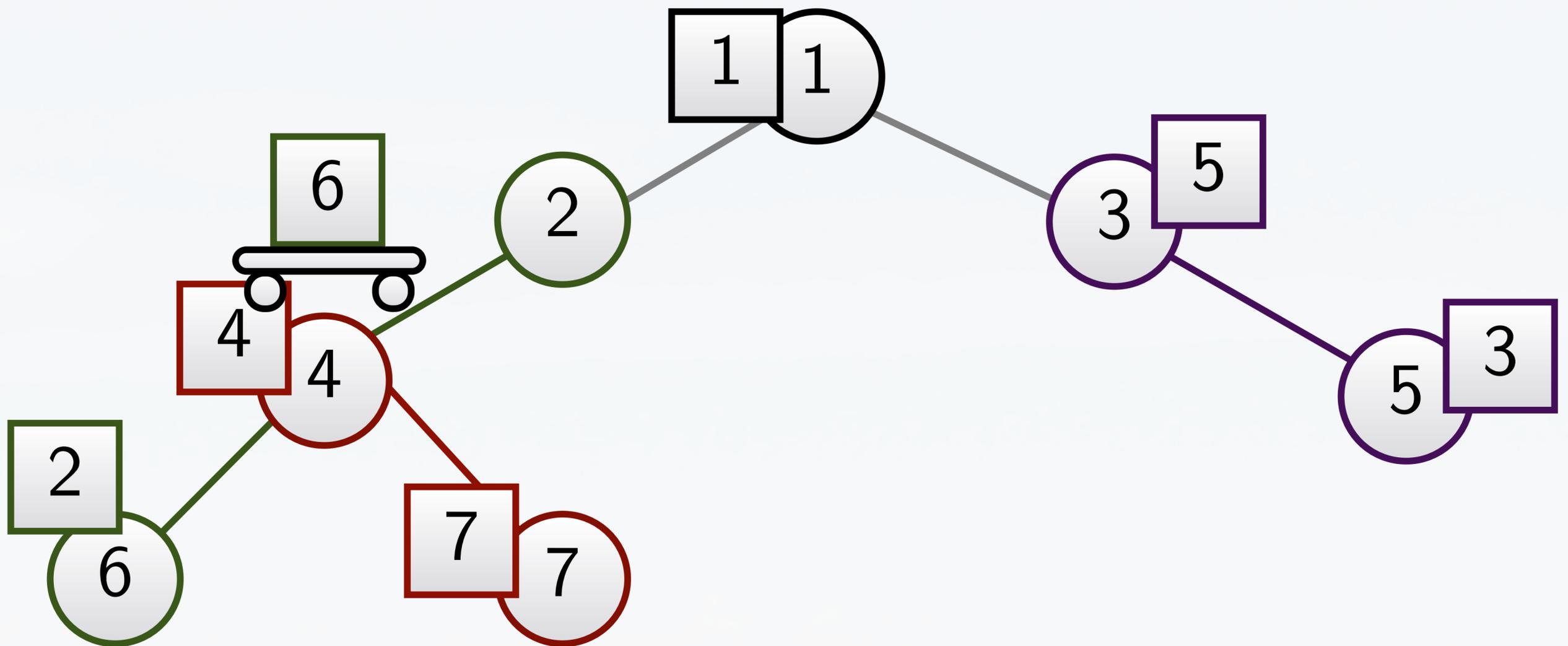
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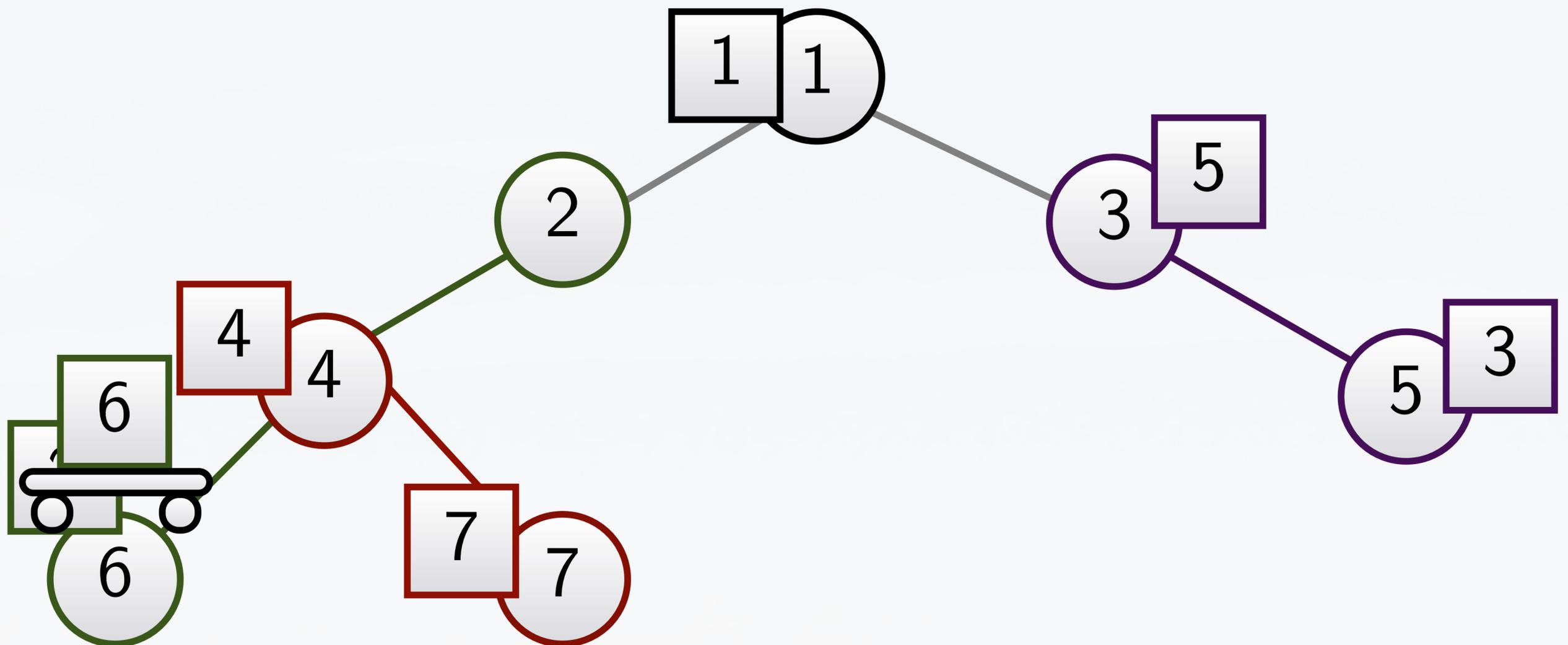
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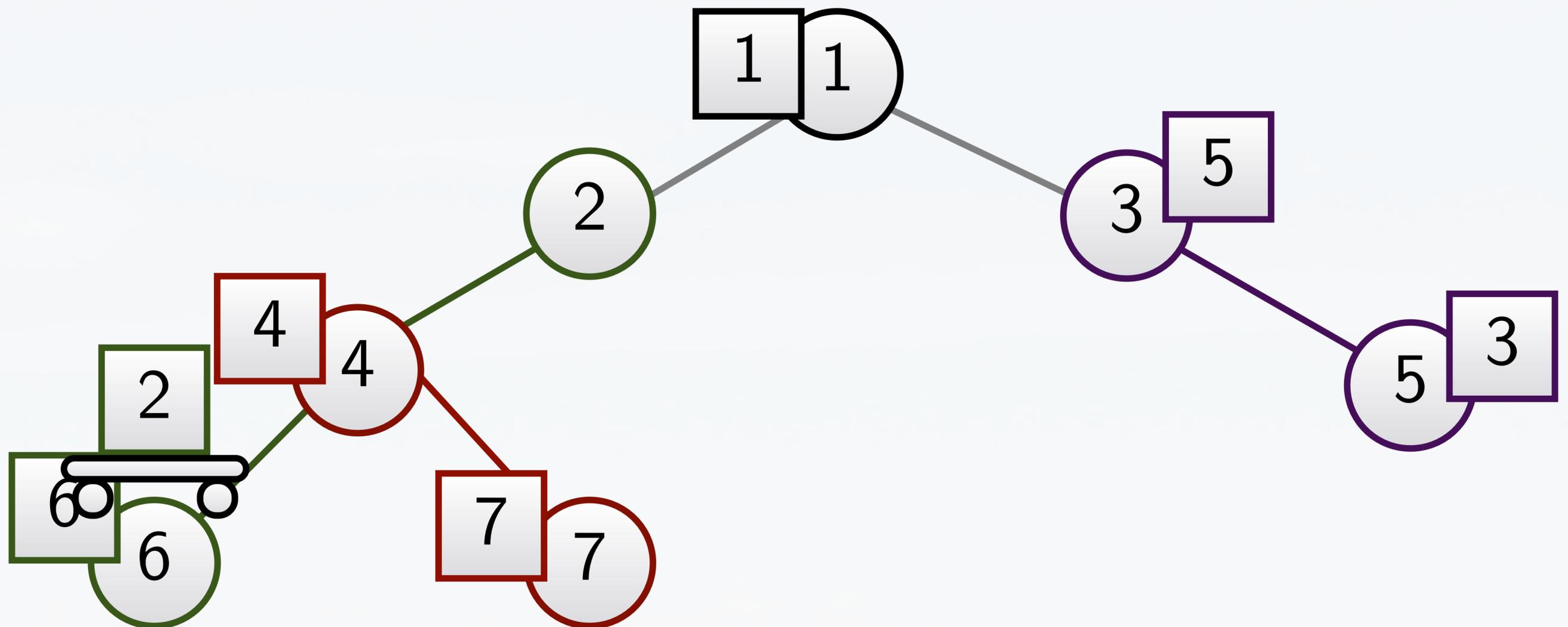
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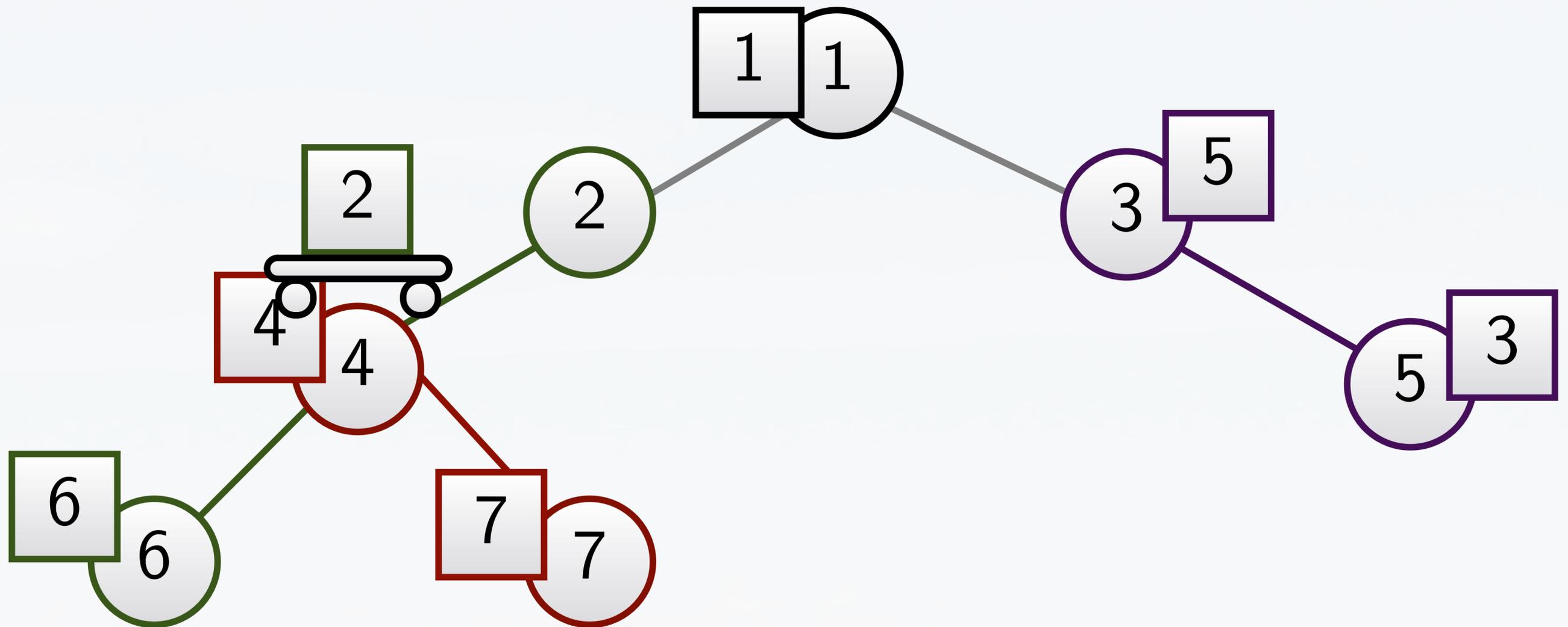
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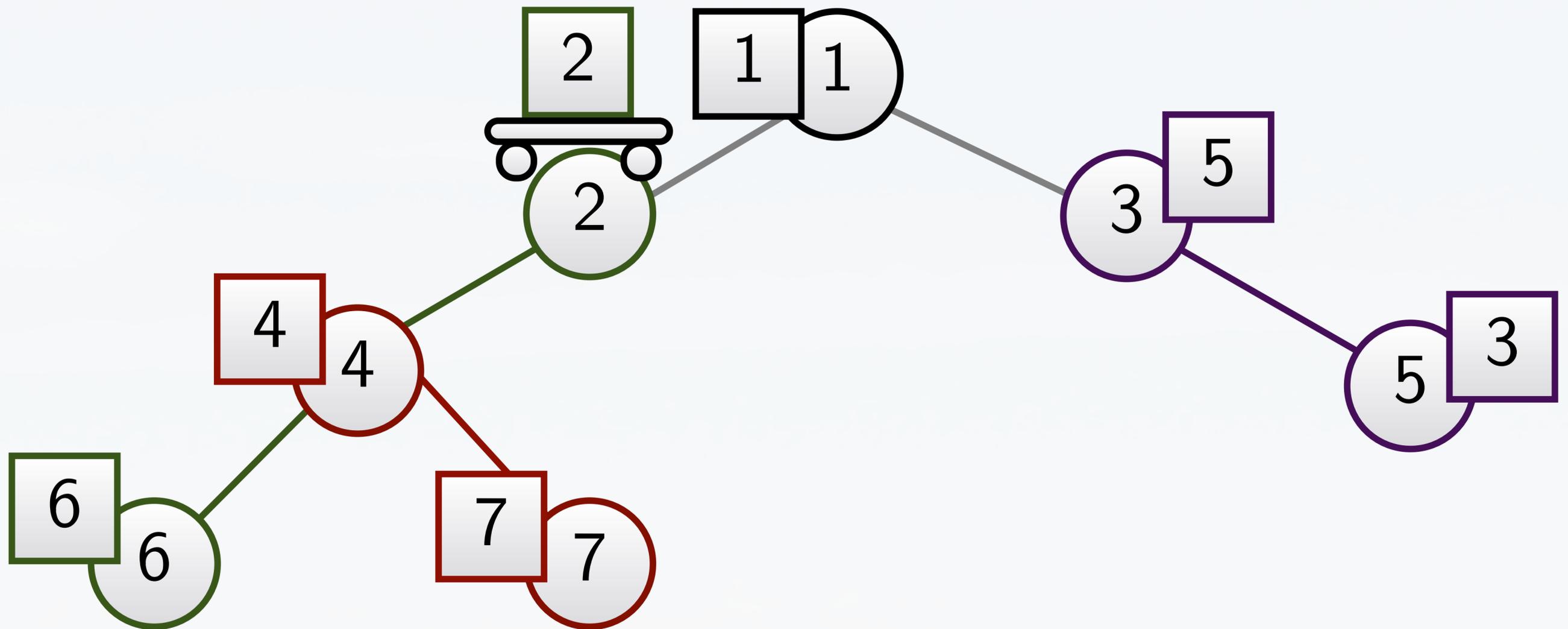
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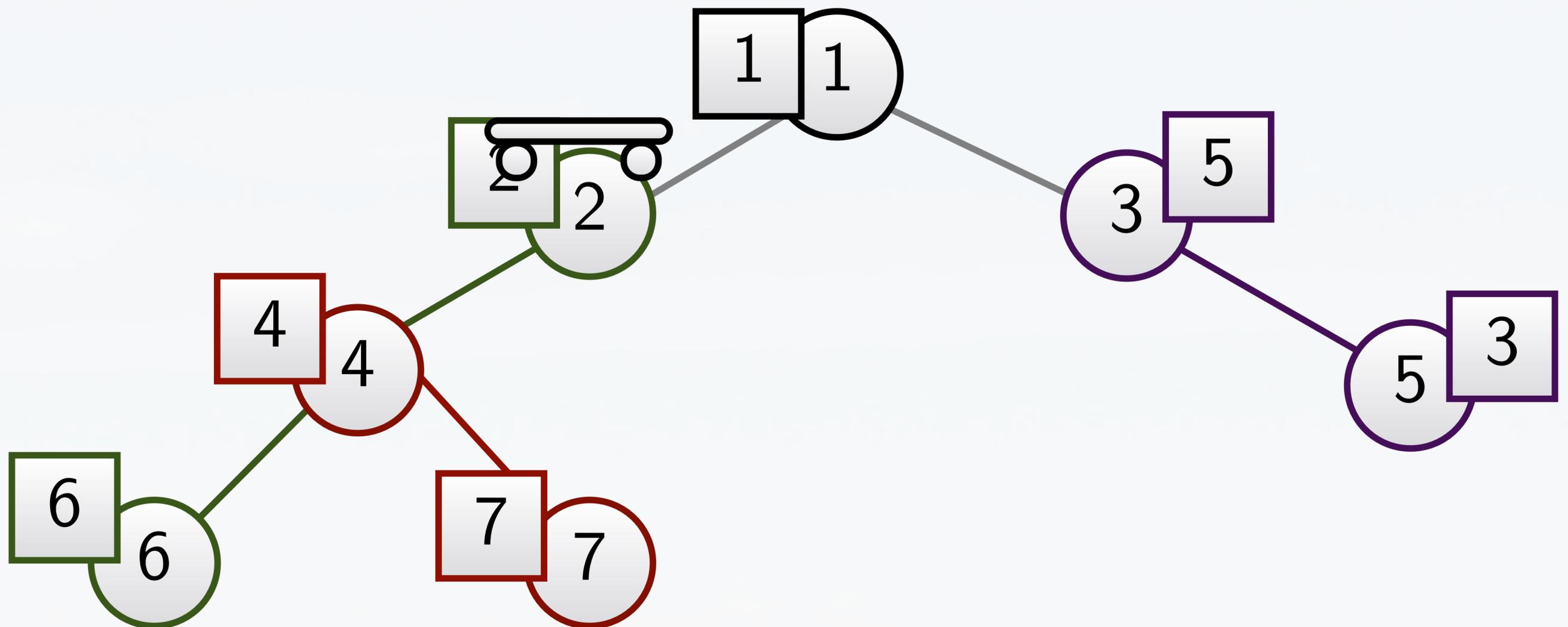
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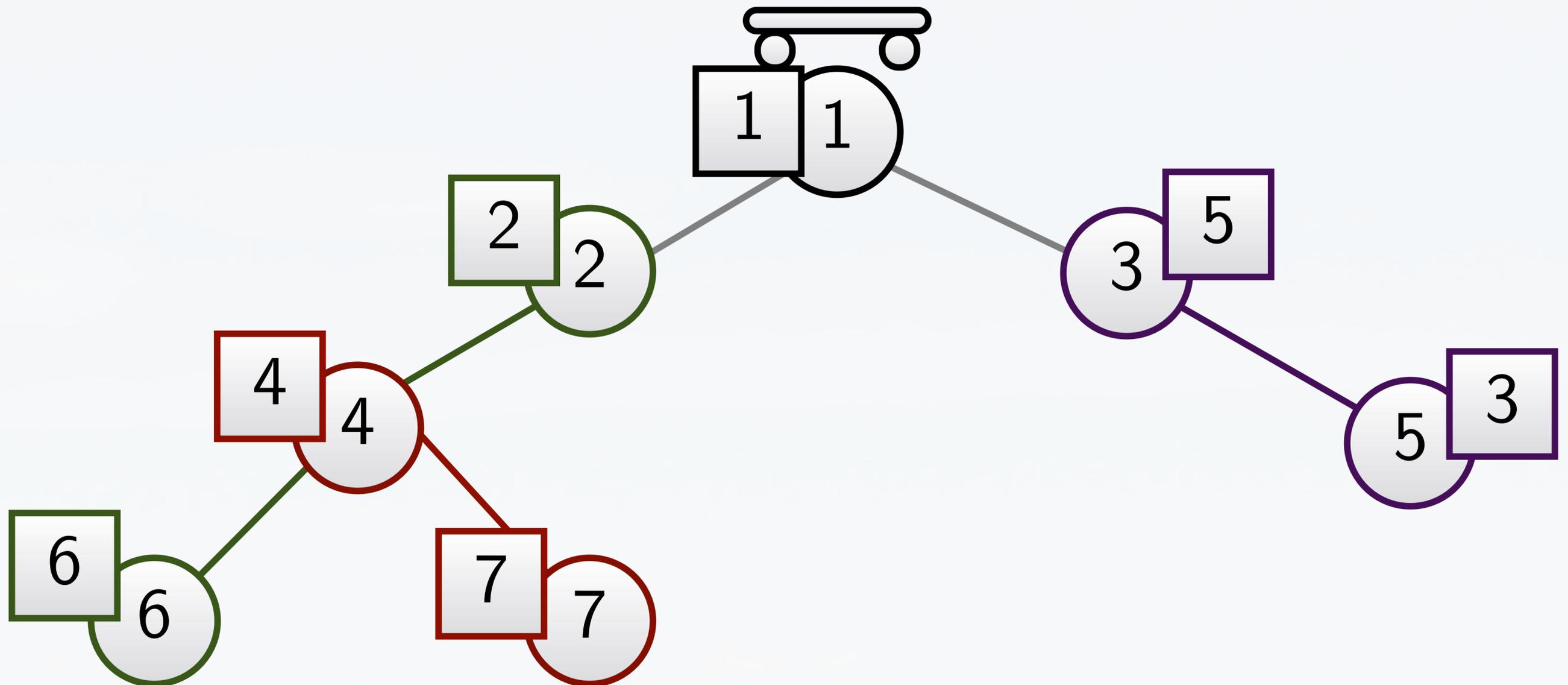
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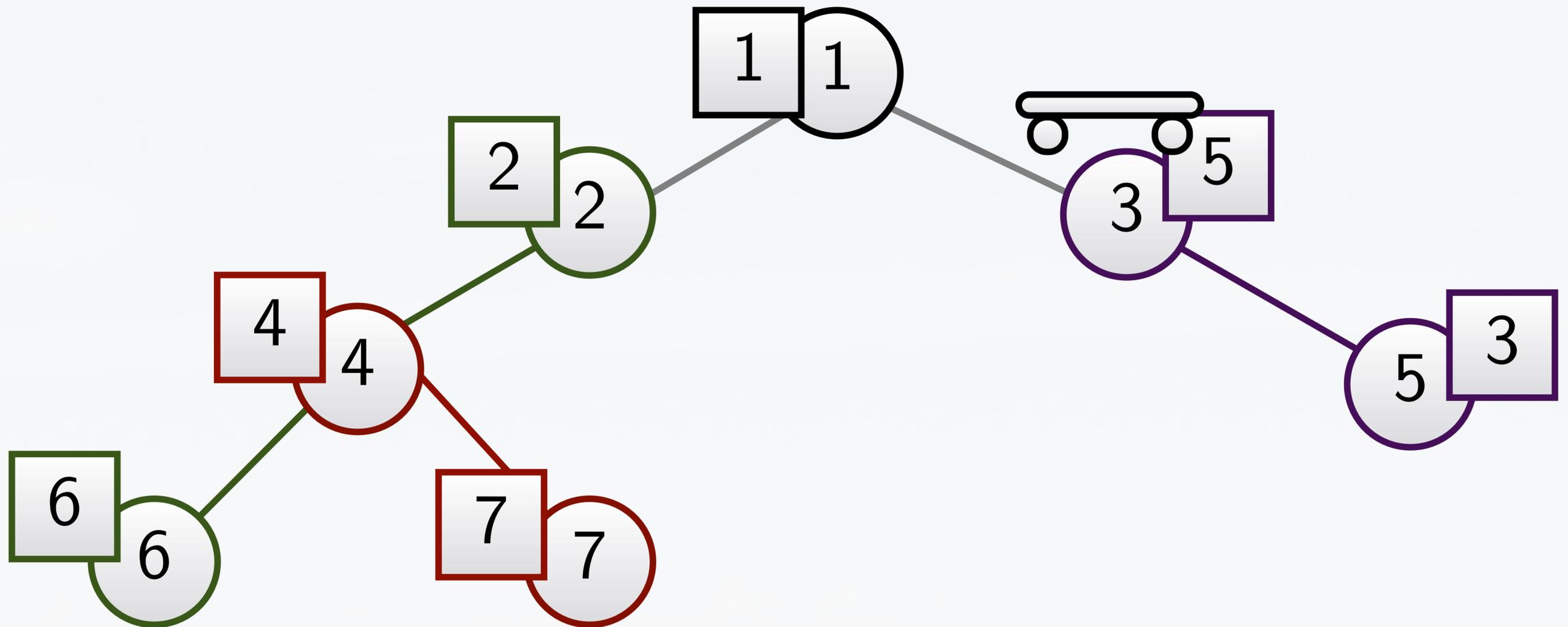
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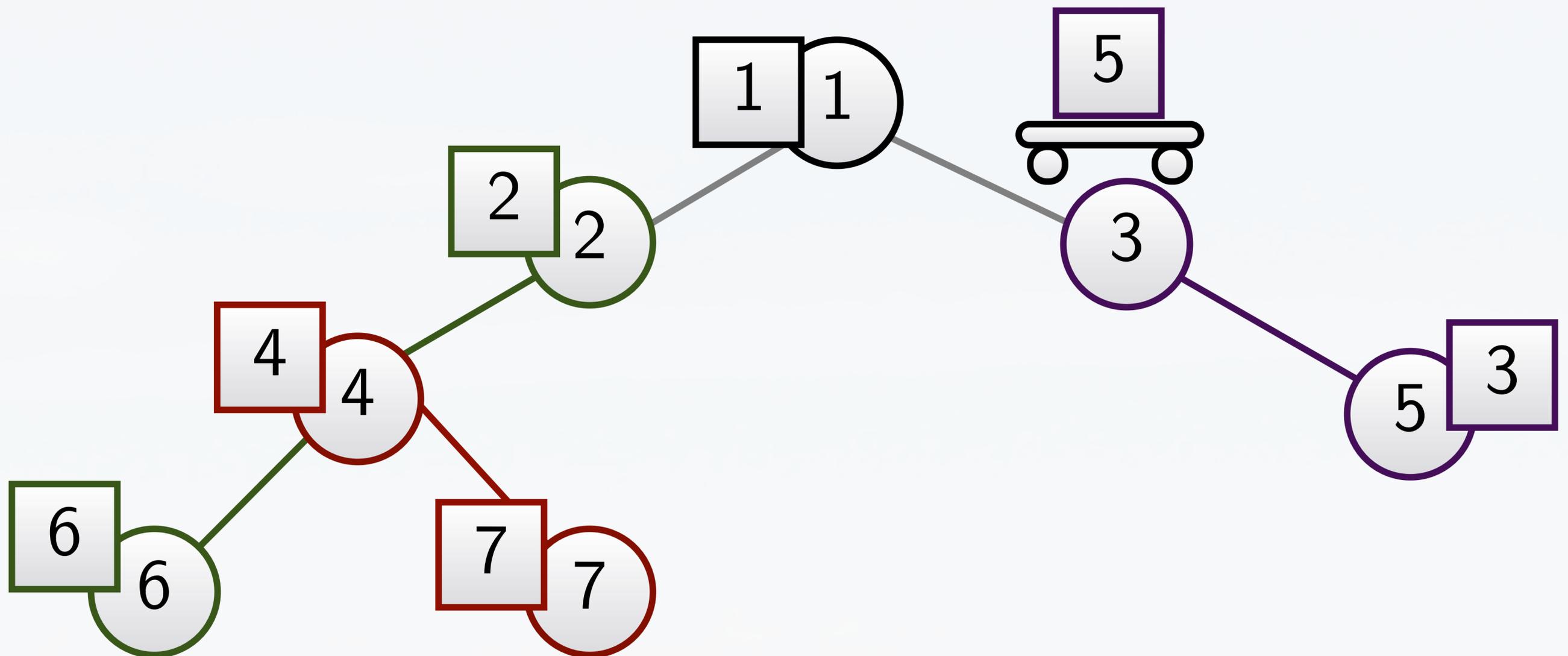
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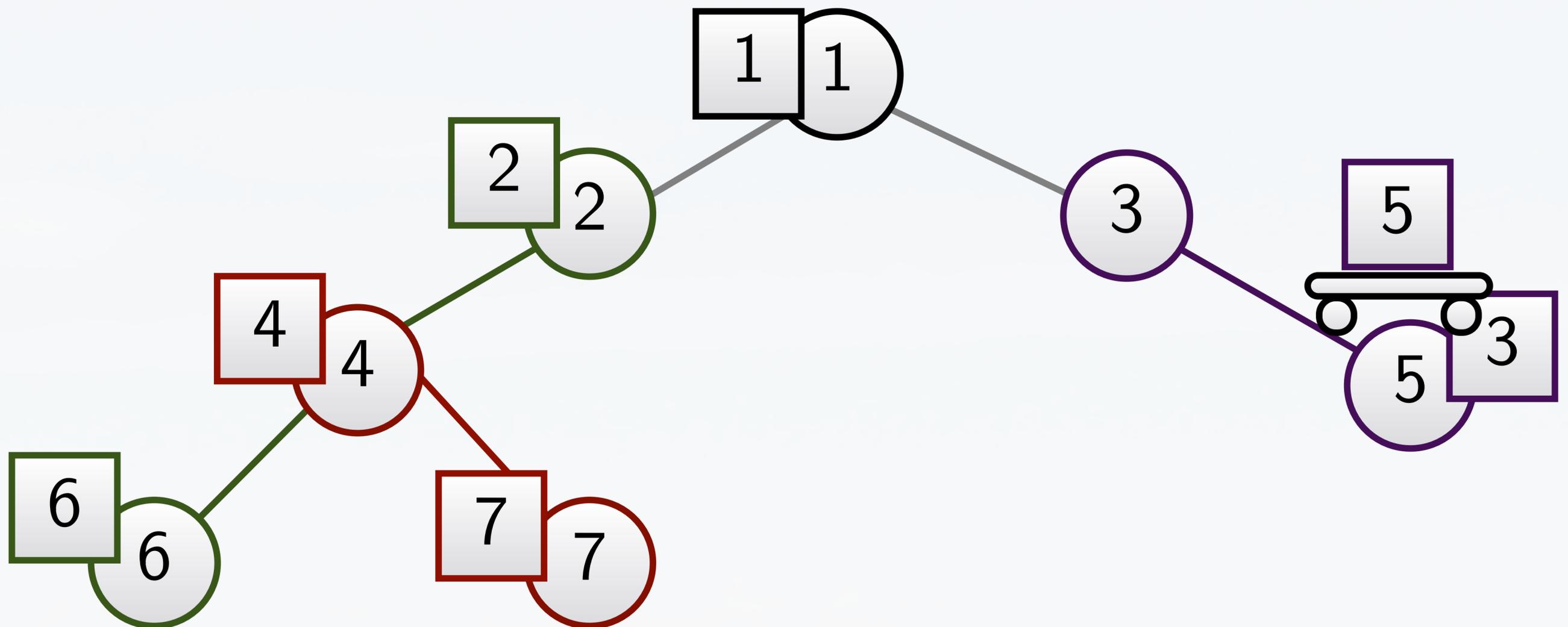
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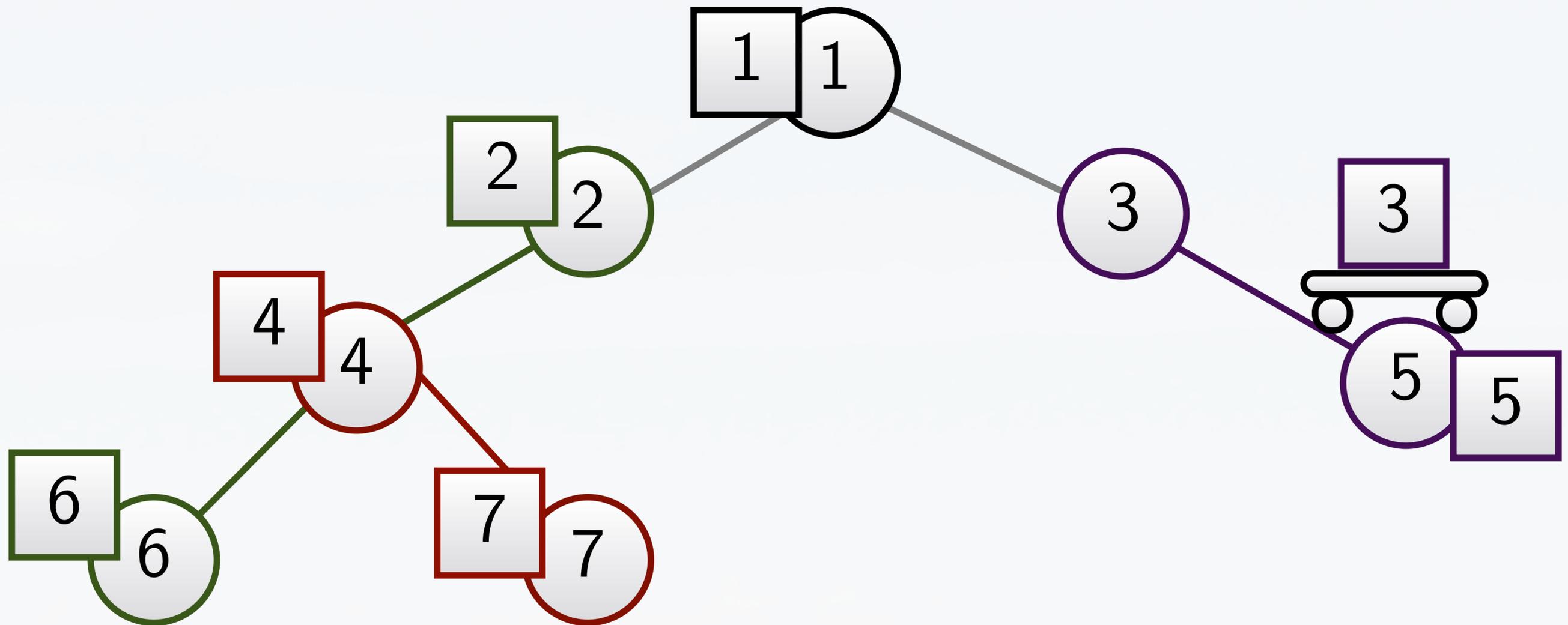
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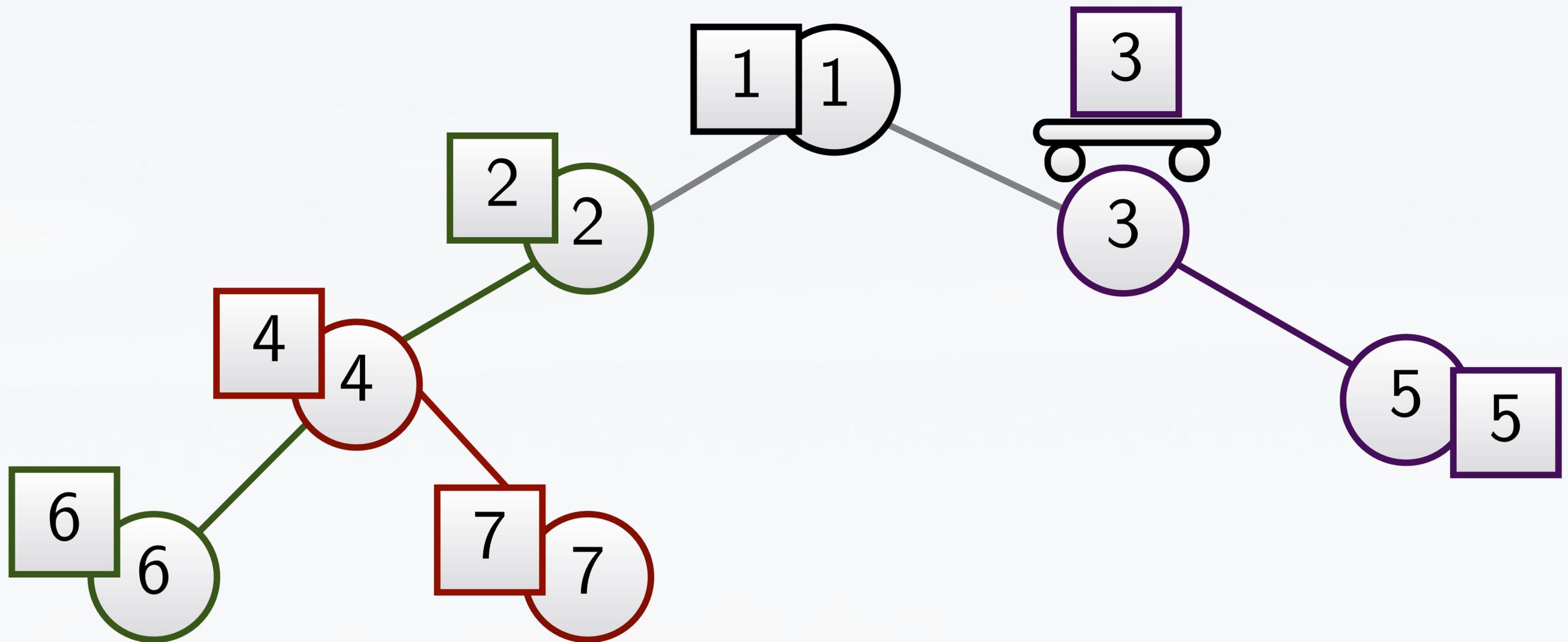
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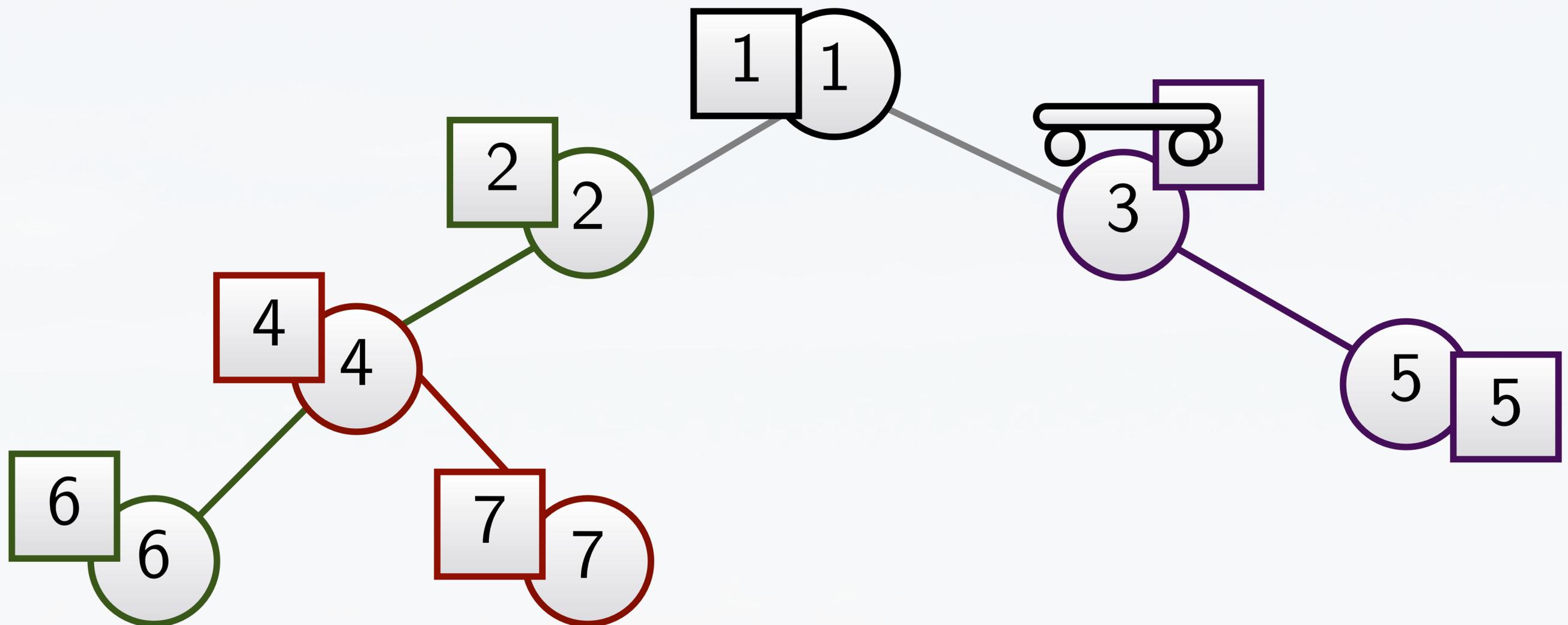
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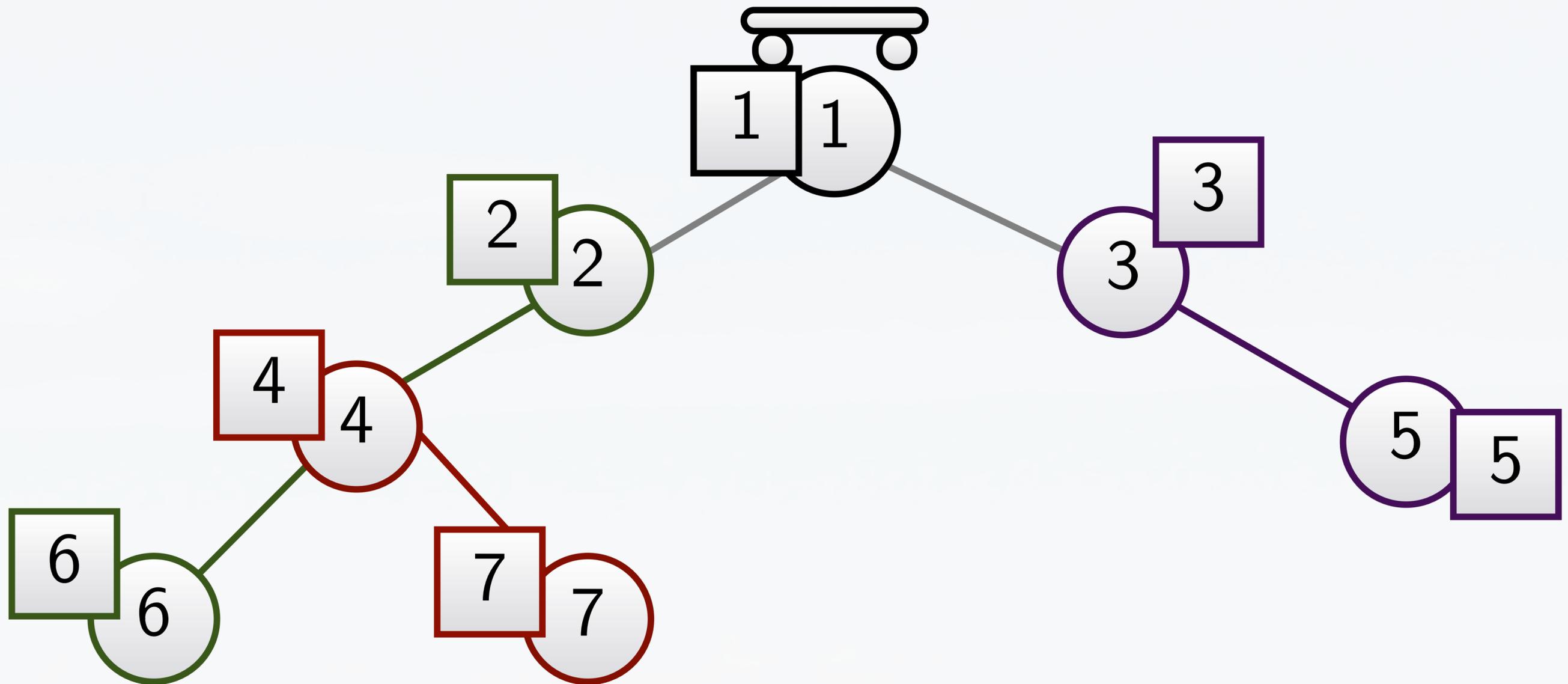
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A step is essential, if it moves a box closer to its target position than it was in any previous state.

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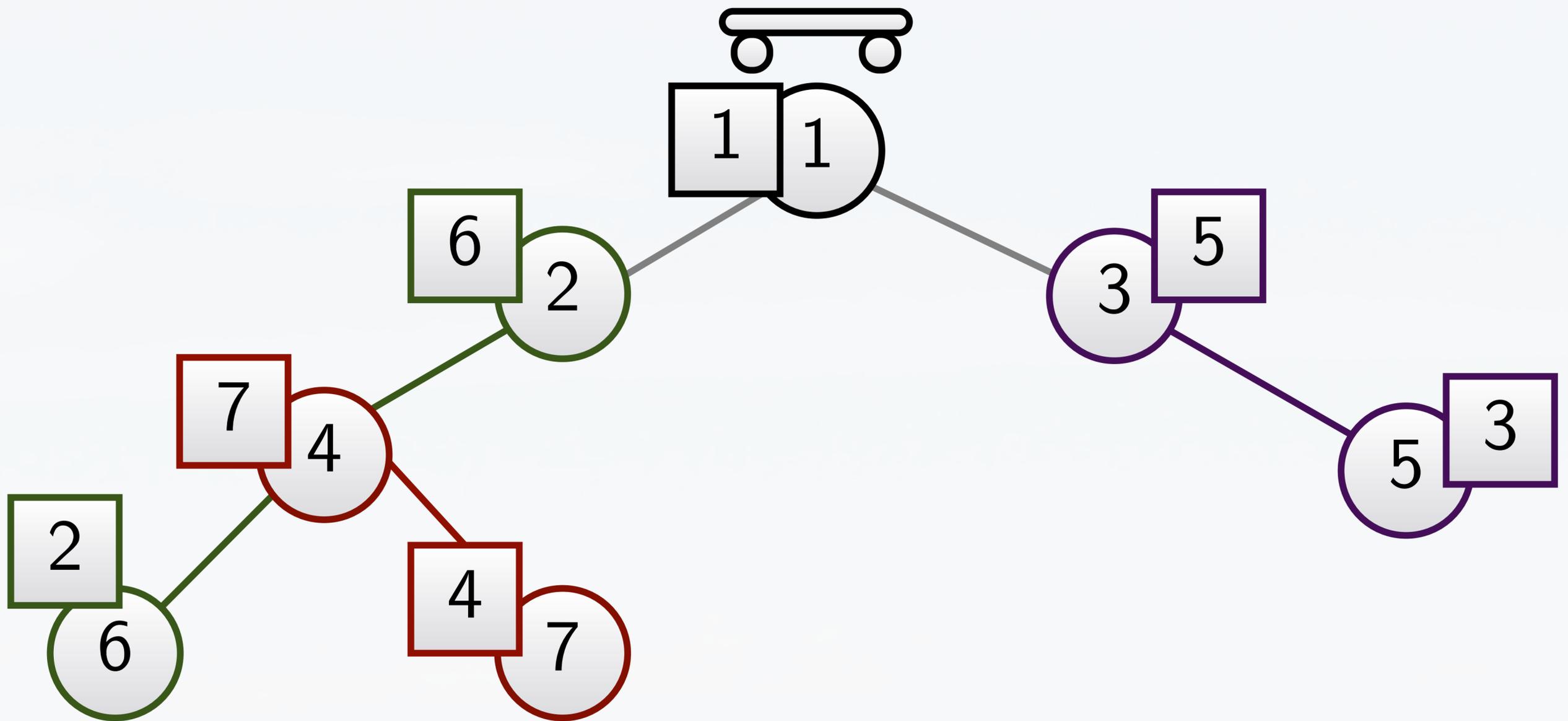
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Lemma: (Lower bound by essential steps)

Every sorting walk contains at least

$$d(\pi) := \sum_{i=1}^n d(i, \pi(i)) \text{ steps.}$$

$$d(\pi) = 1 + 1 + 1 + 1 + 2 + 2 = 8$$



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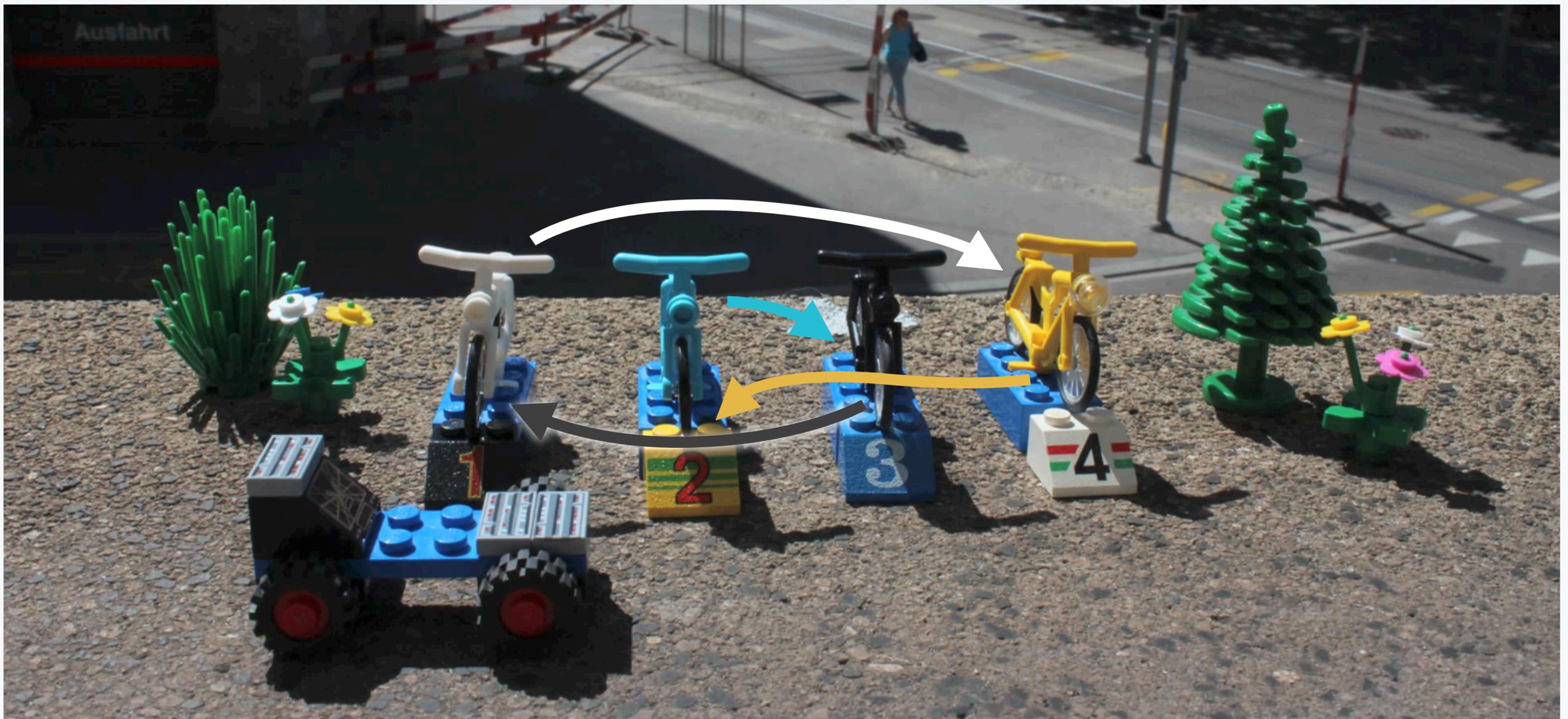
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Remaining: How can we interleave the cycles to close this linear gap between the bounds?

Path graph with the robot starting at the border.
Straightforward if they form a single cycle.



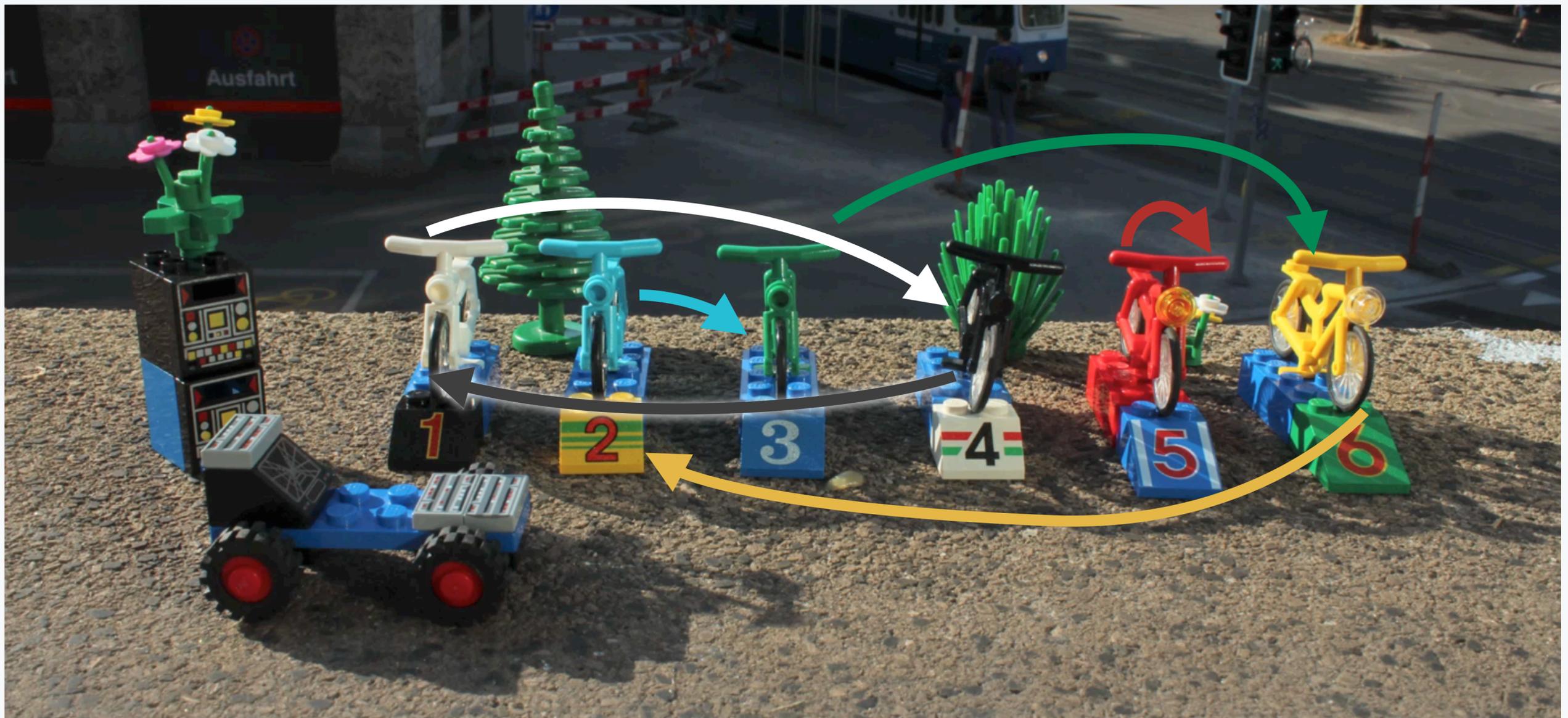
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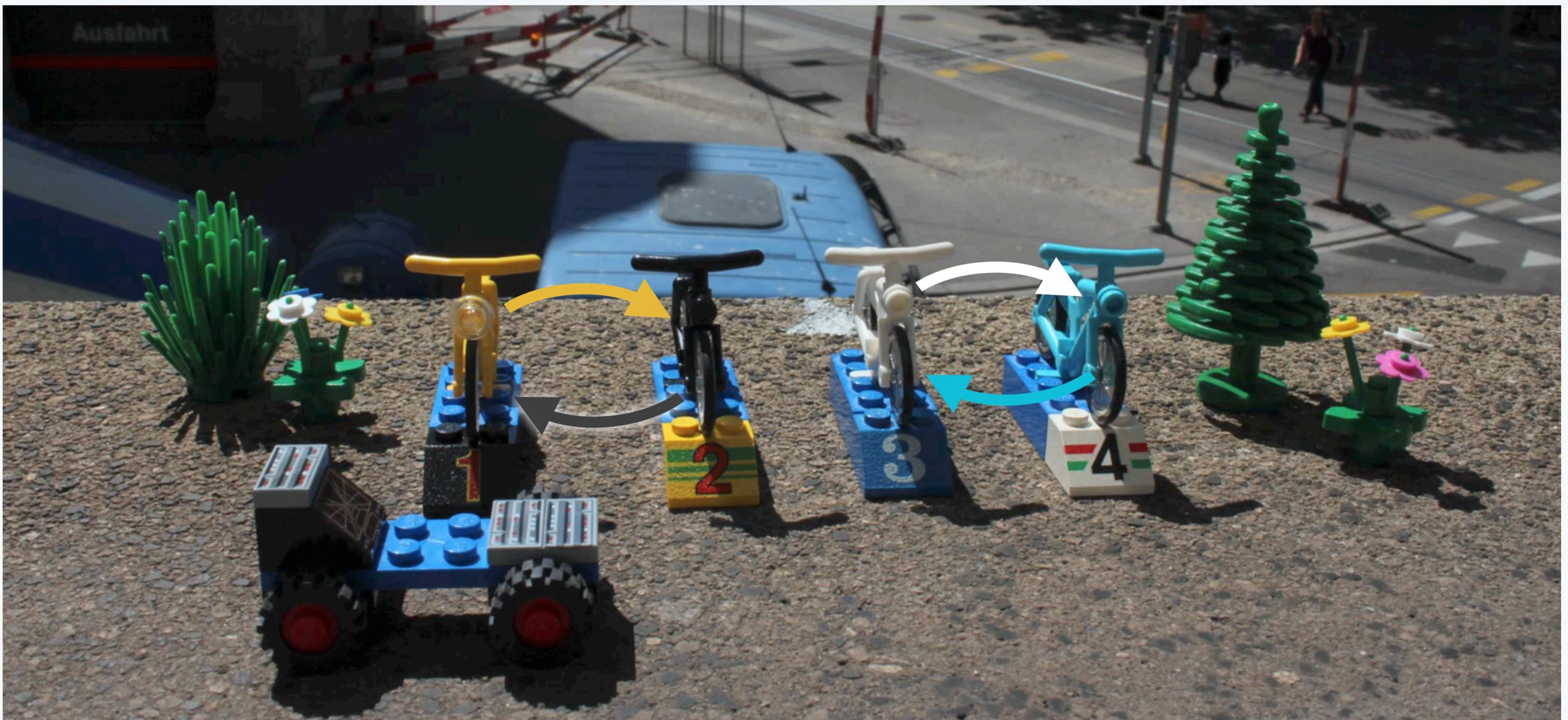
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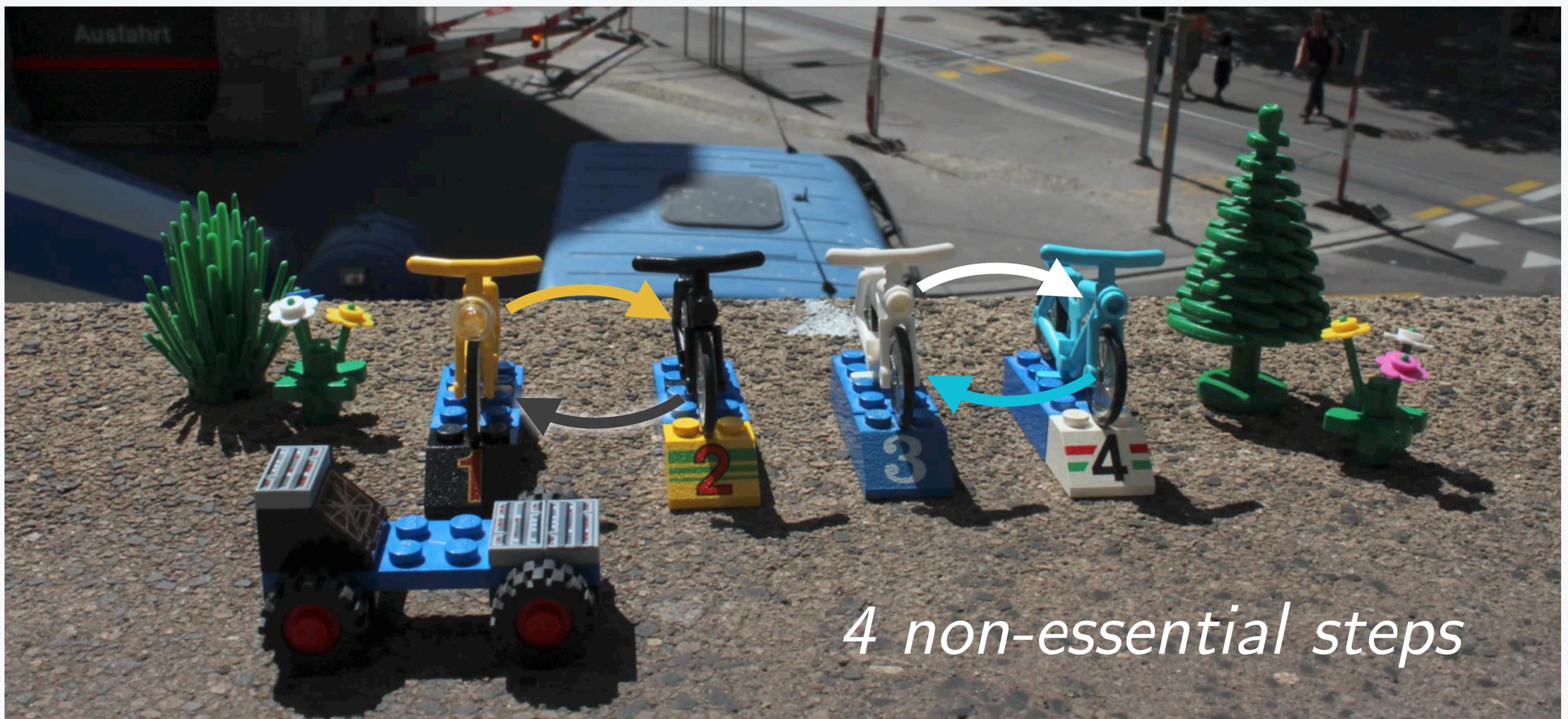
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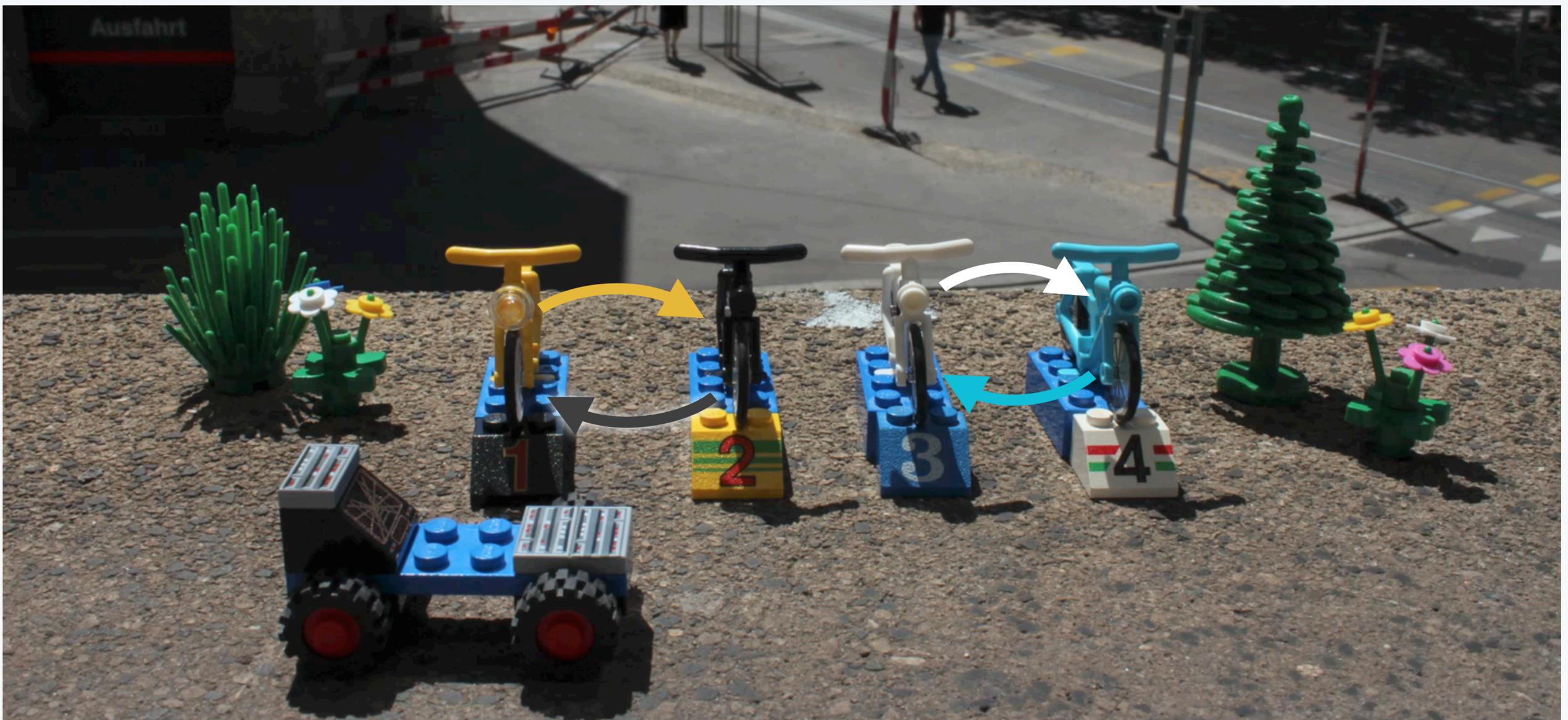
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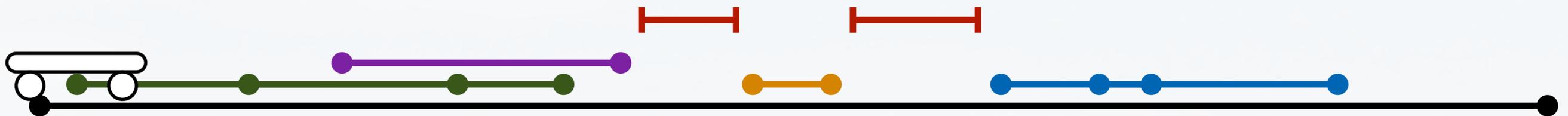


Theorem: The shortest sorting path on a path P has $d(\pi) + 2 \cdot (\# \text{uncovered edges between cycles})$ steps and can be found in time $\mathcal{O}(n^2)$.

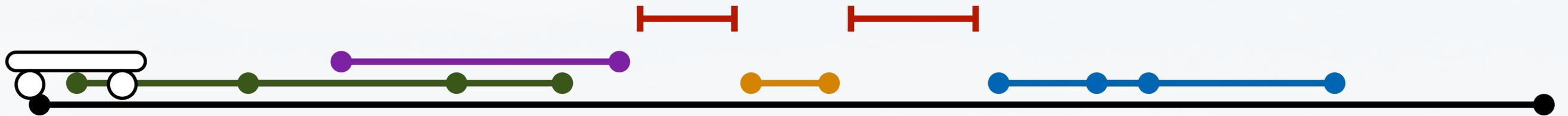
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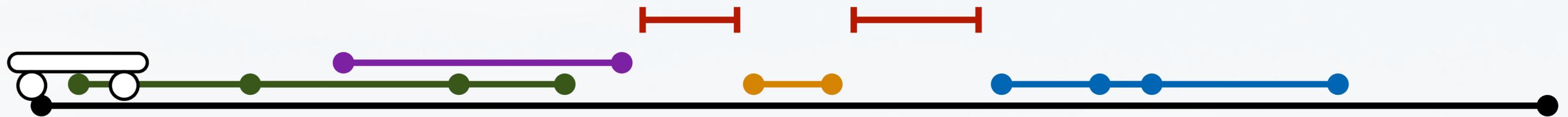


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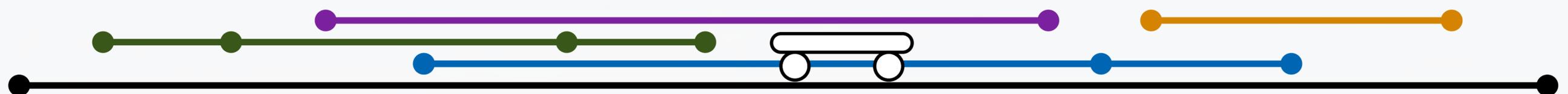
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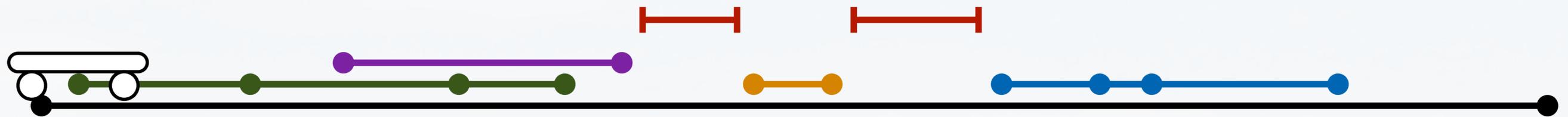
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Open: What if we do not start at the border?



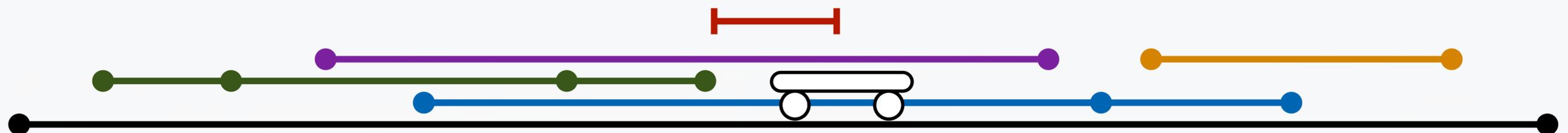
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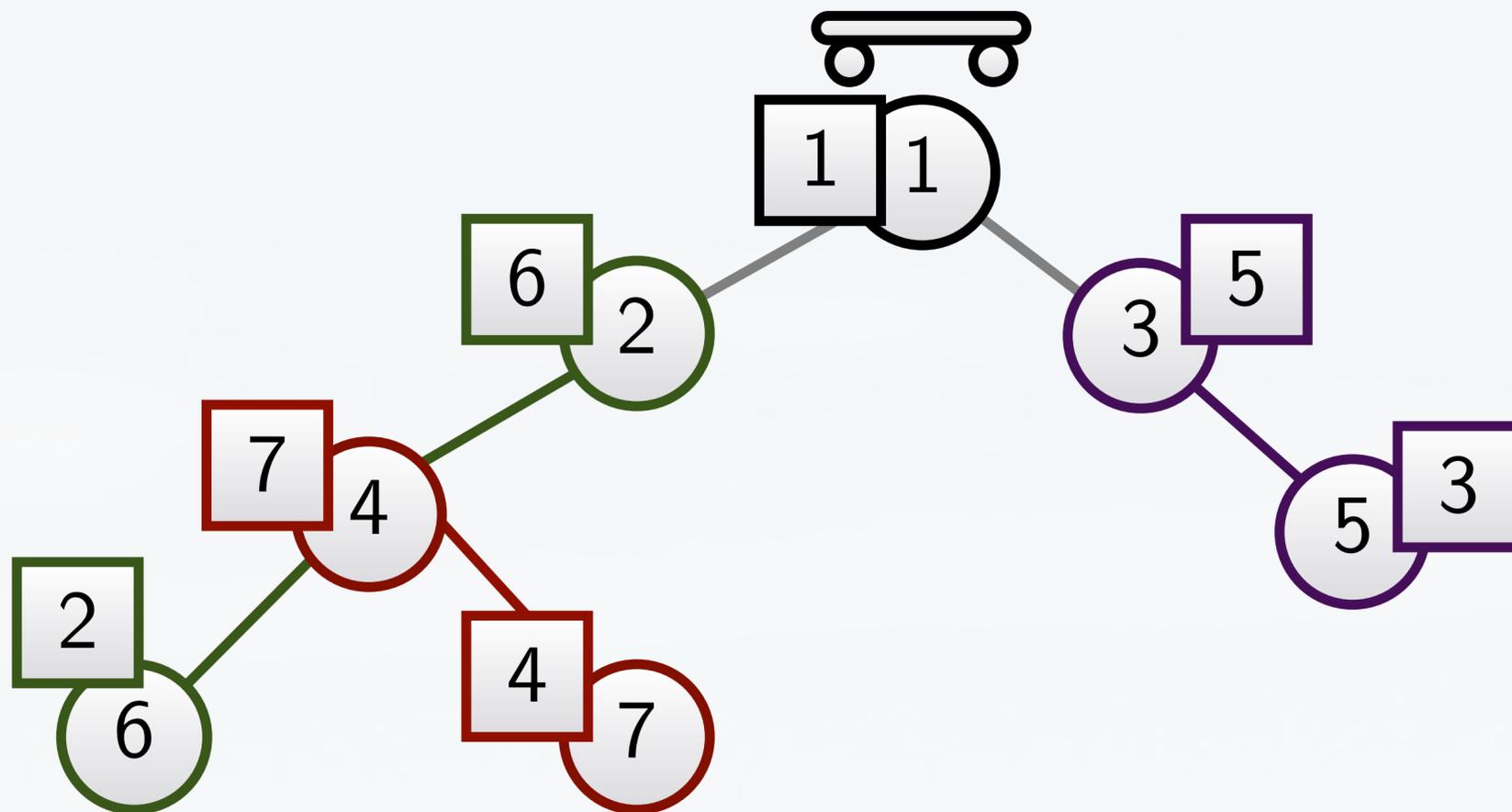
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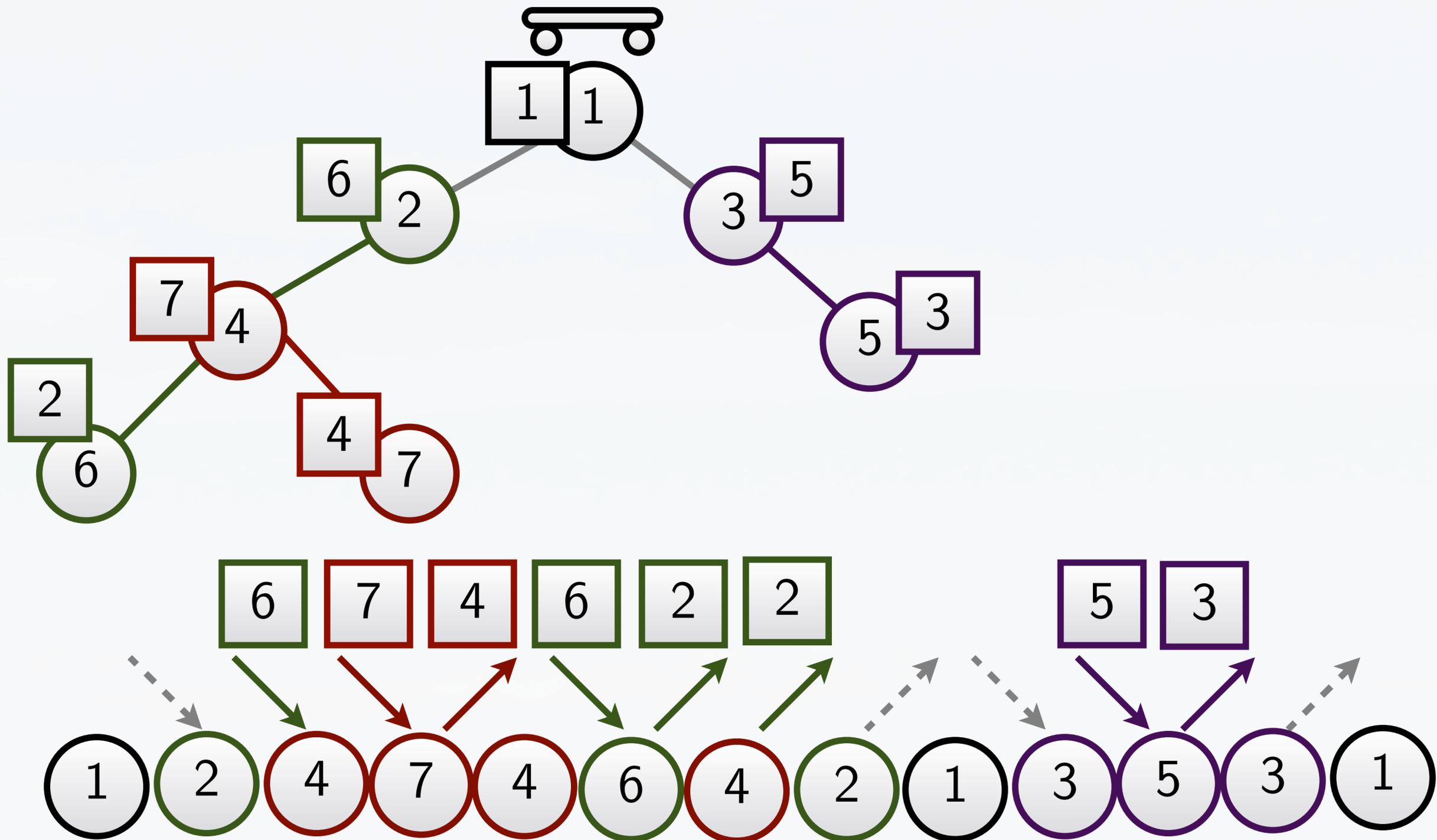


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How do we minimize the non-essential steps?

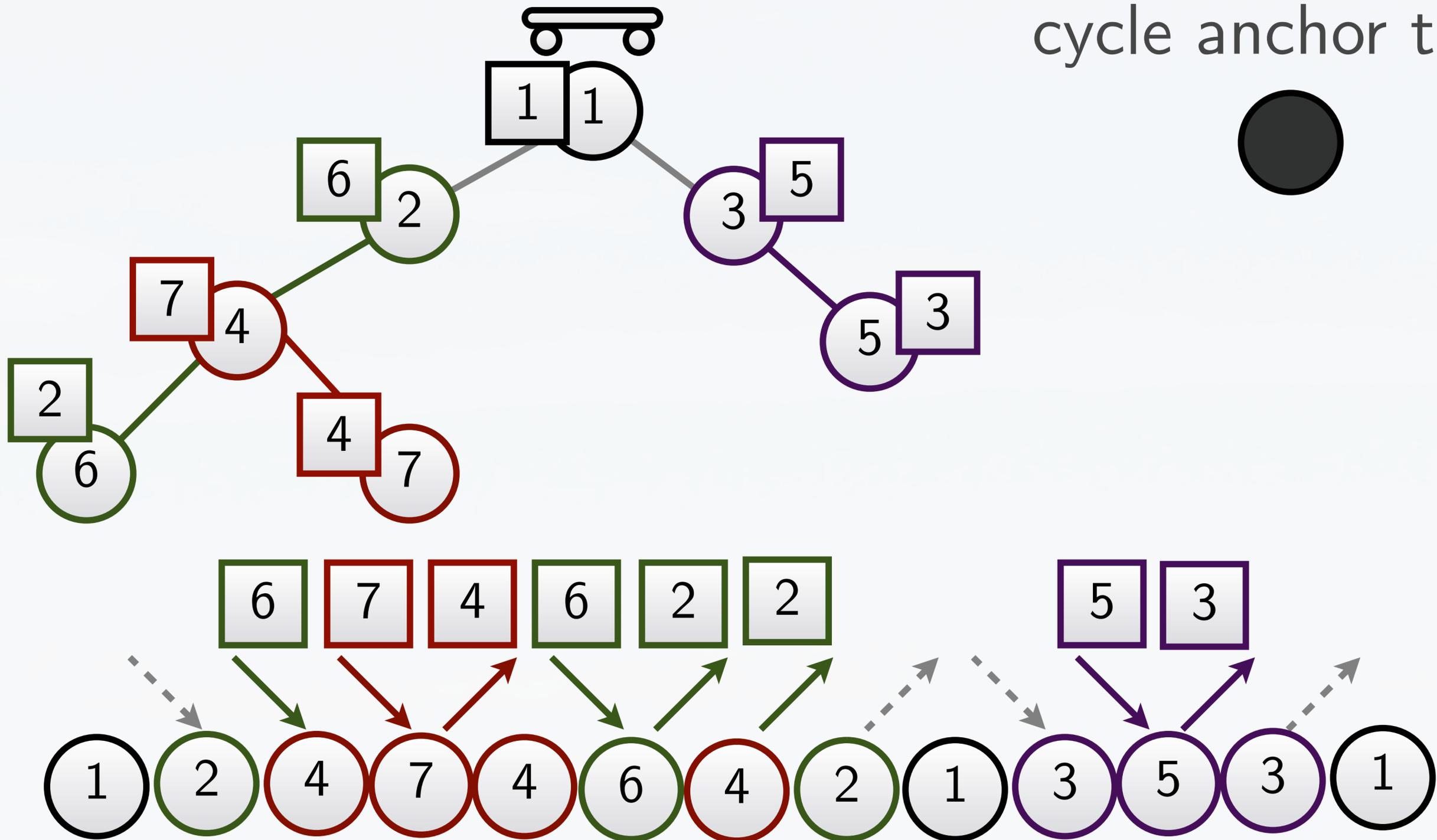


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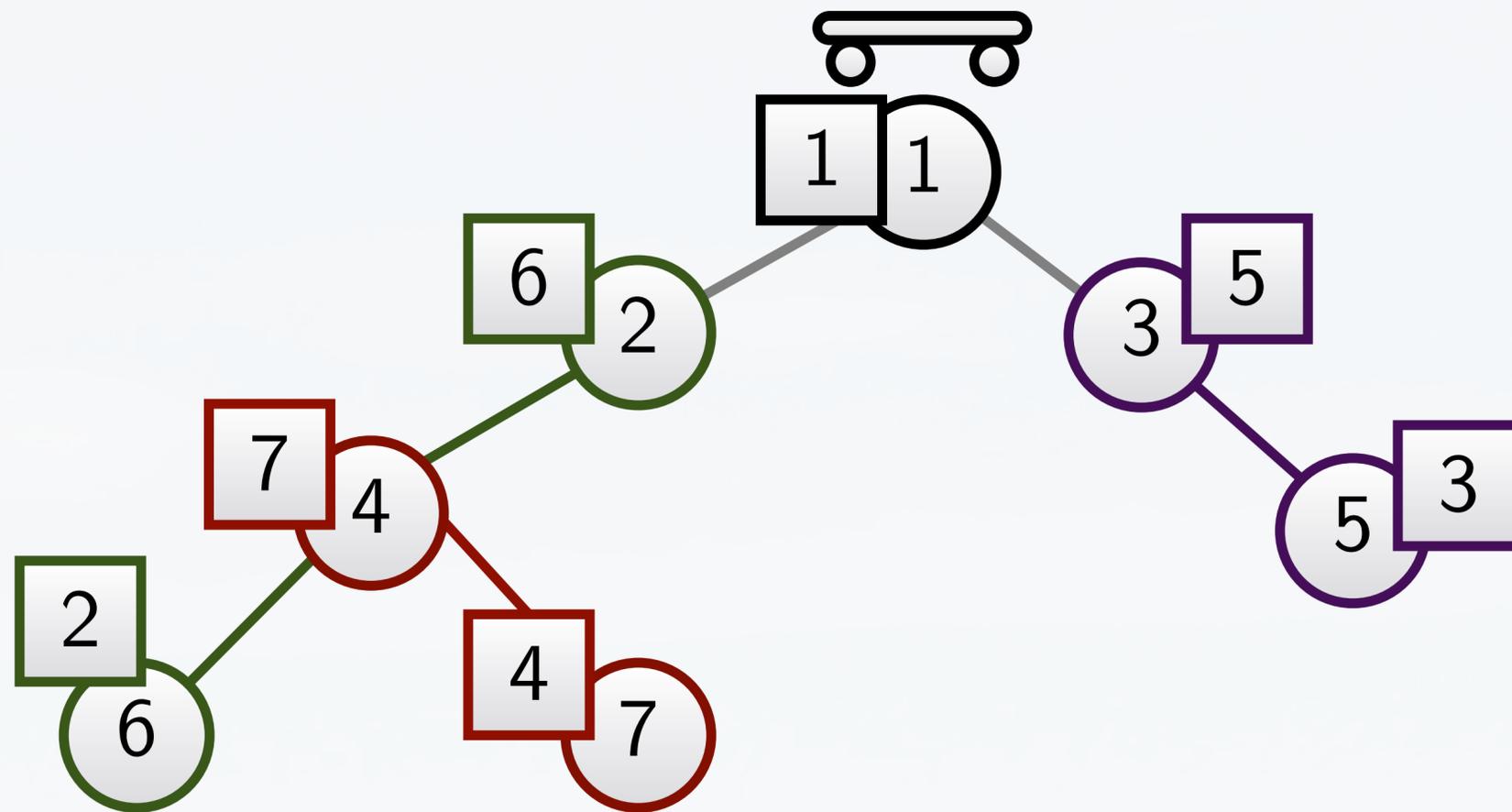


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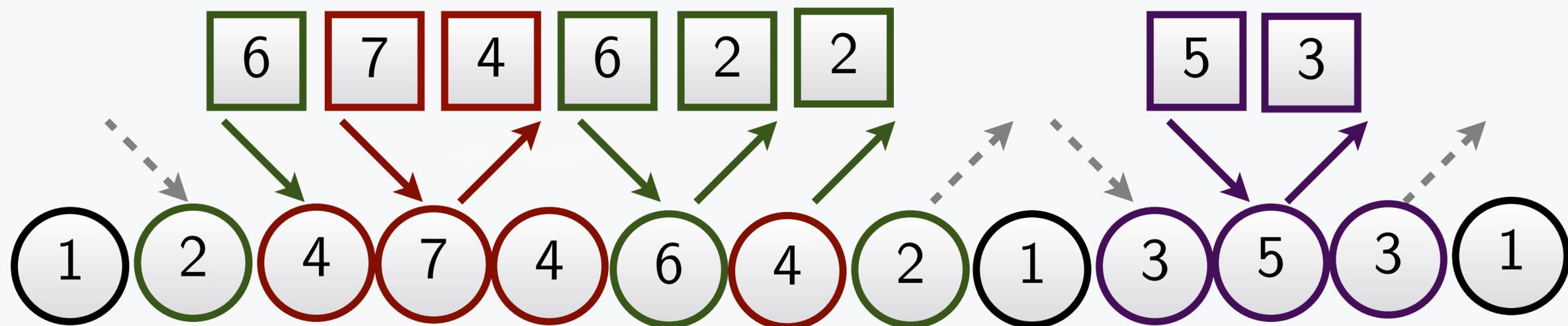
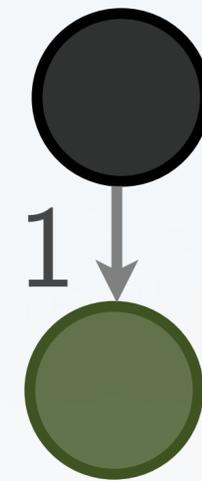
cycle anchor tree



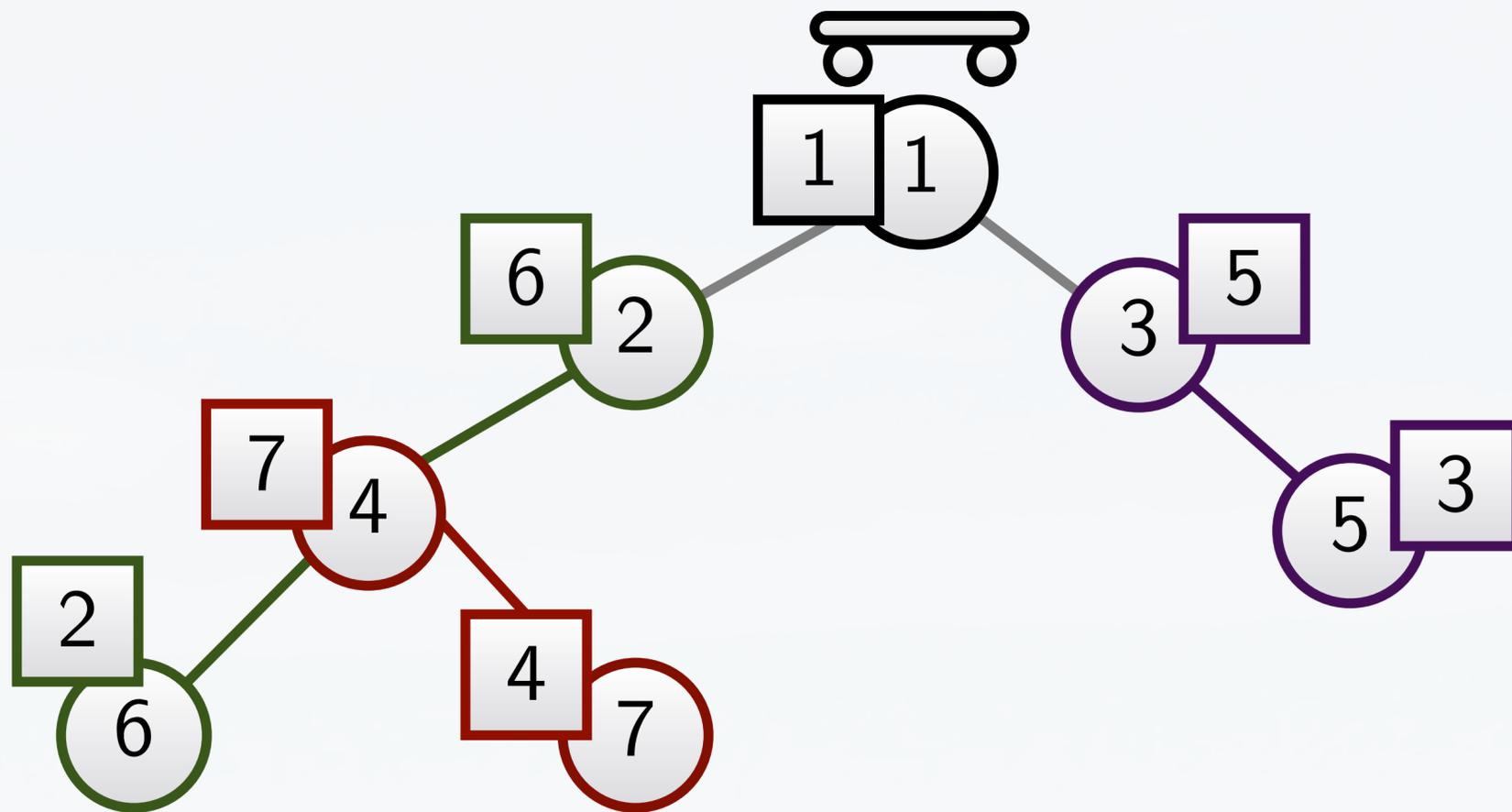
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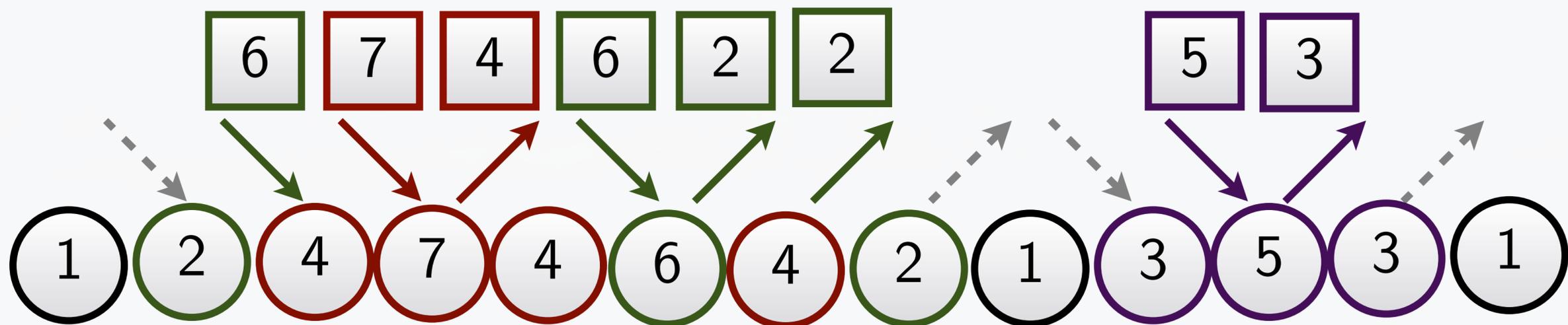
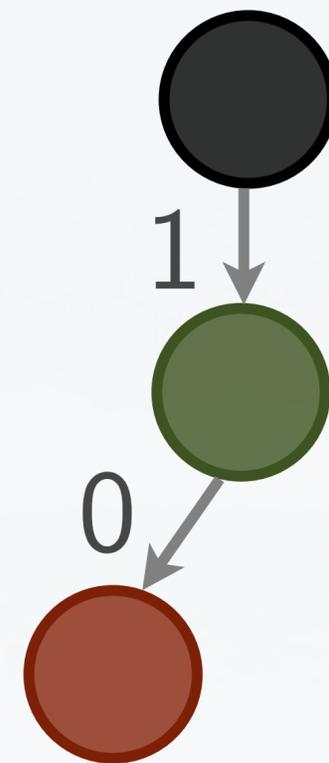
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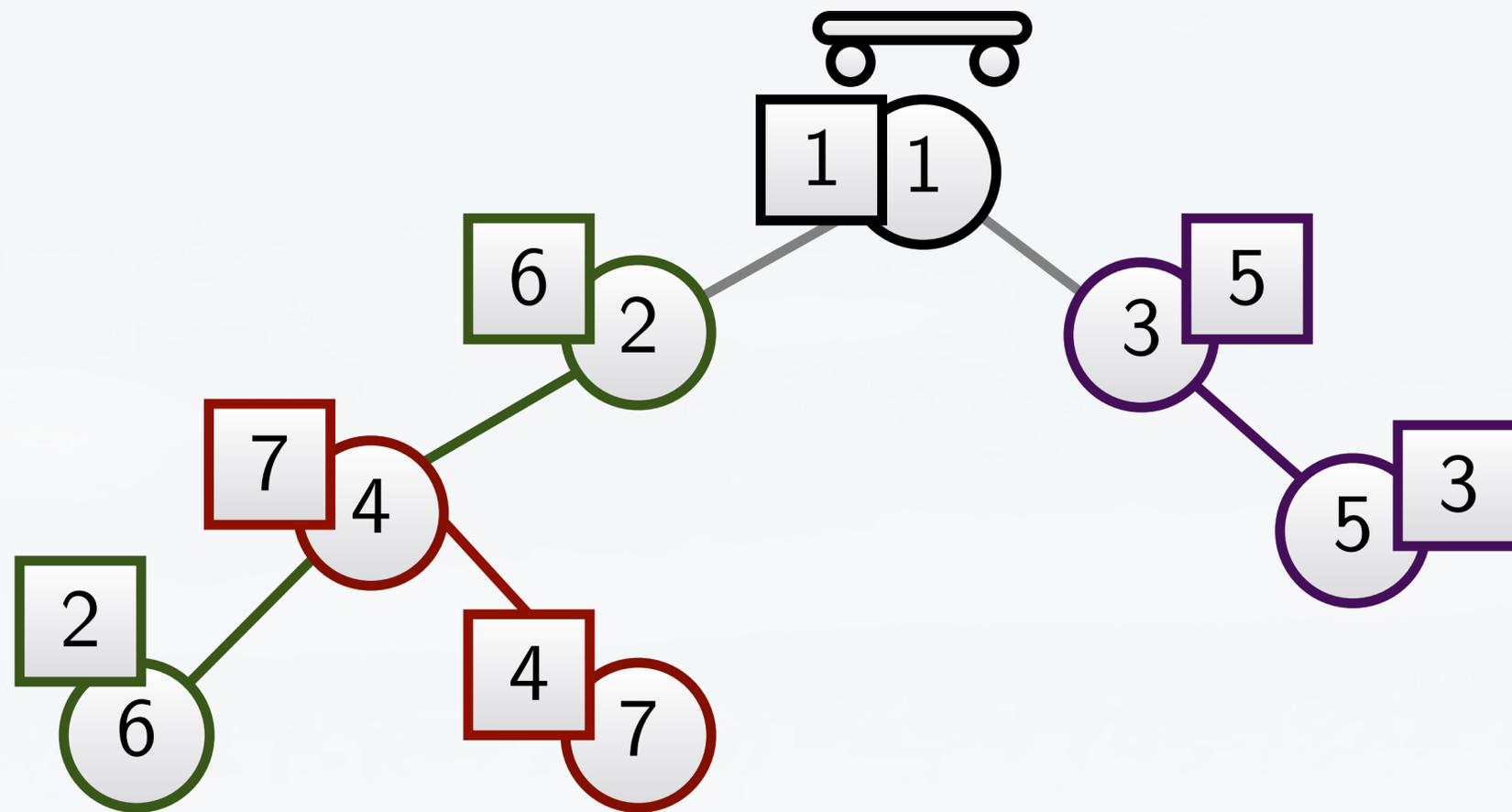
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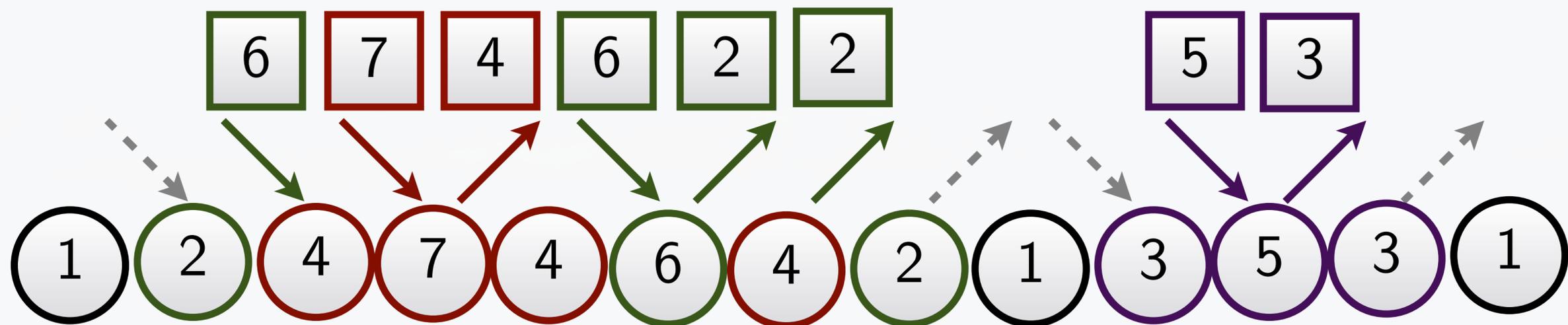
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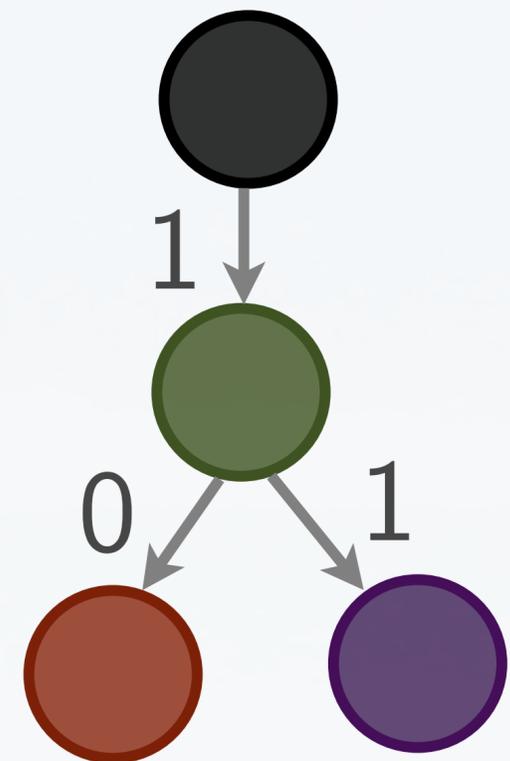
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How do we minimize the non-essential steps?

Edge cost $c((C_1, C_2)) =$
minimal number of down
steps from any vertex
covered by C_1 to a vertex
containing a box of C_2

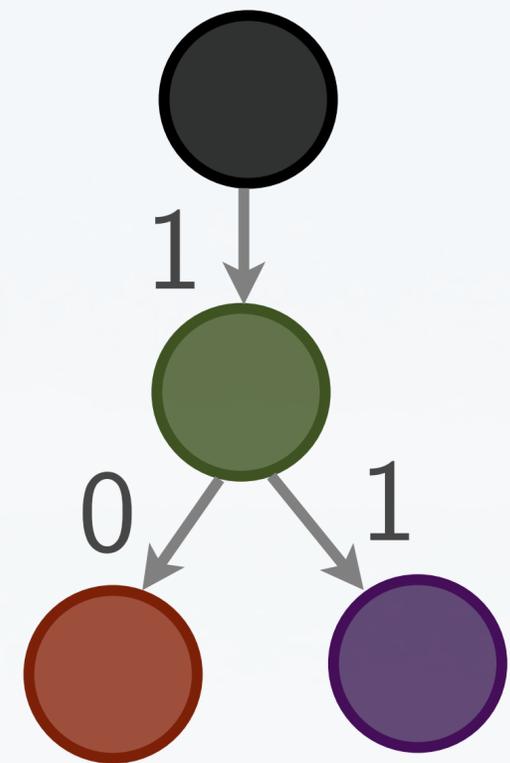
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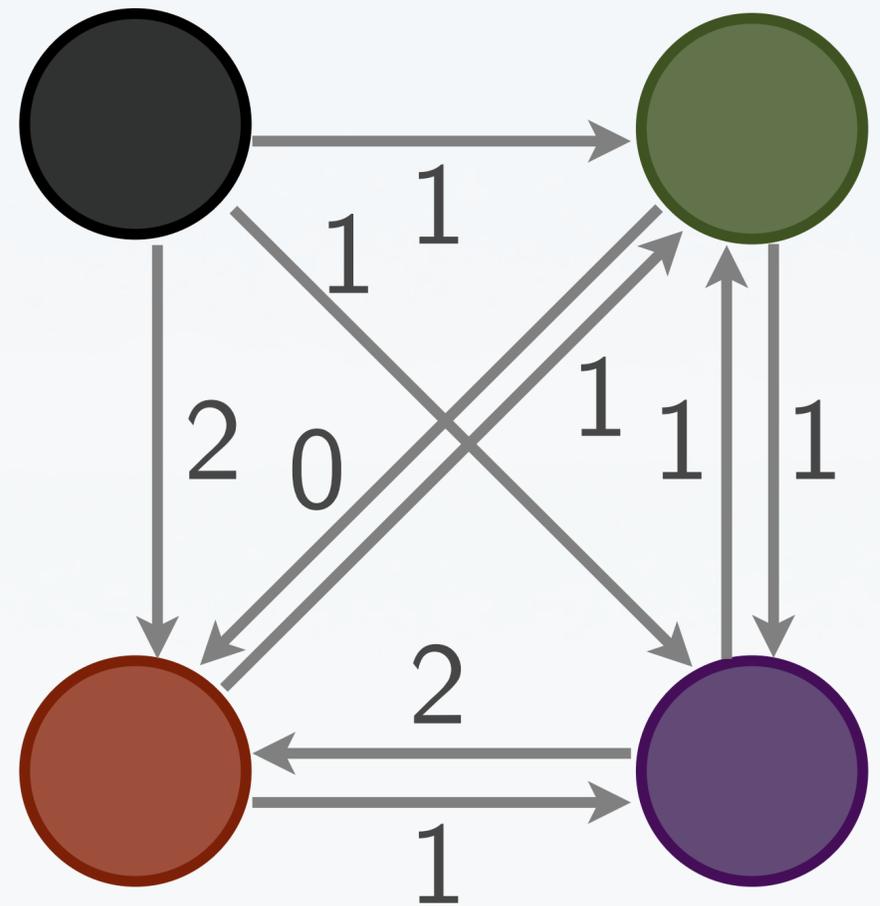
cycle anchor tree



Observation: A cycle anchor tree determines the length of all corresponding sorting walks.

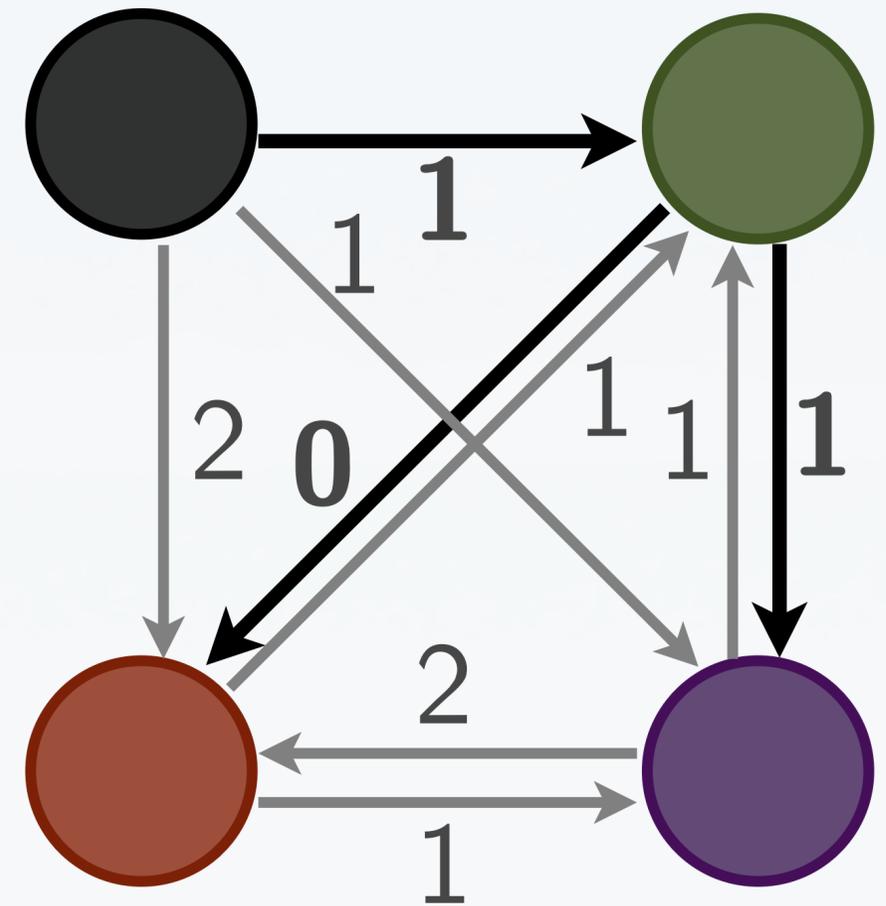
How do we find the cheapest cycle anchor tree?

- Start with the complete directed graph on all cycles.
- Find a cheapest direct subgraph rooted at ● using Edmond's algorithm for optimum branchings.



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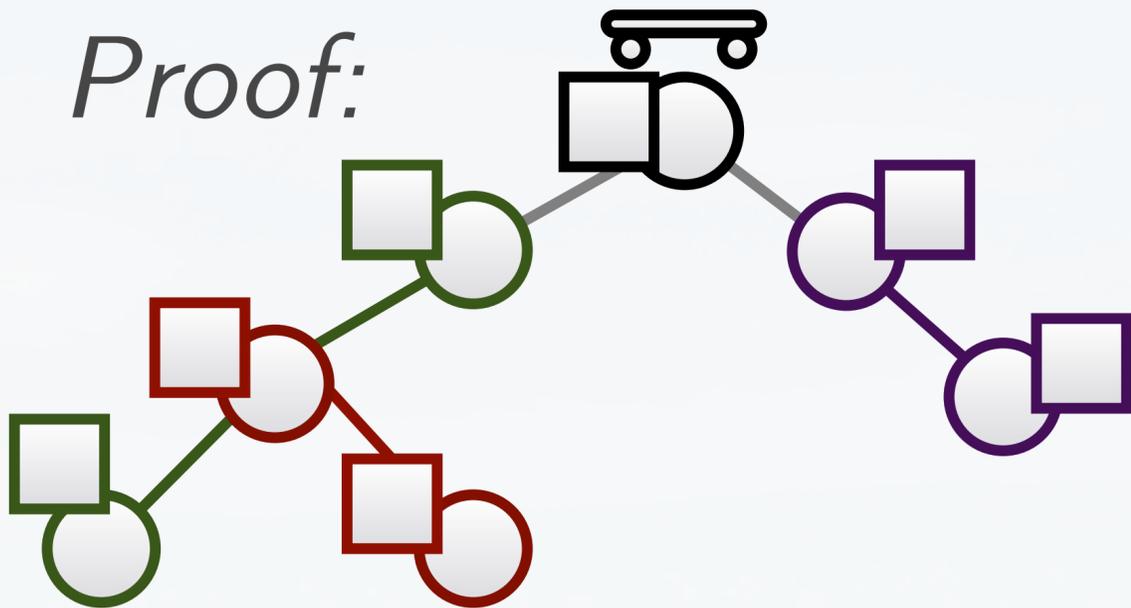
- Start with the complete directed graph on all cycles.
- Find a cheapest direct subgraph rooted at  using Edmond's algorithm for optimum branchings.



Theorem: The shortest sorting path on a tree T can be found in time $\mathcal{O}(n^2)$.

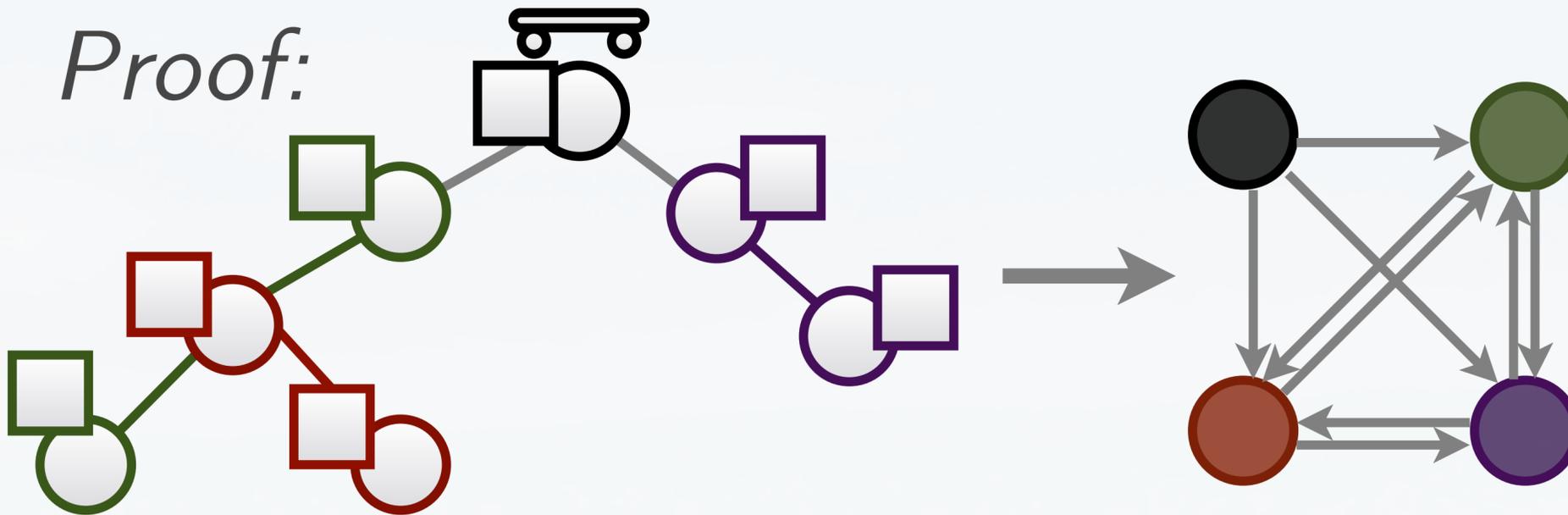
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Proof:



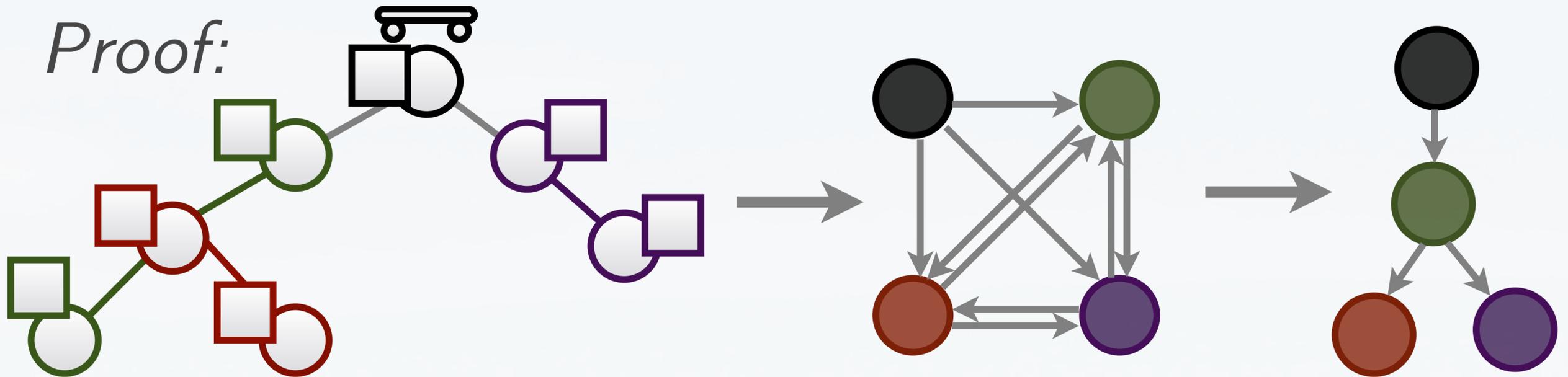
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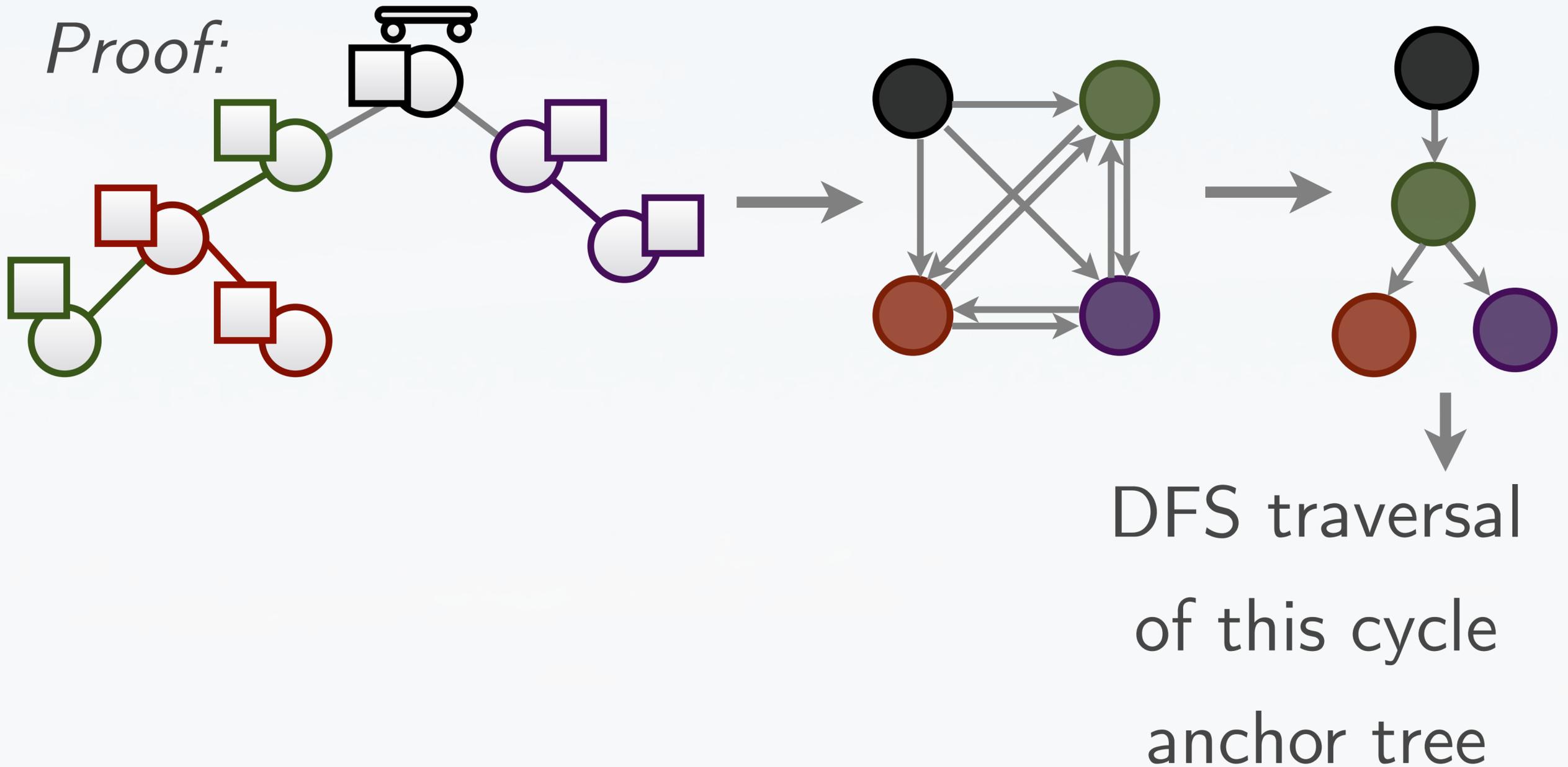
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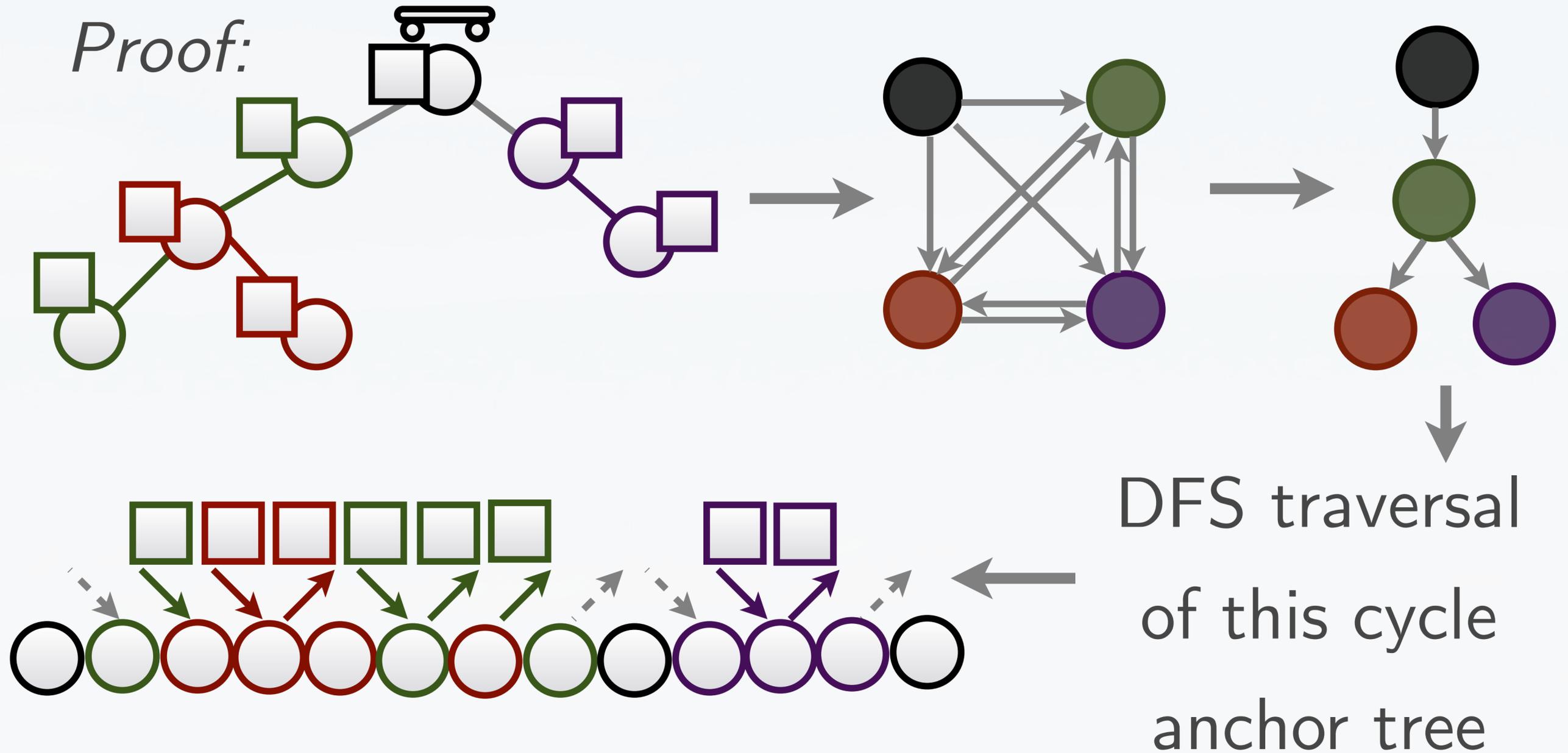
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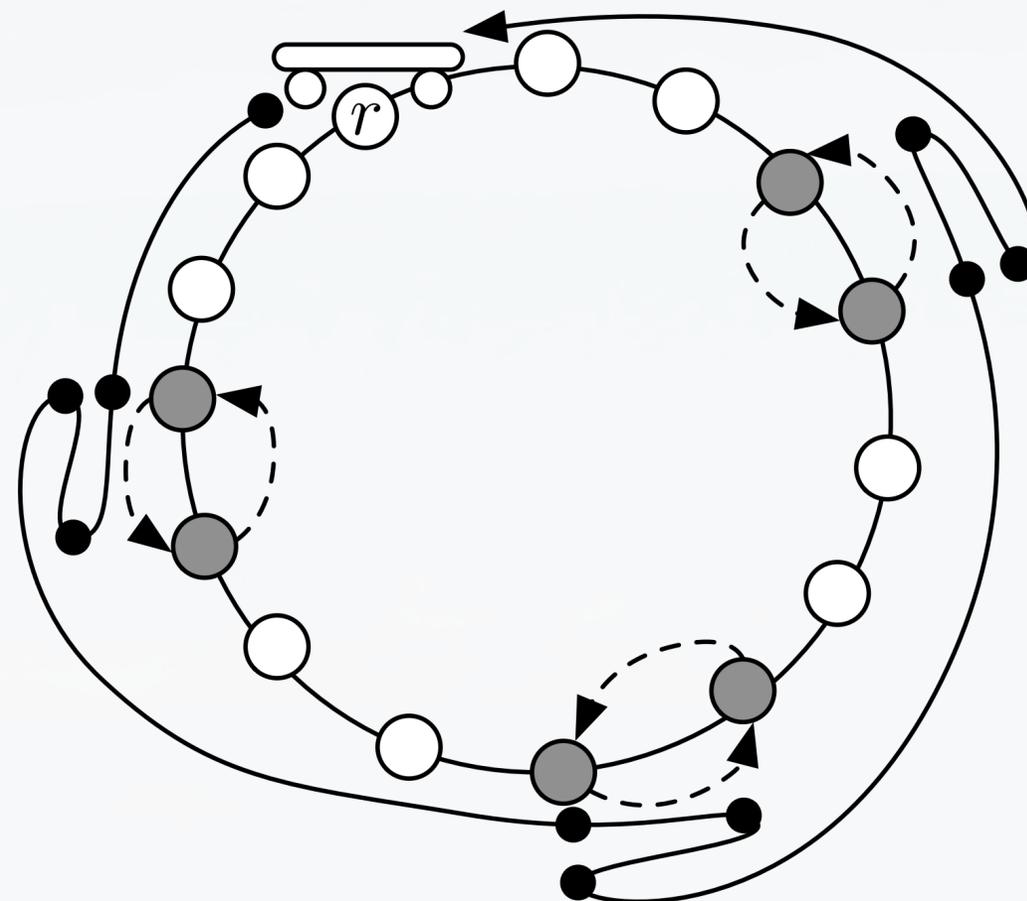
Proof:



Theorem: The shortest sorting path on a circle C can be found in time $\mathcal{O}(n^3)$.

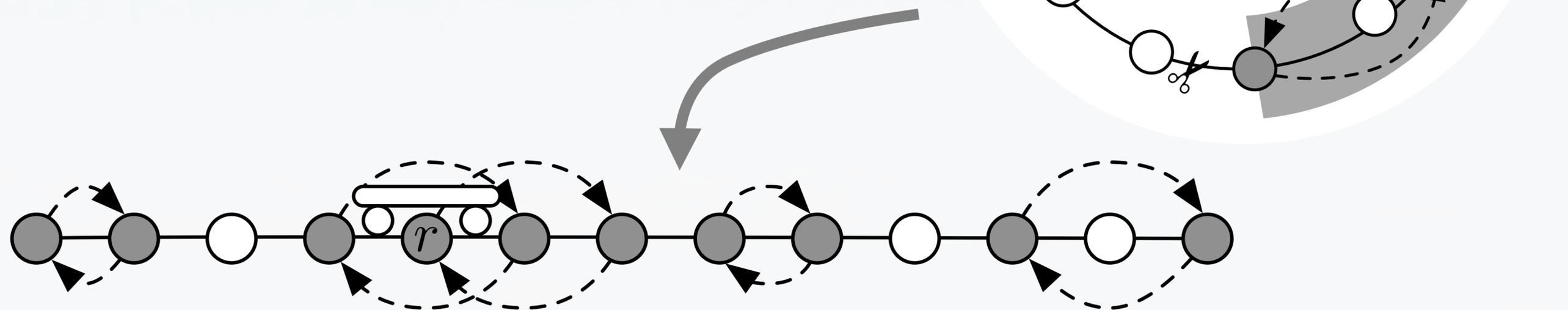
Theorem: The shortest sorting path on a circle C can be found in time $\mathcal{O}(n^3)$.

Proof Ideas: Full circle might be necessary.



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Proof Ideas: Reduce it to sorting on a path.



What if we look at more general graphs and allow multiple cycles?

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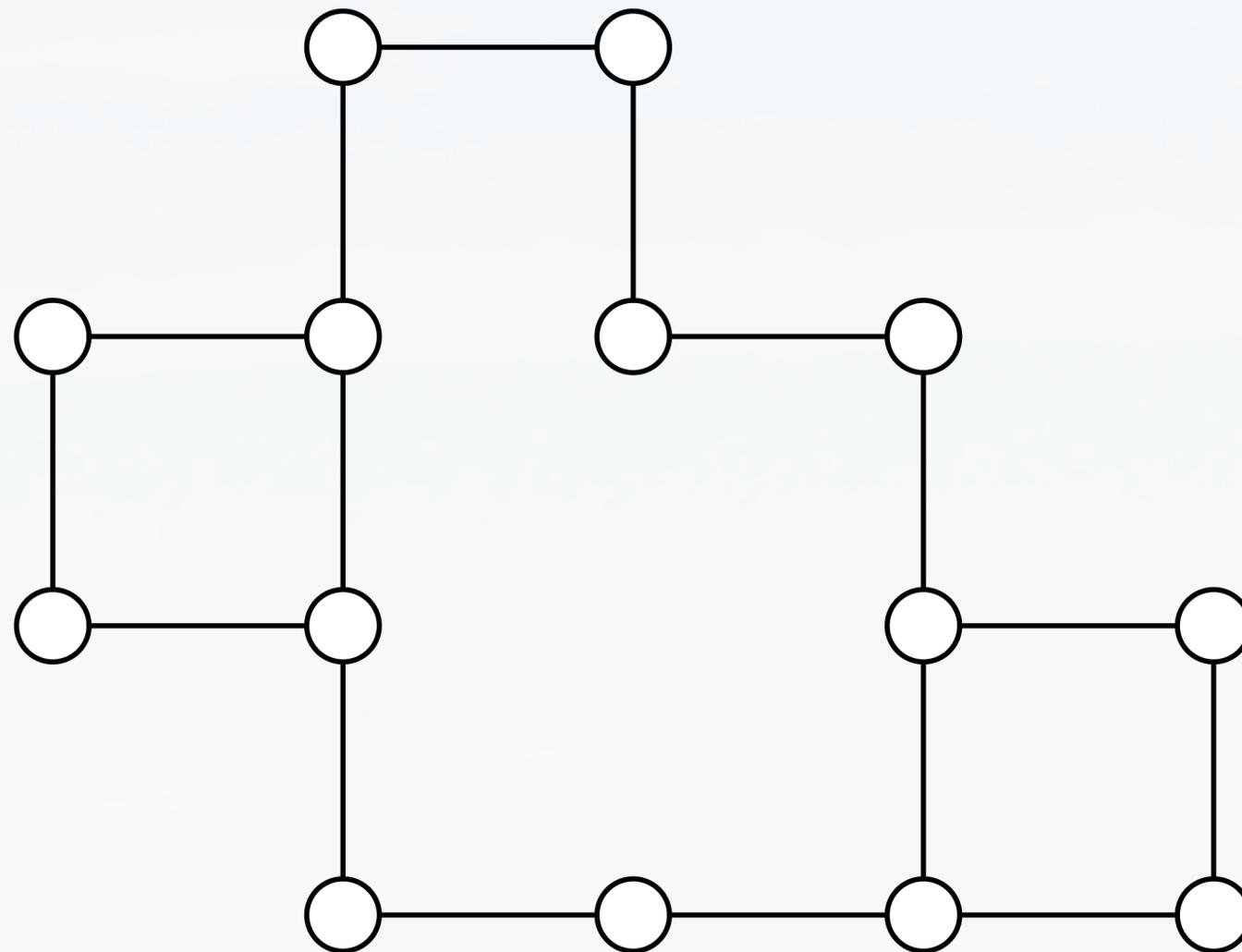
Theorem: Finding a shortest sorting walk is *NP*-complete for planar graphs.

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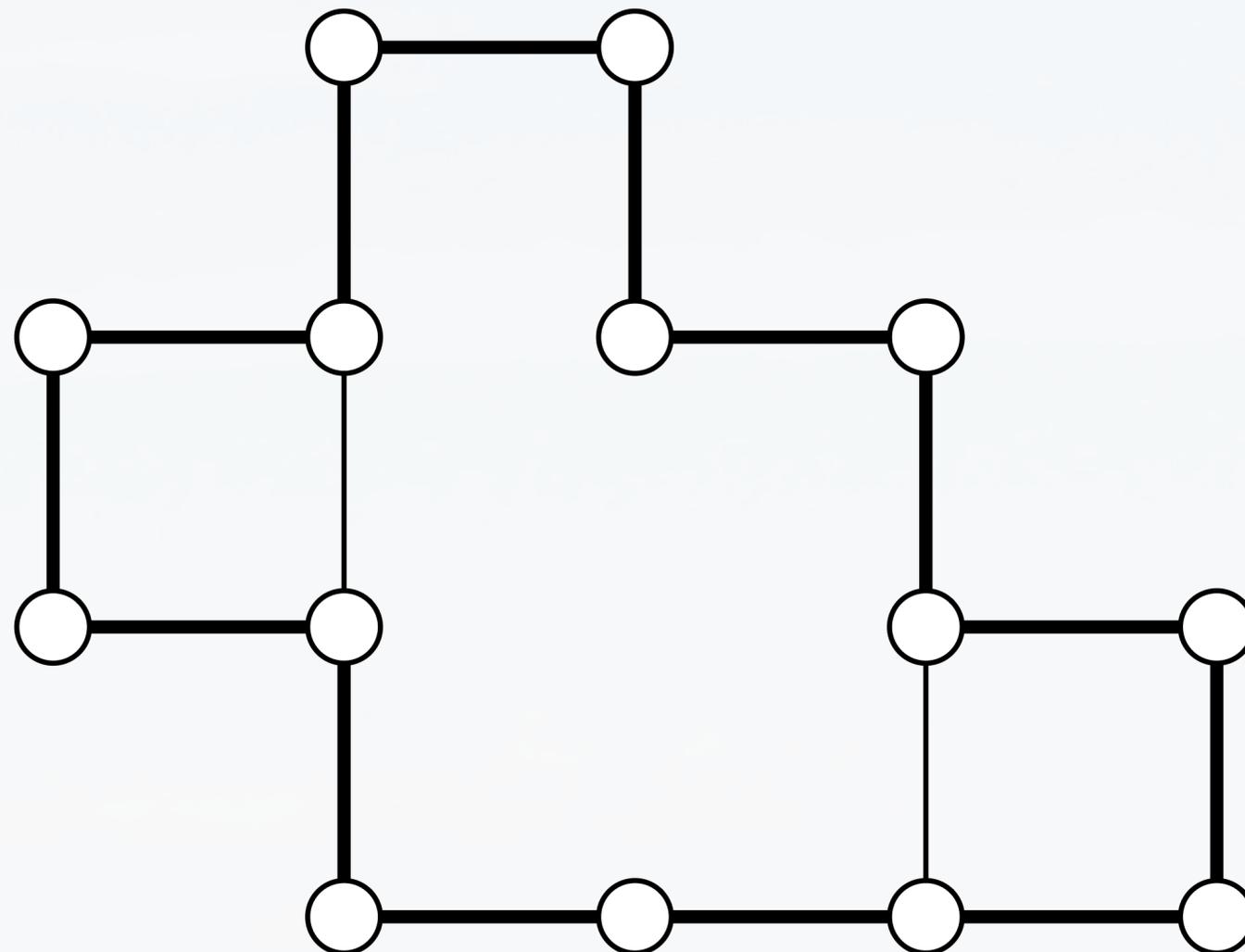
Theorem: Finding a shortest sorting walk is *NP*-complete for planar graphs.

Proof: Reduction from the problem of finding Hamiltonian circuits for grid graphs.

Theorem [Itai et al. 1981]: Finding Hamiltonian circuits for grid graphs is *NP*-complete.

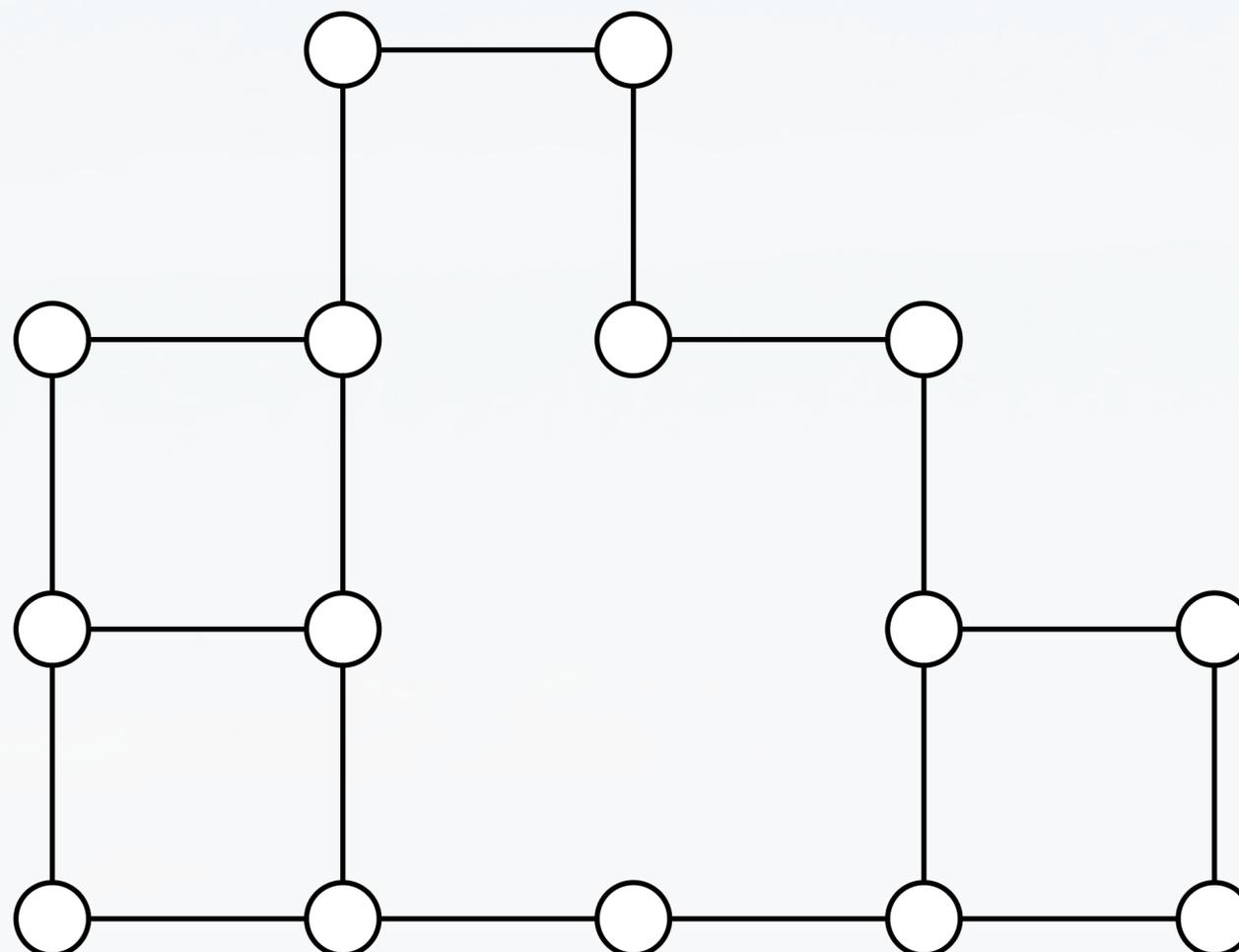


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Box handling takes significant time in practice.

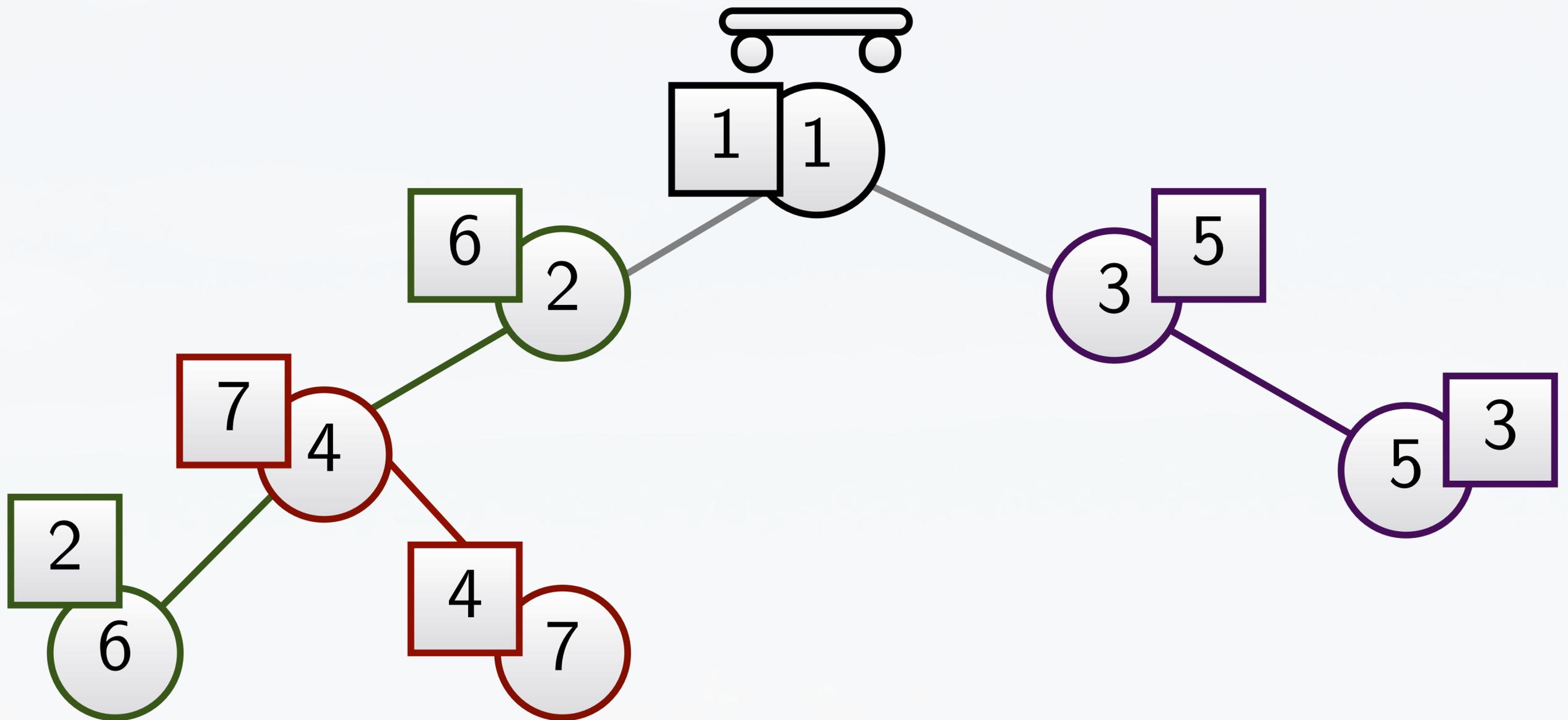
Different cost function:

- count number of swaps
- minimizing number of steps as a second priority

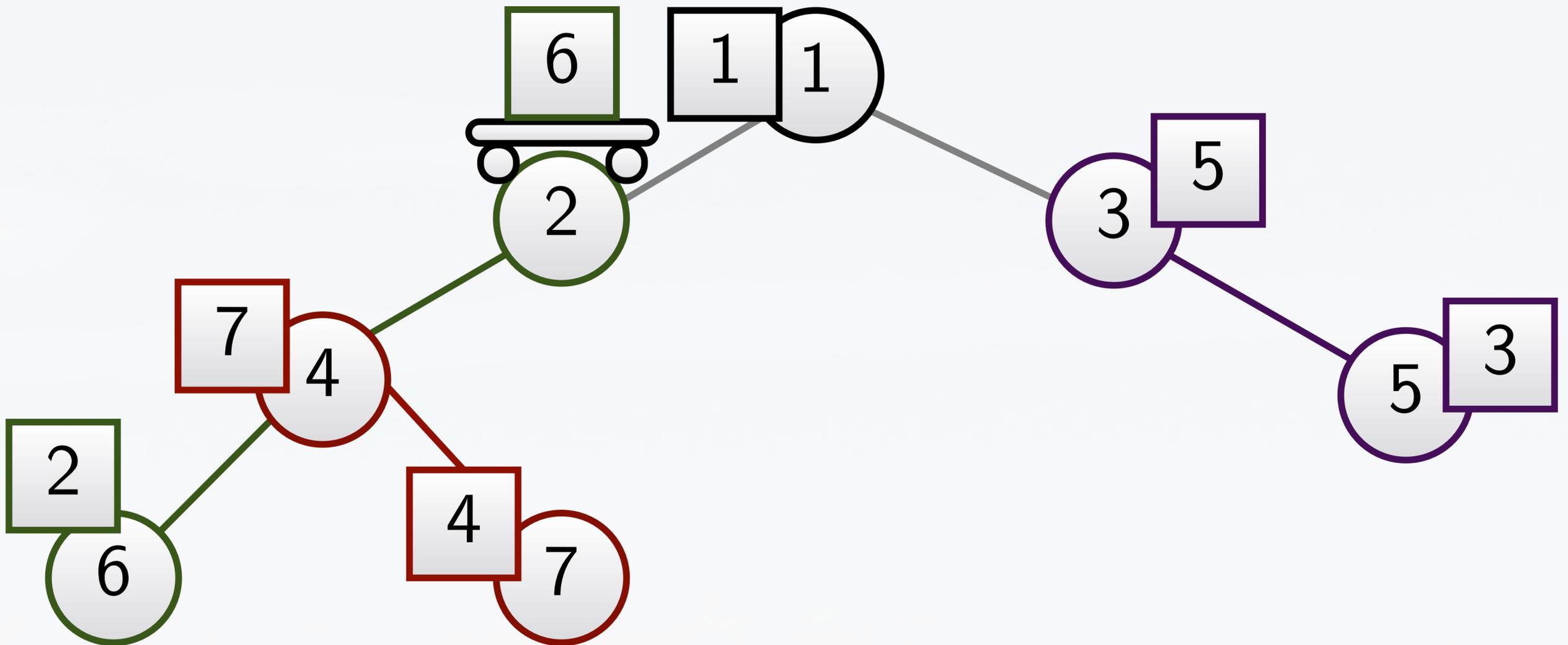
Observations:

- no interleaving of cycles anymore
- non-essential steps form a subtree containing r and a vertex of every cycle of π .

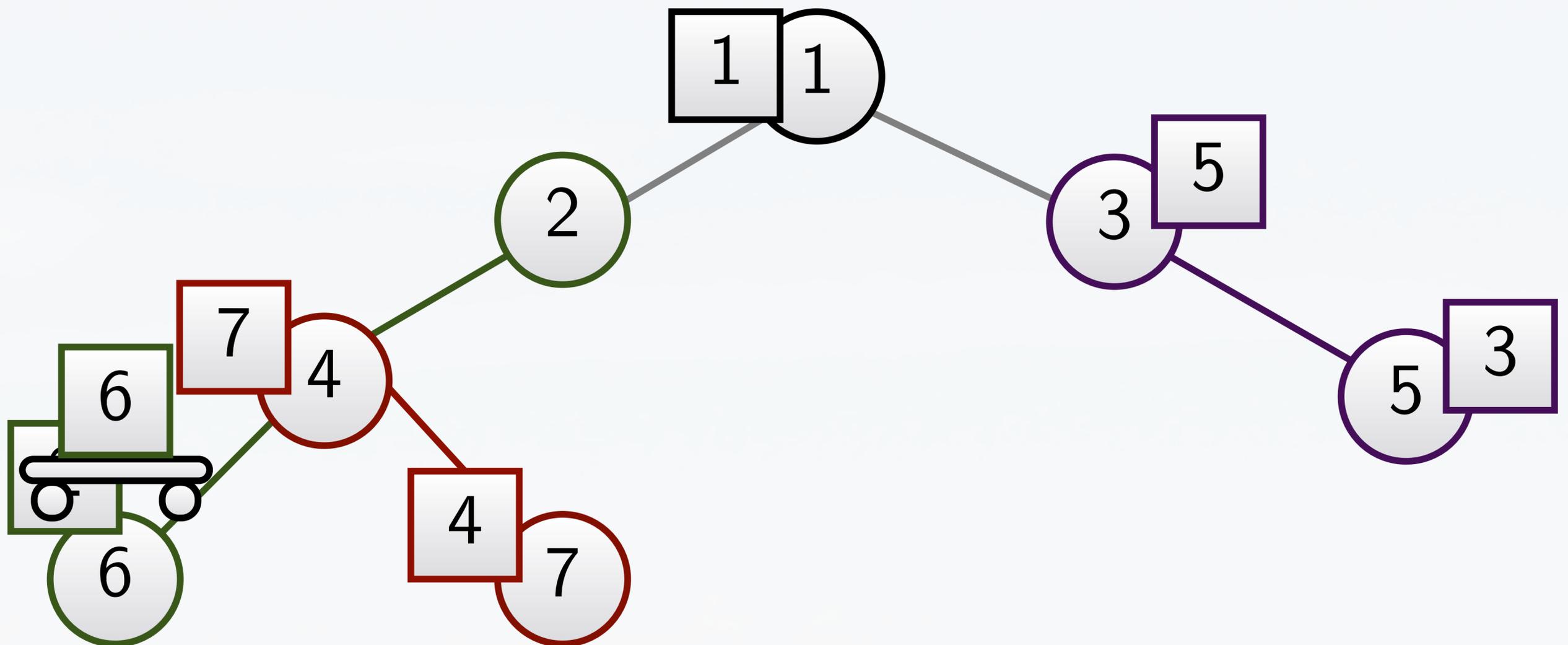
Fewest Swaps



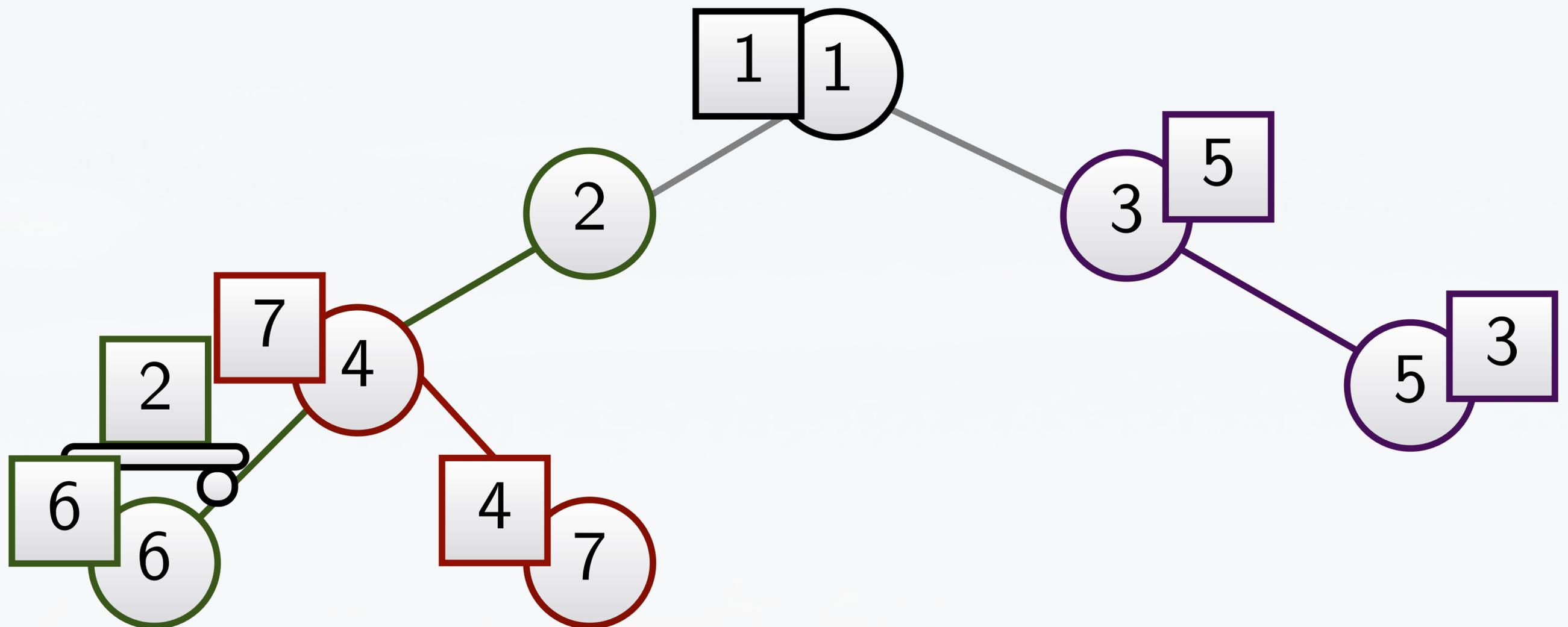
Fewest Swaps



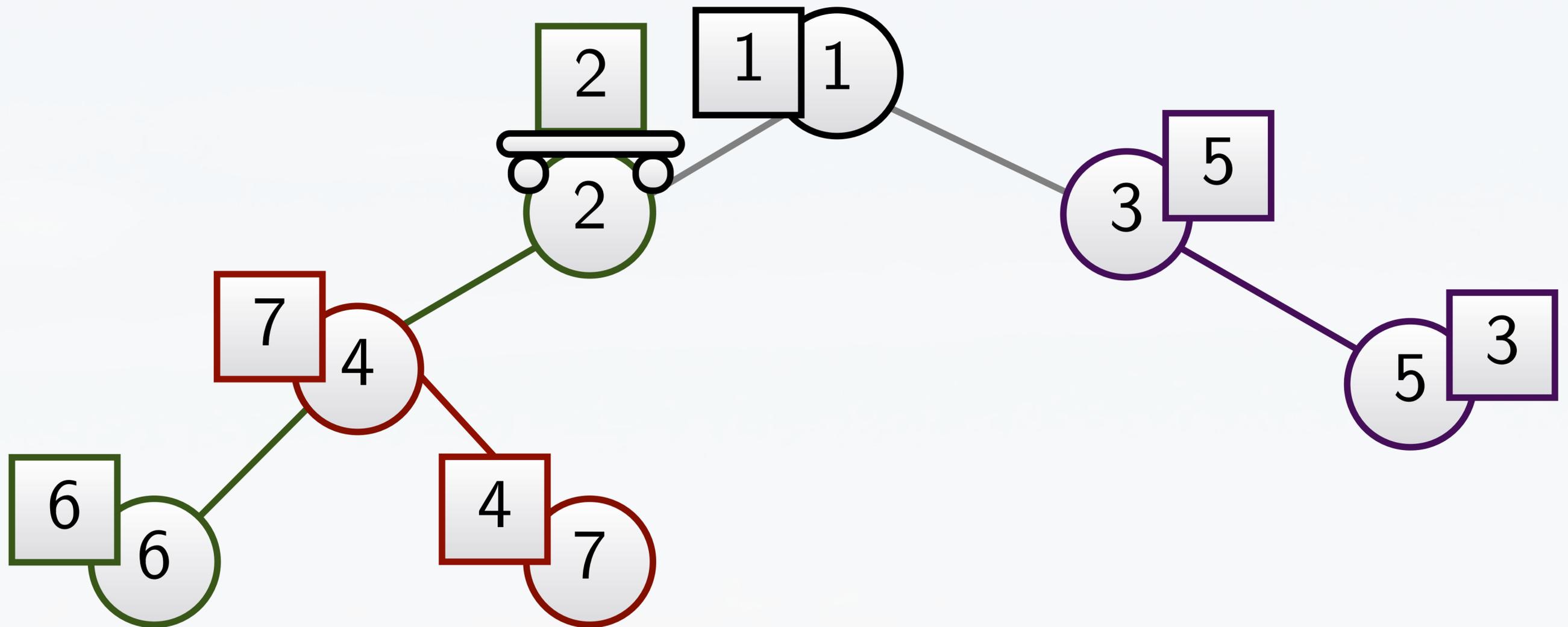
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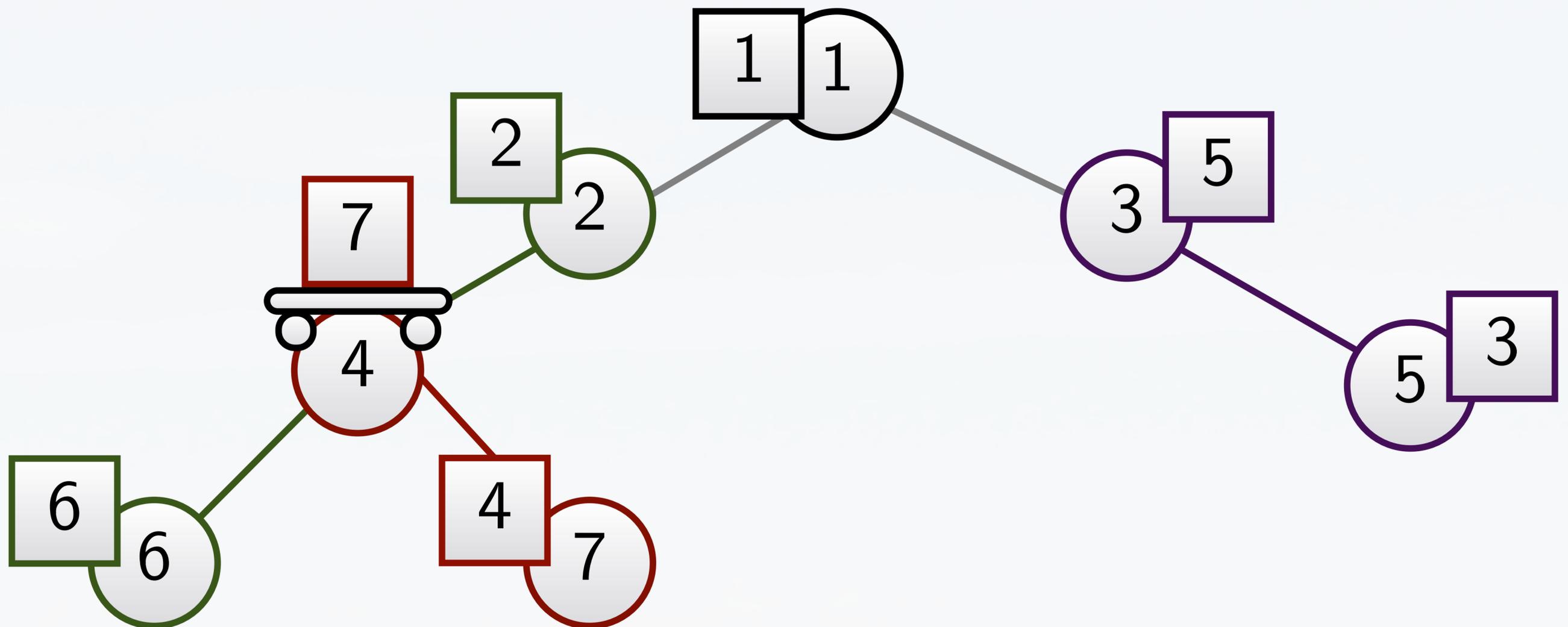
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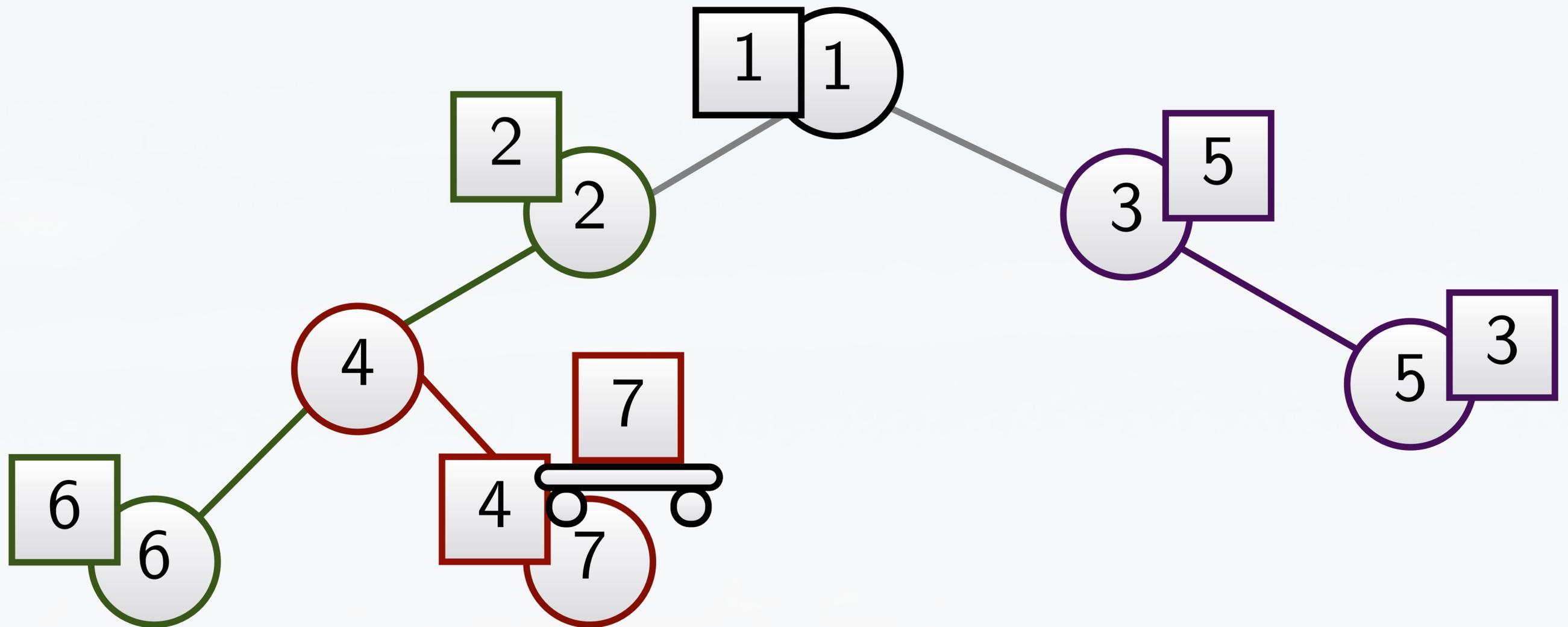
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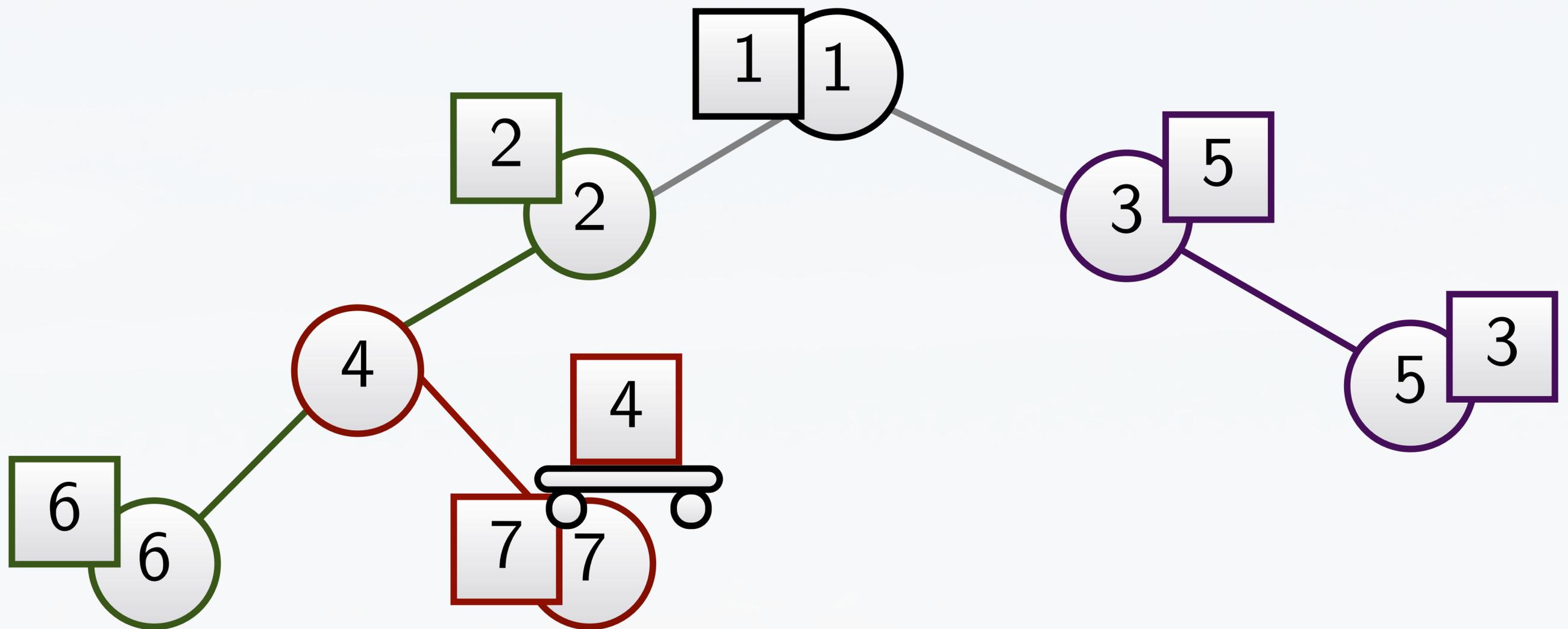
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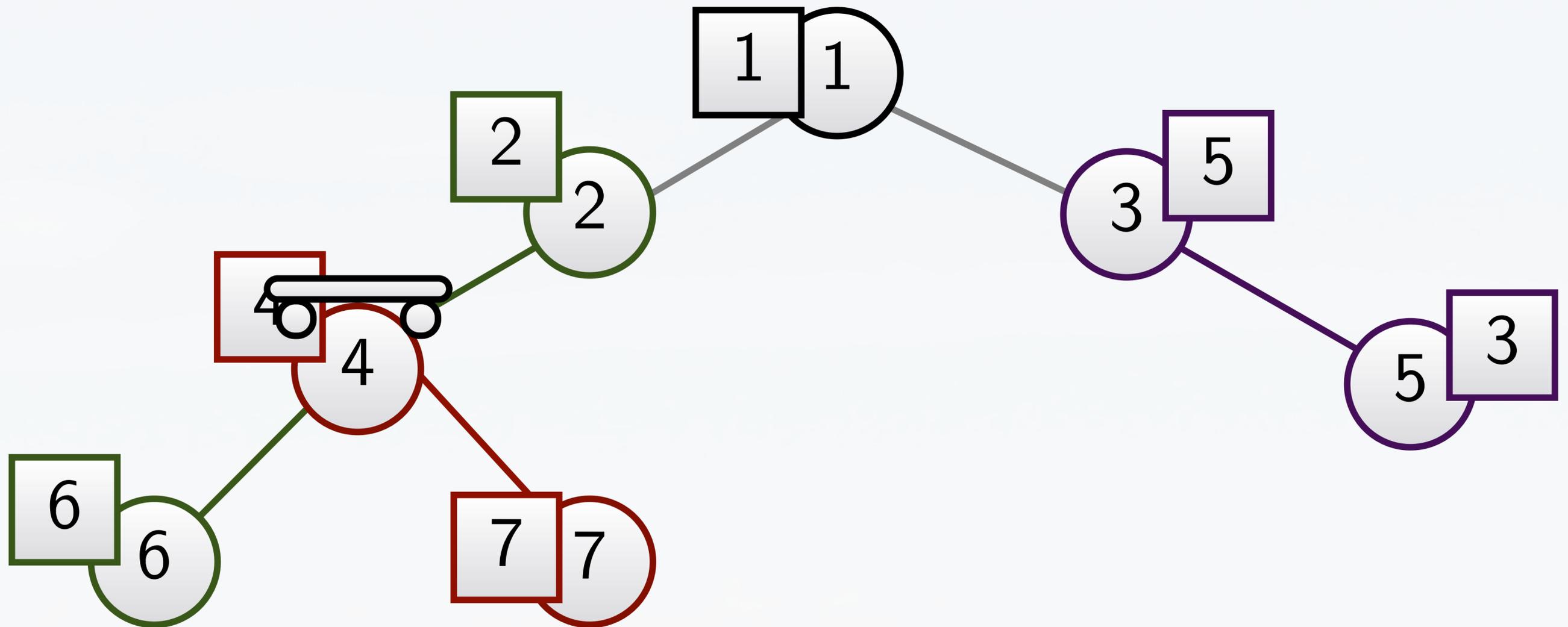
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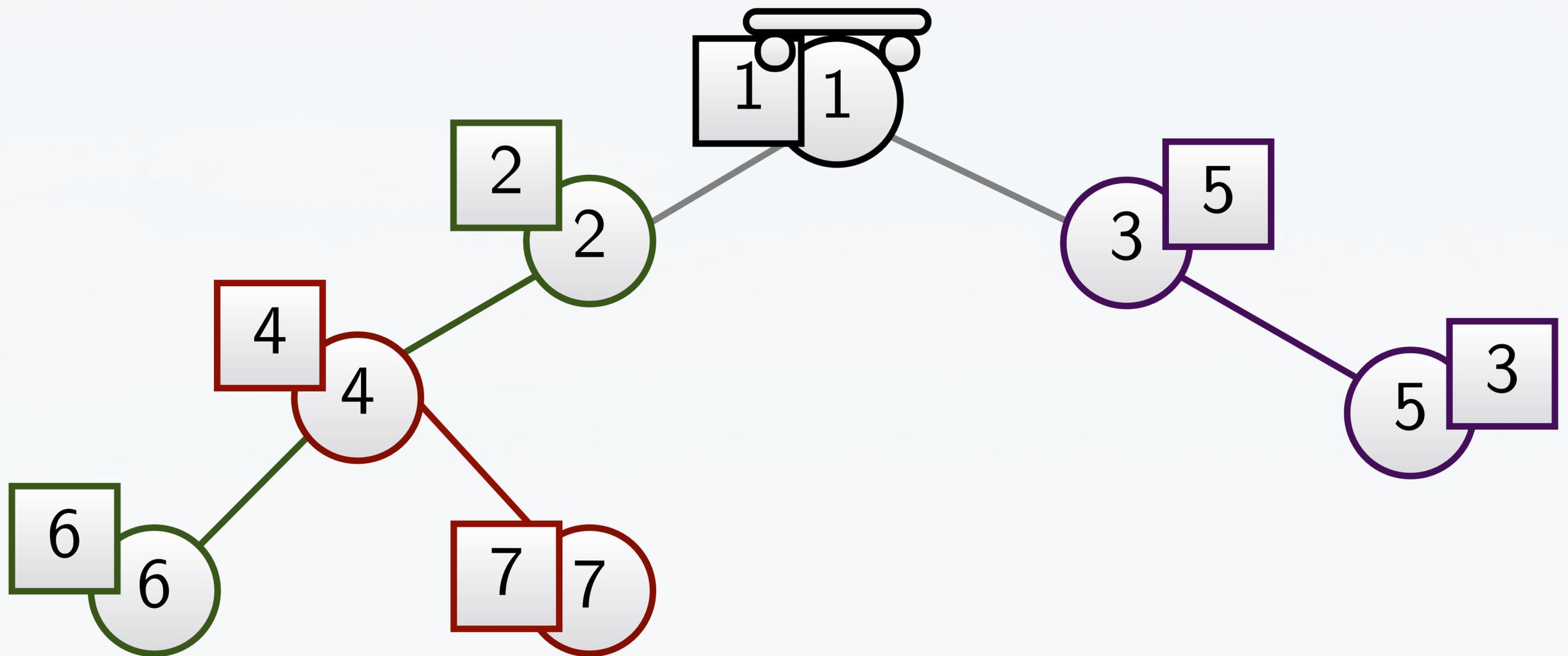


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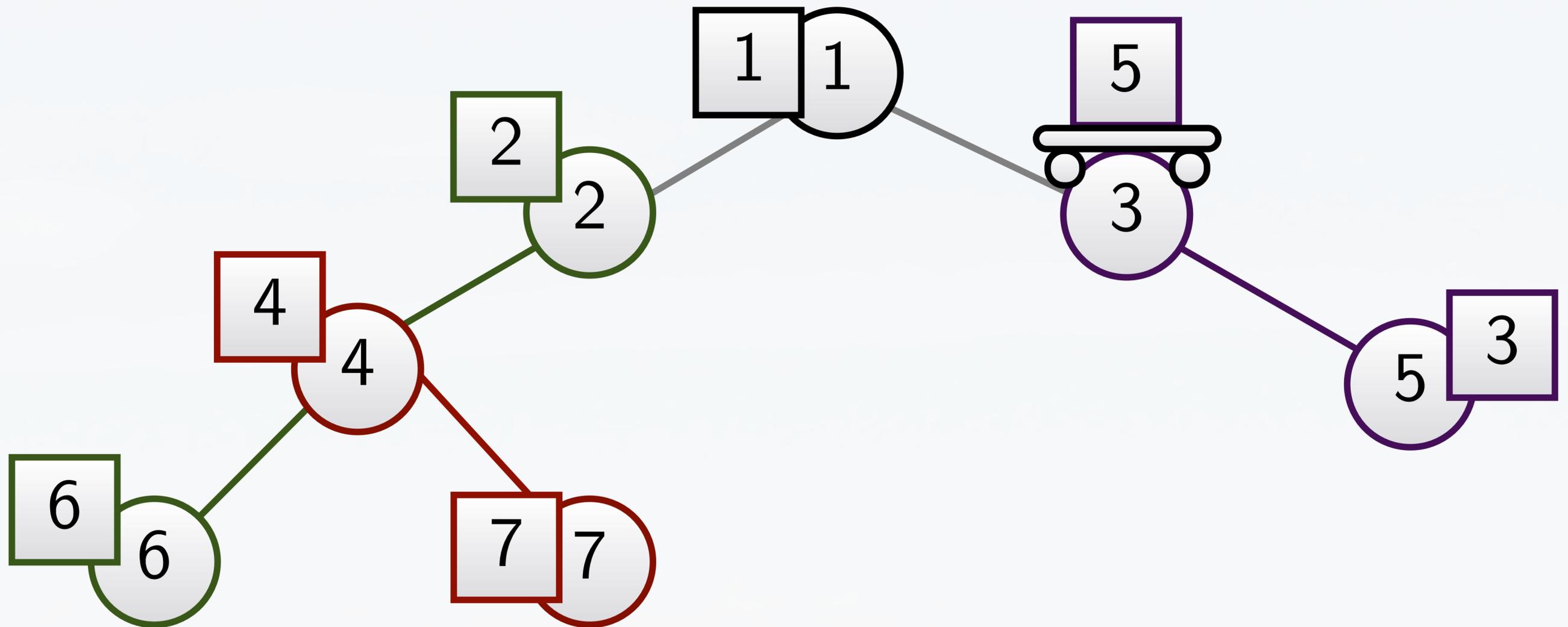


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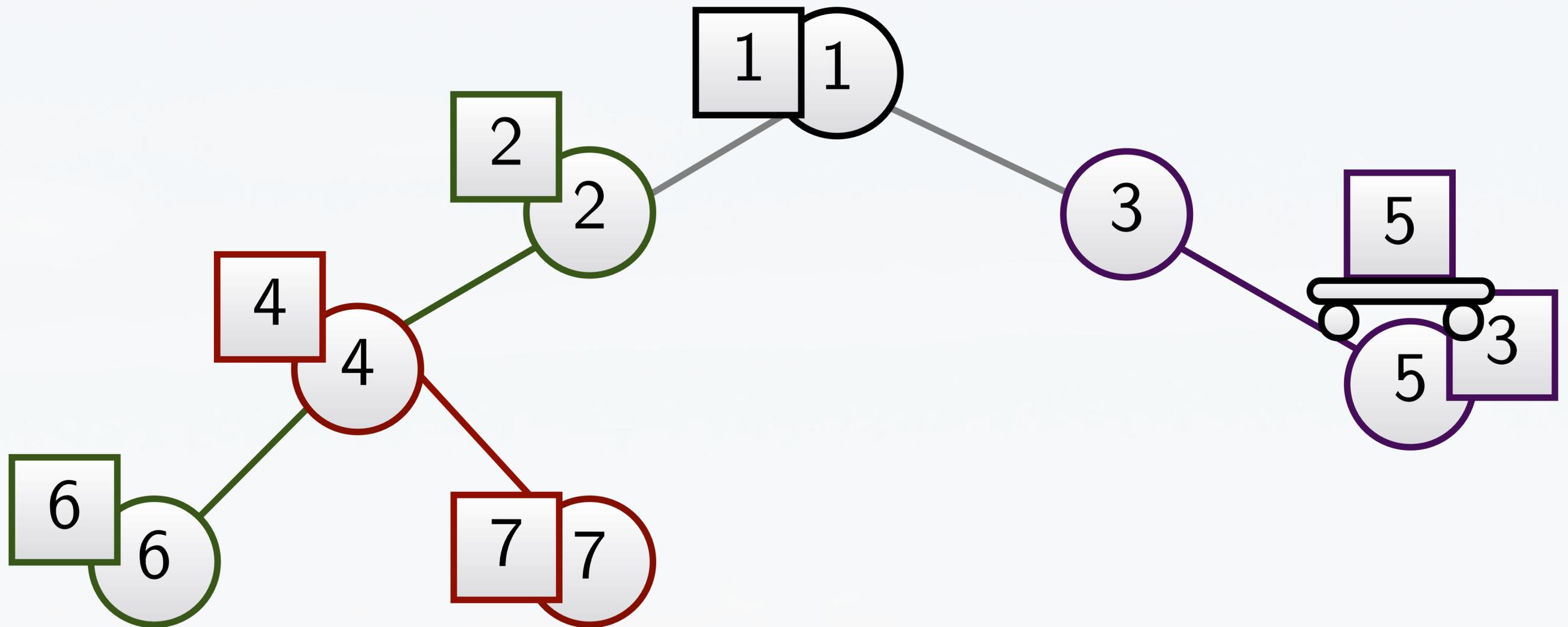




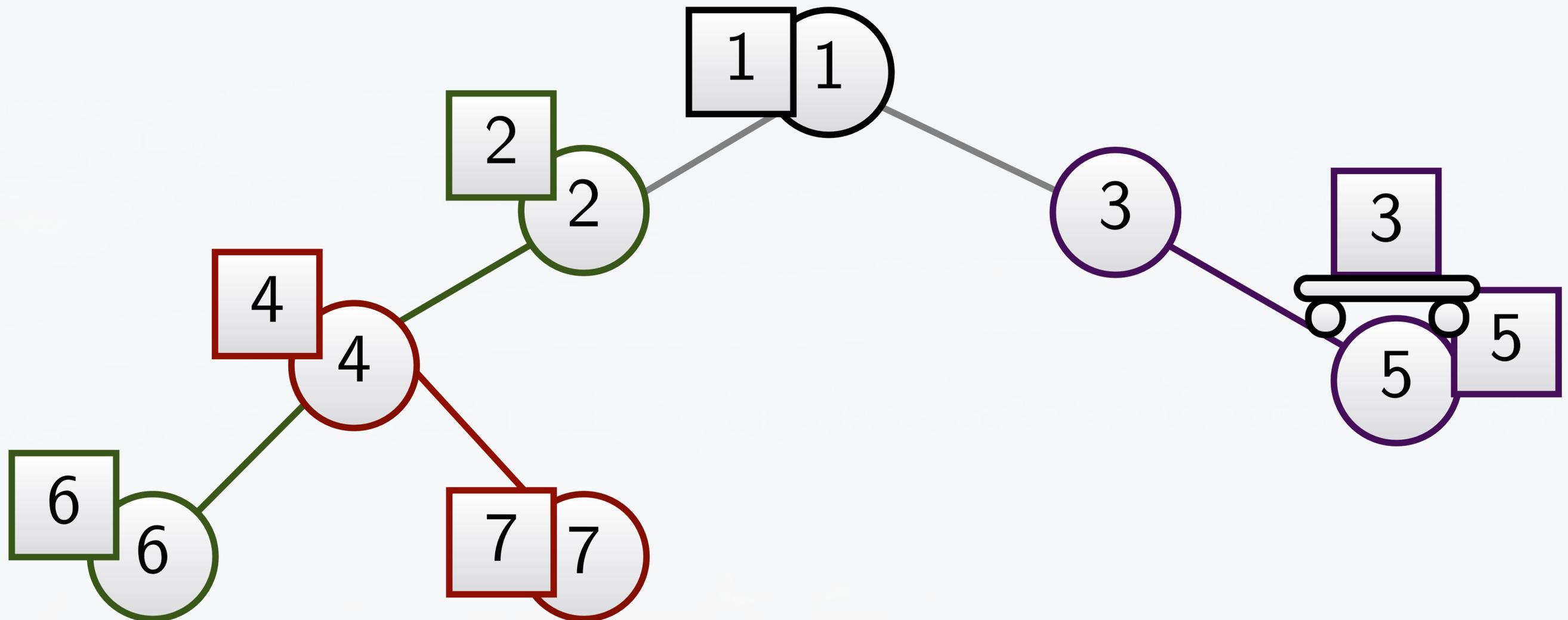
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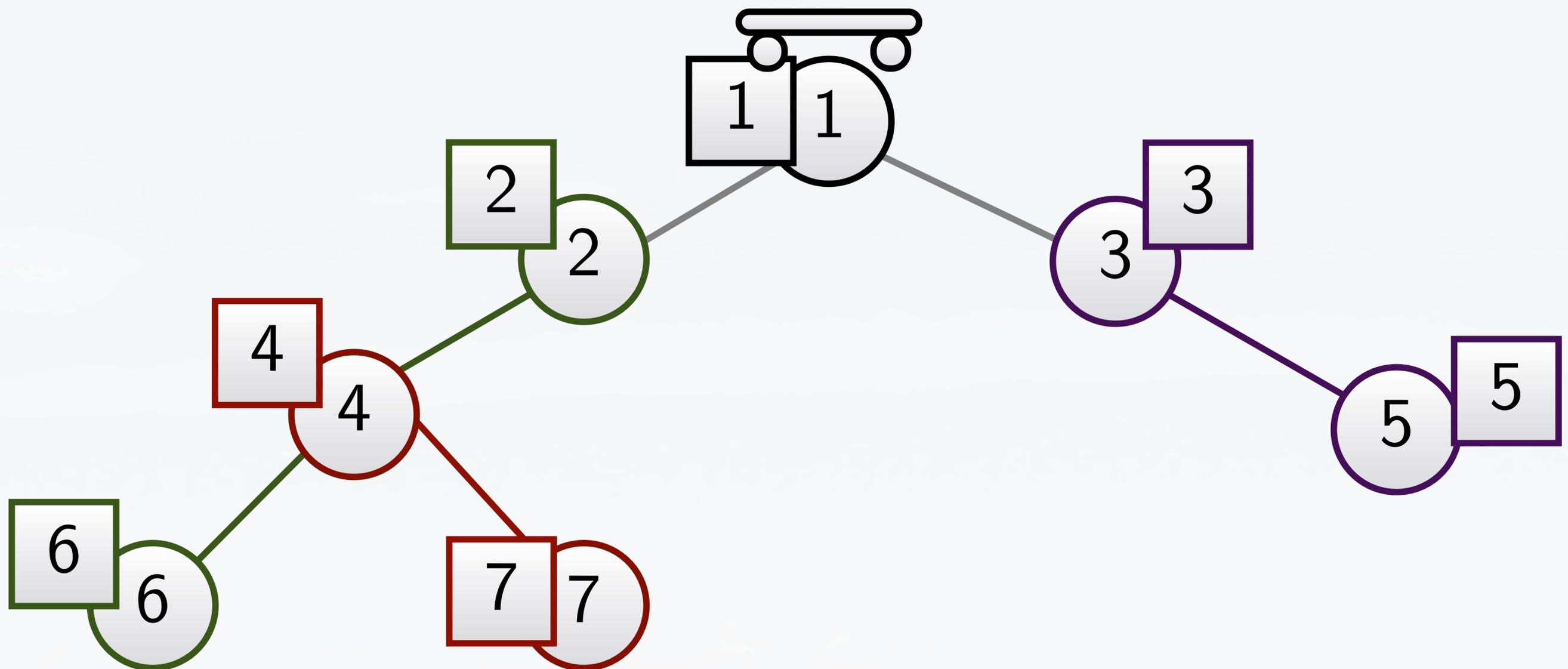


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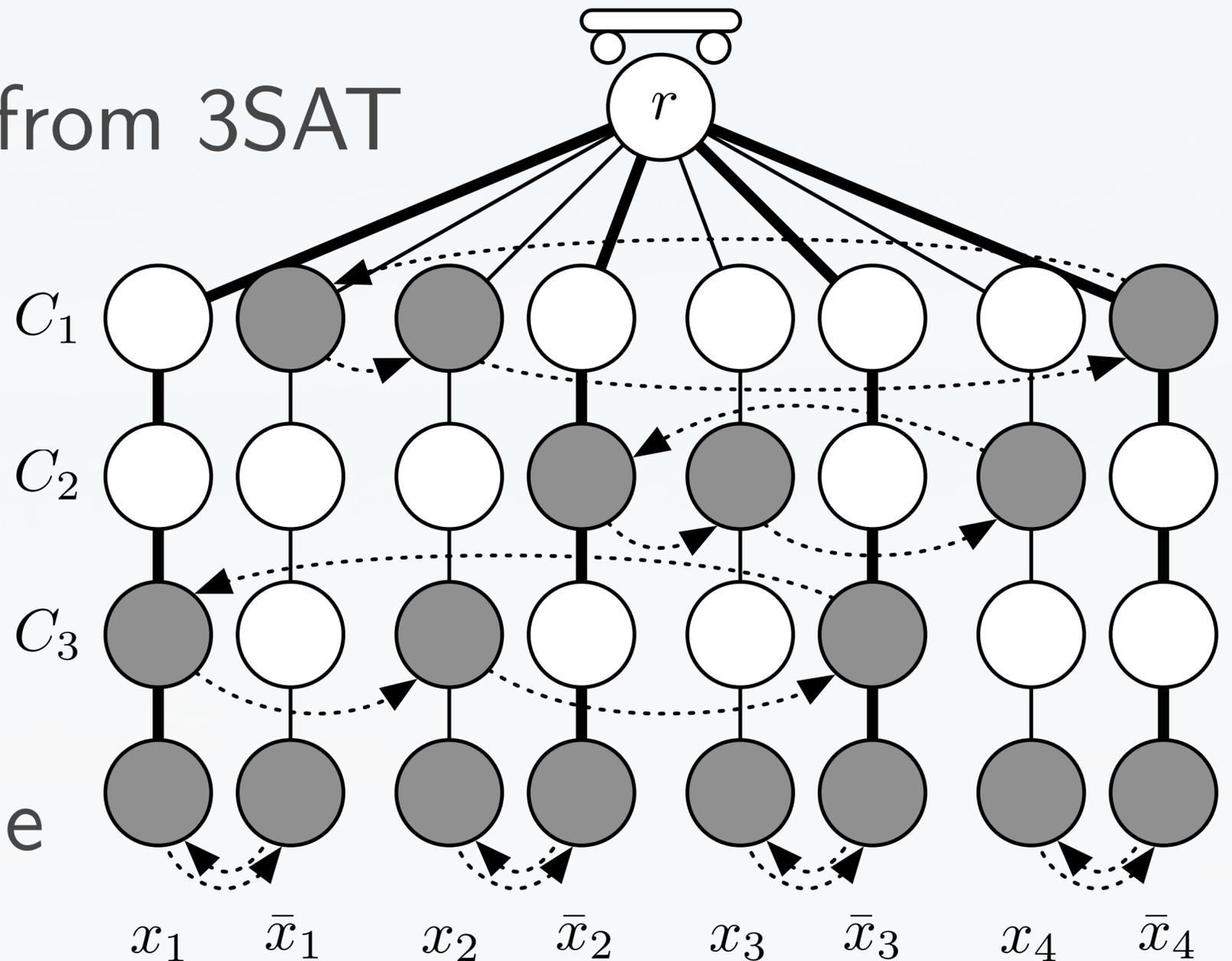


Theorem: Finding a swap-optimal sorting walk on a tree is NP-complete.

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Proof: Reduction from 3SAT

- Spider graph
- One leg per literal
- One cycle per clause & variable



Sorting of physical objects

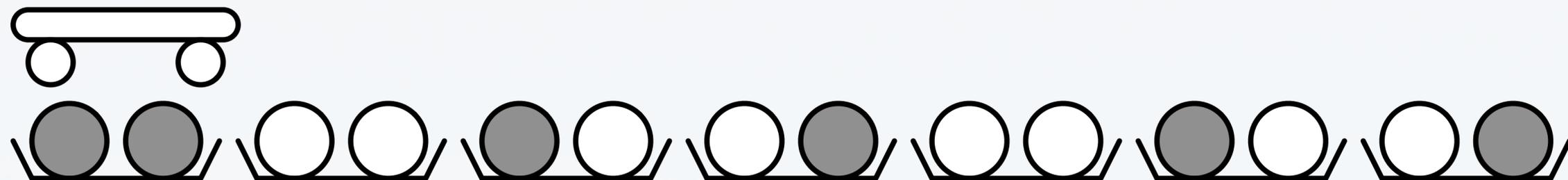
- using prefix reversals, stacks and queues, etc.

Sorting using a given set of possible swaps

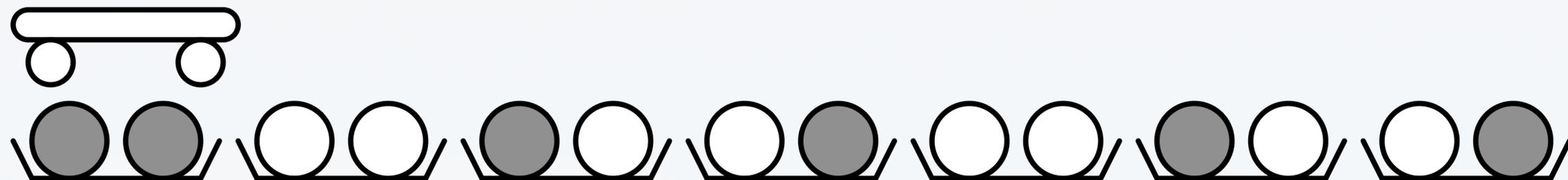
- swapping any pair [1849, Cayley]
- swapping adjacent pairs [1973, Knuth]
 - bubble sort is optimal (inversion number)
 - 2-approximation on trees [2014, Yamanaka et al.]

Group Steiner Tree Problem [1999, Ihler et al.]

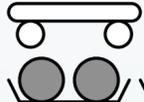
Coding competition task by Luka Kalinovic, 2006



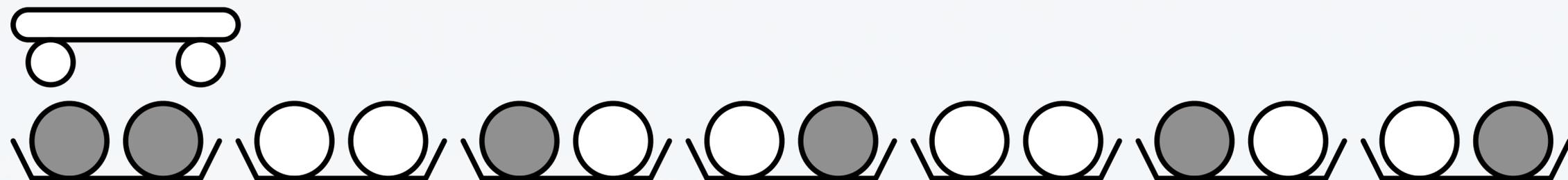
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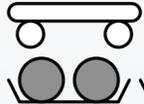
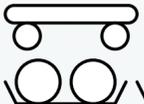
Robot that can carry up to two marbles at a time.

Goal:   or  

Coding competition task by Luka Kalinovic, 2006



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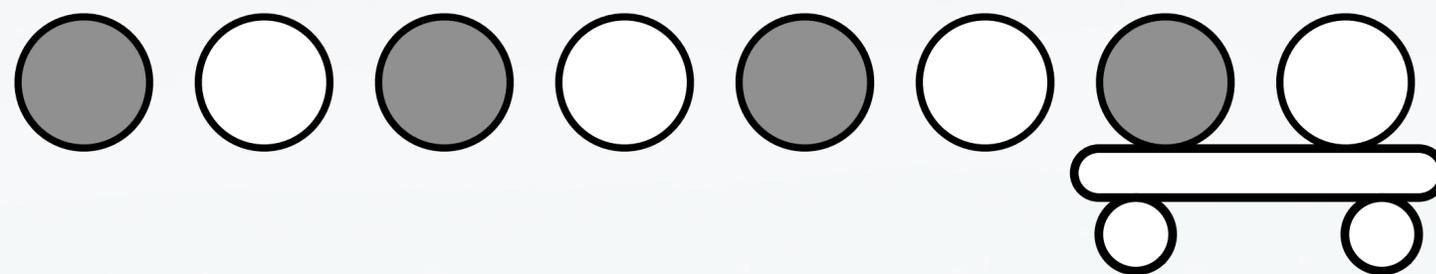
Goal:         or       

Solution: Build graph of lower-bound constraints.

Find an Eulerian path through it. Use an essential-step-argument to show optimality.

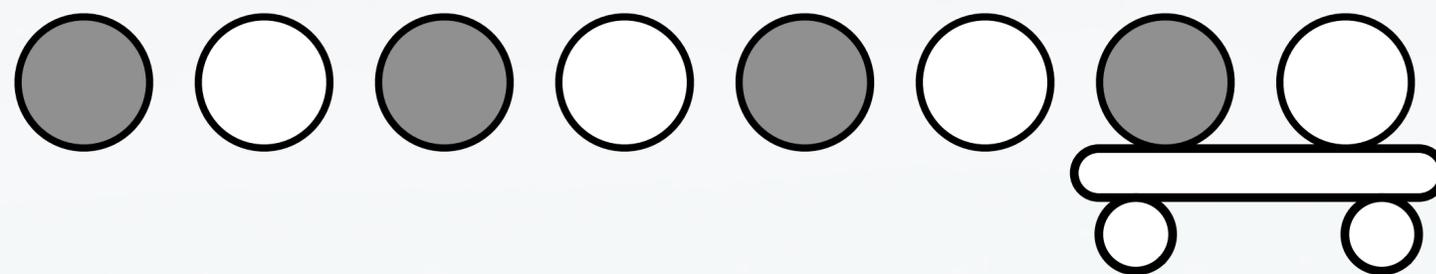
Coin Puzzle by Peter Tait (1890), ICPC WF 2014

In every move this robot can carry exactly two neighboring marbles for an arbitrary distance.



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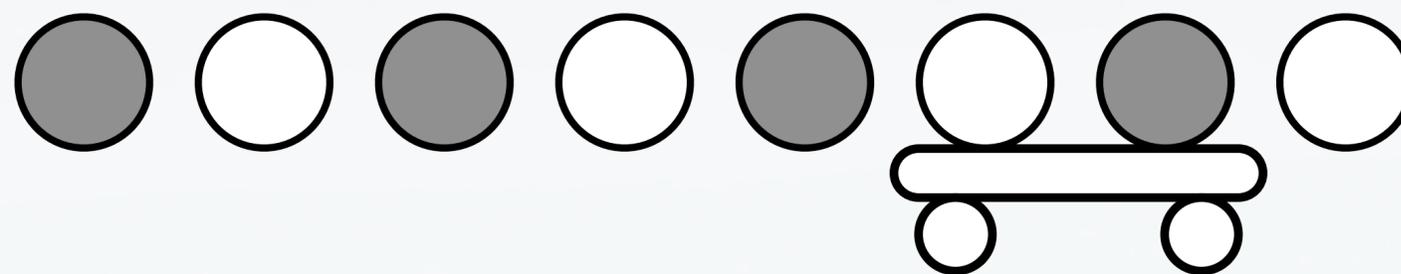
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Solution: Show inductively that it is always possible to do in n steps for n pairs of marbles.

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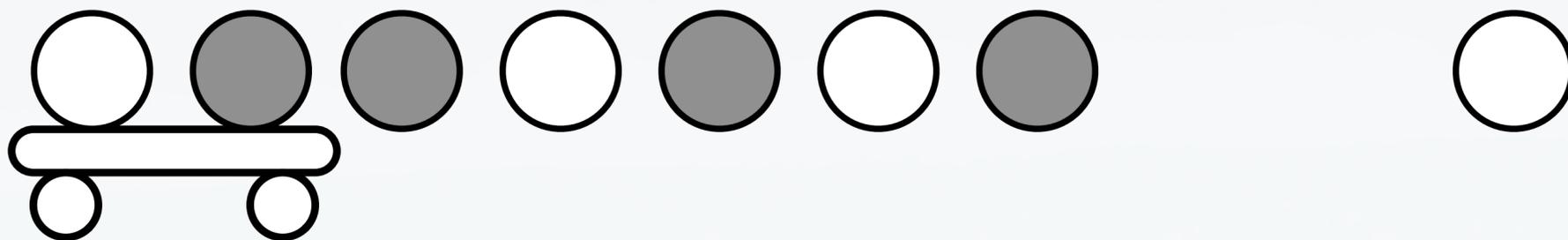
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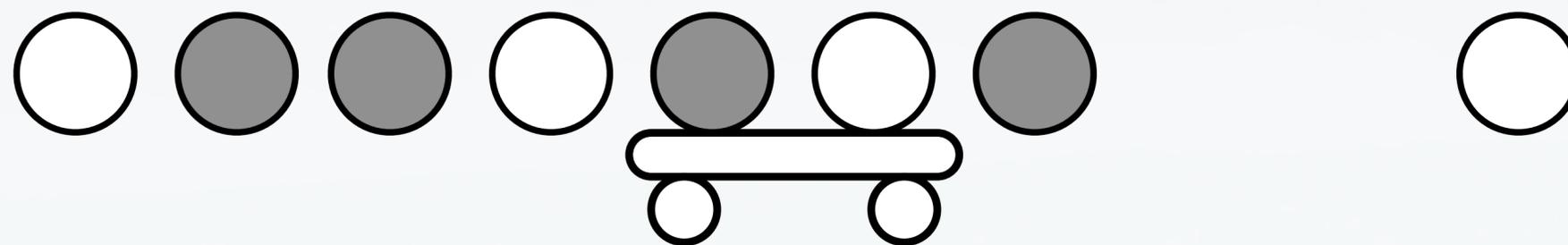
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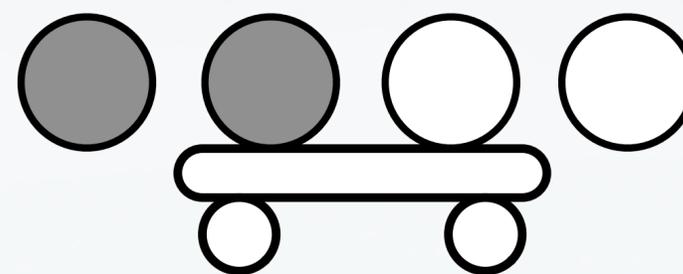
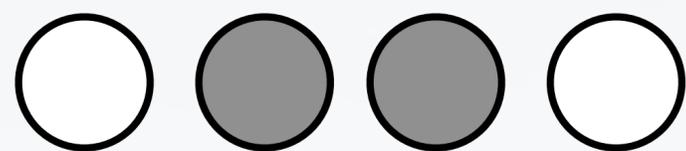
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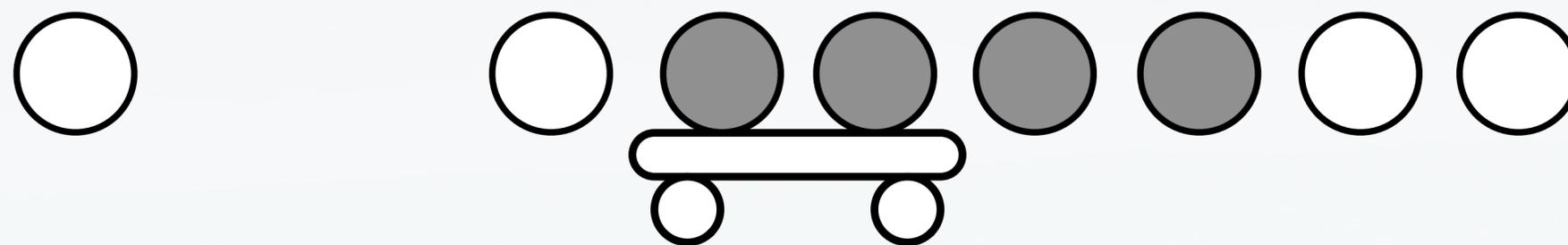
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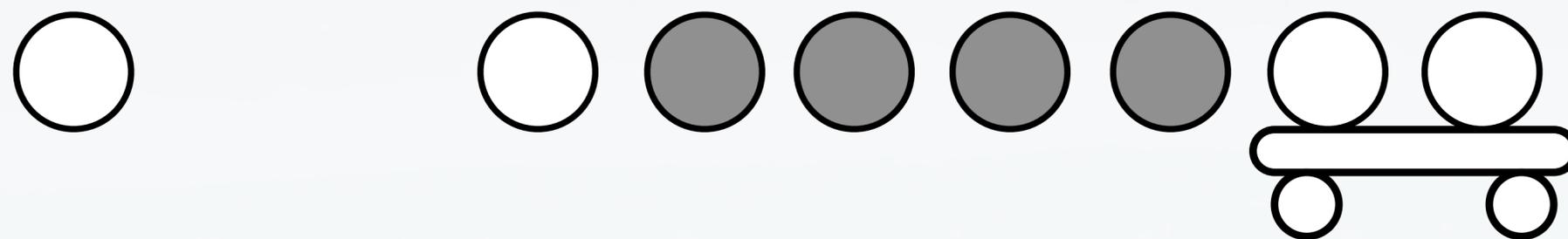
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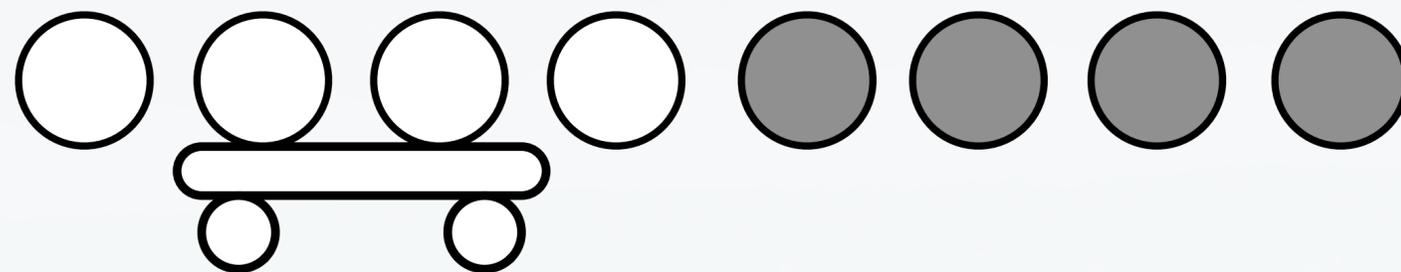
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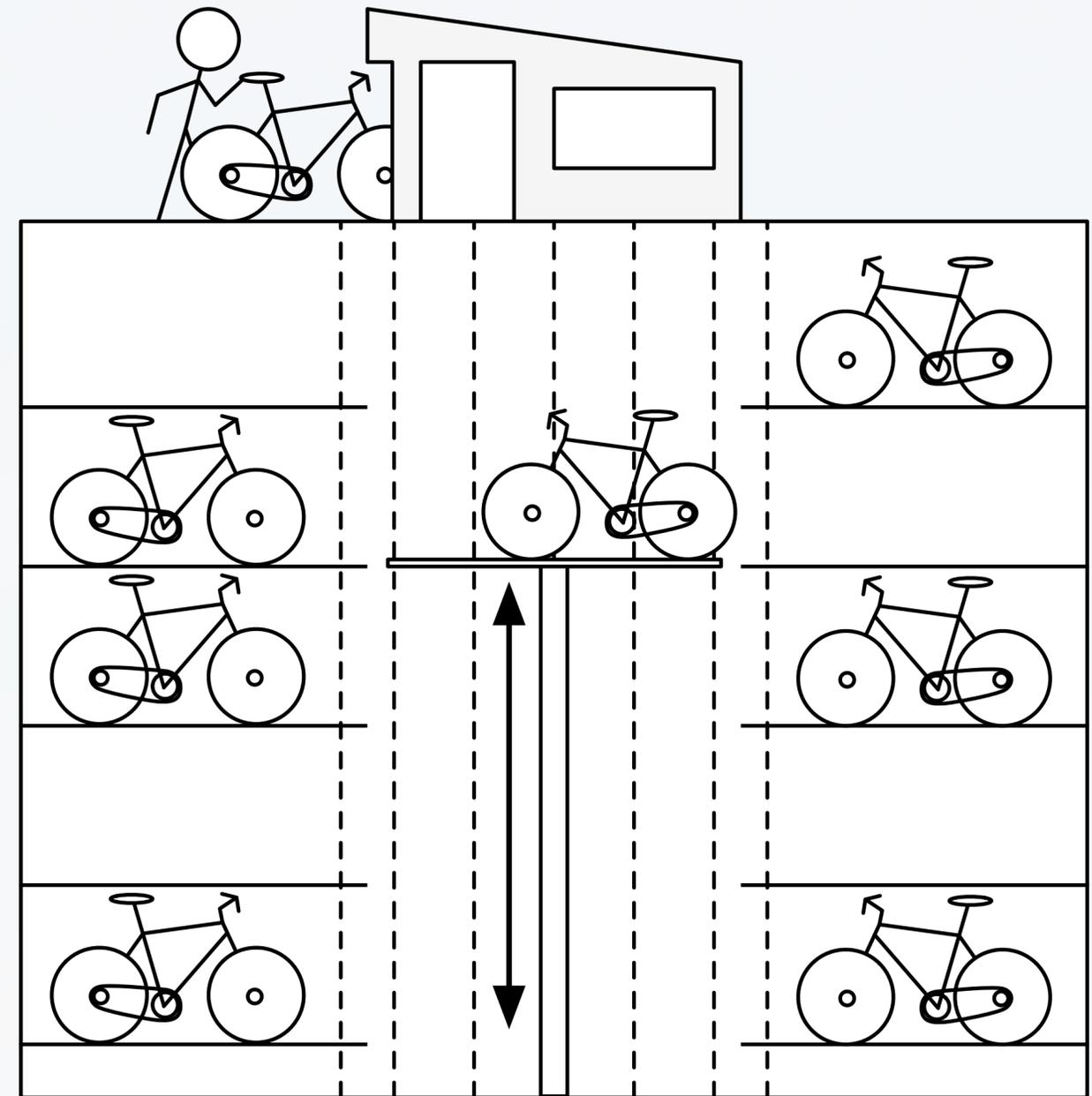
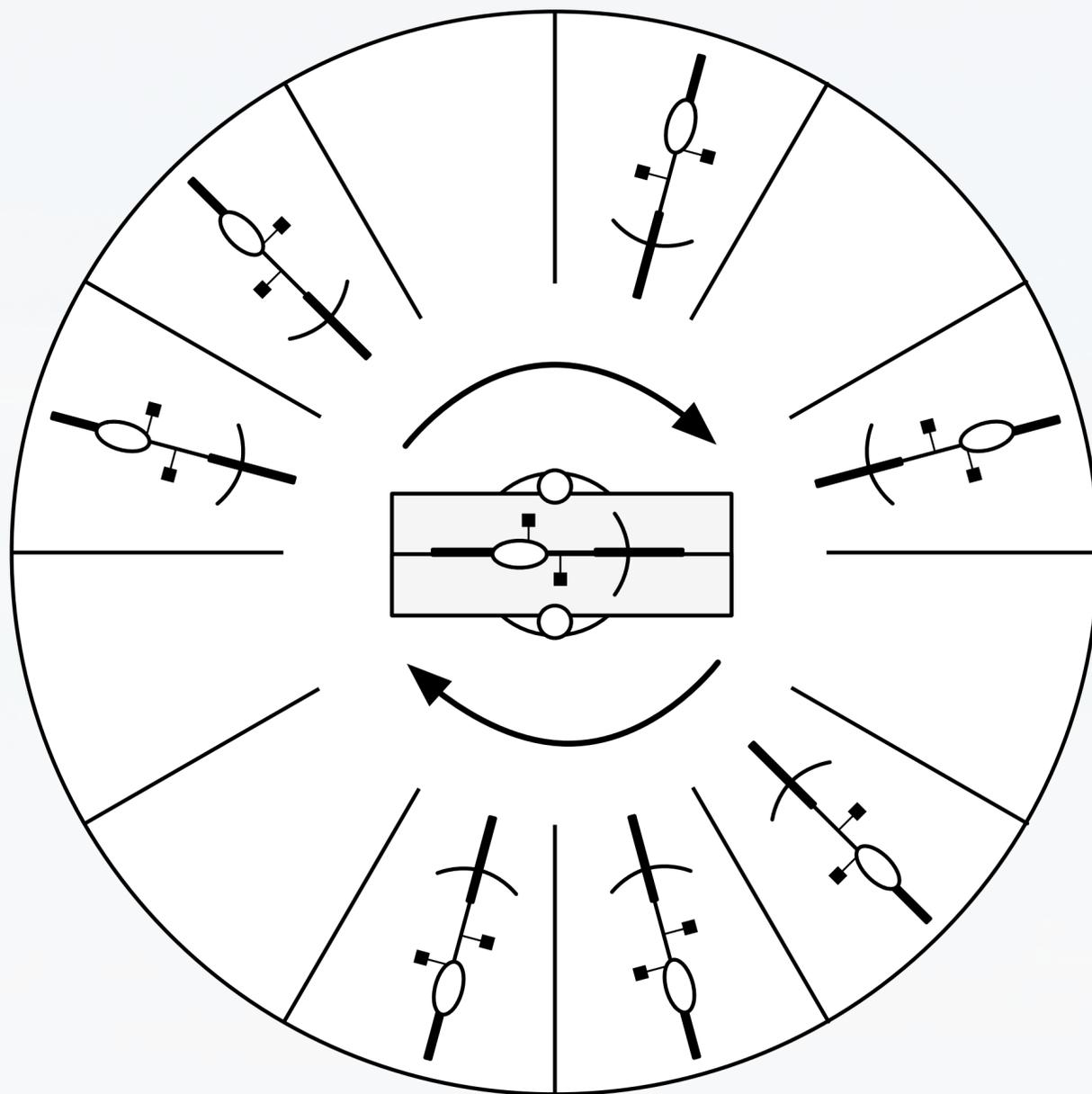
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Other Systems

What else did people try for automated parking?



Vertical lift with circular storage slots around it



Example: ECO Cycle in Tokyo by Giken Seisakusho

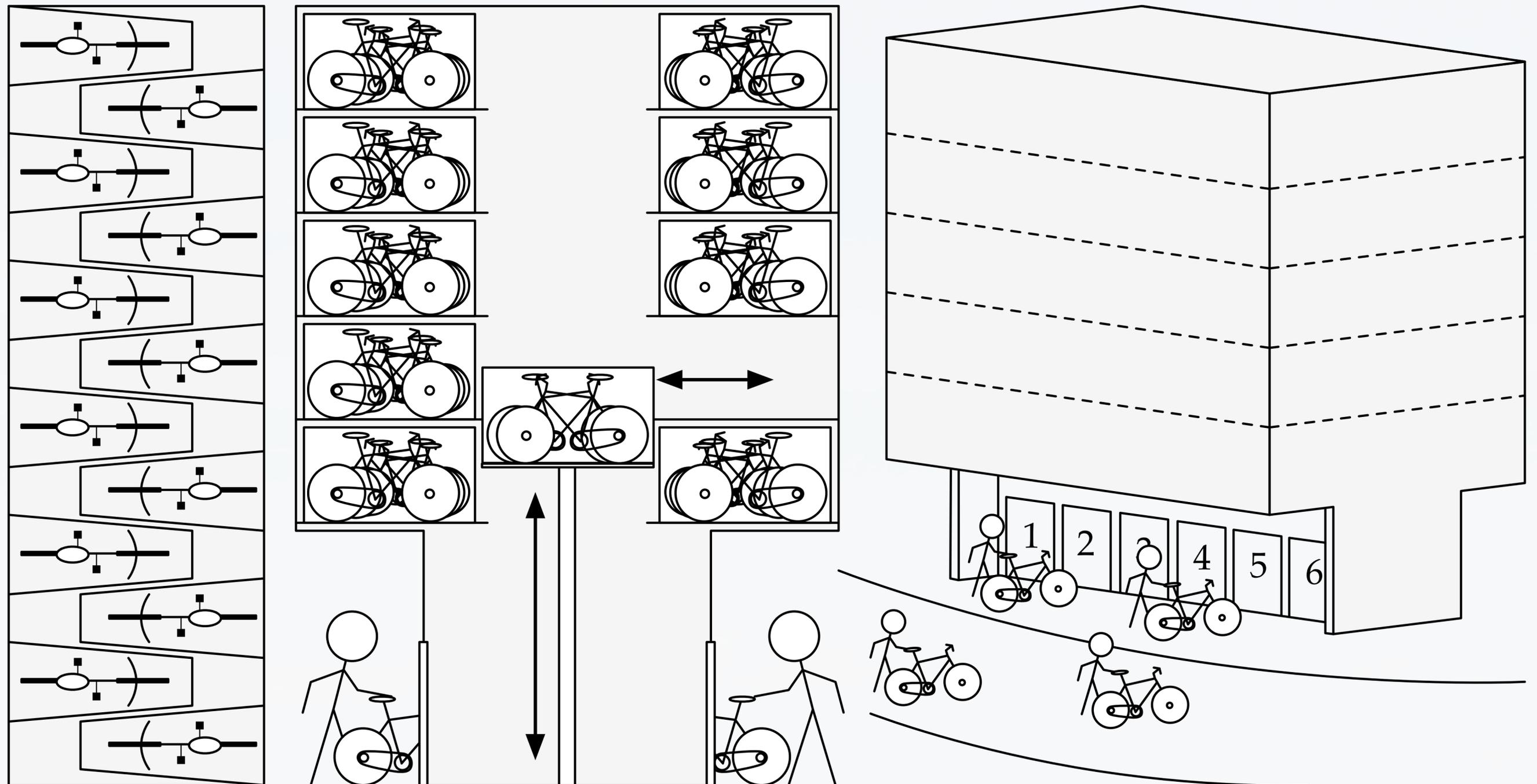


Video by Giken Seisakusho Co. LTD.

Example: Auto Züri West by Skyline Parking



Vertical lift for pallets of 12 bicycles



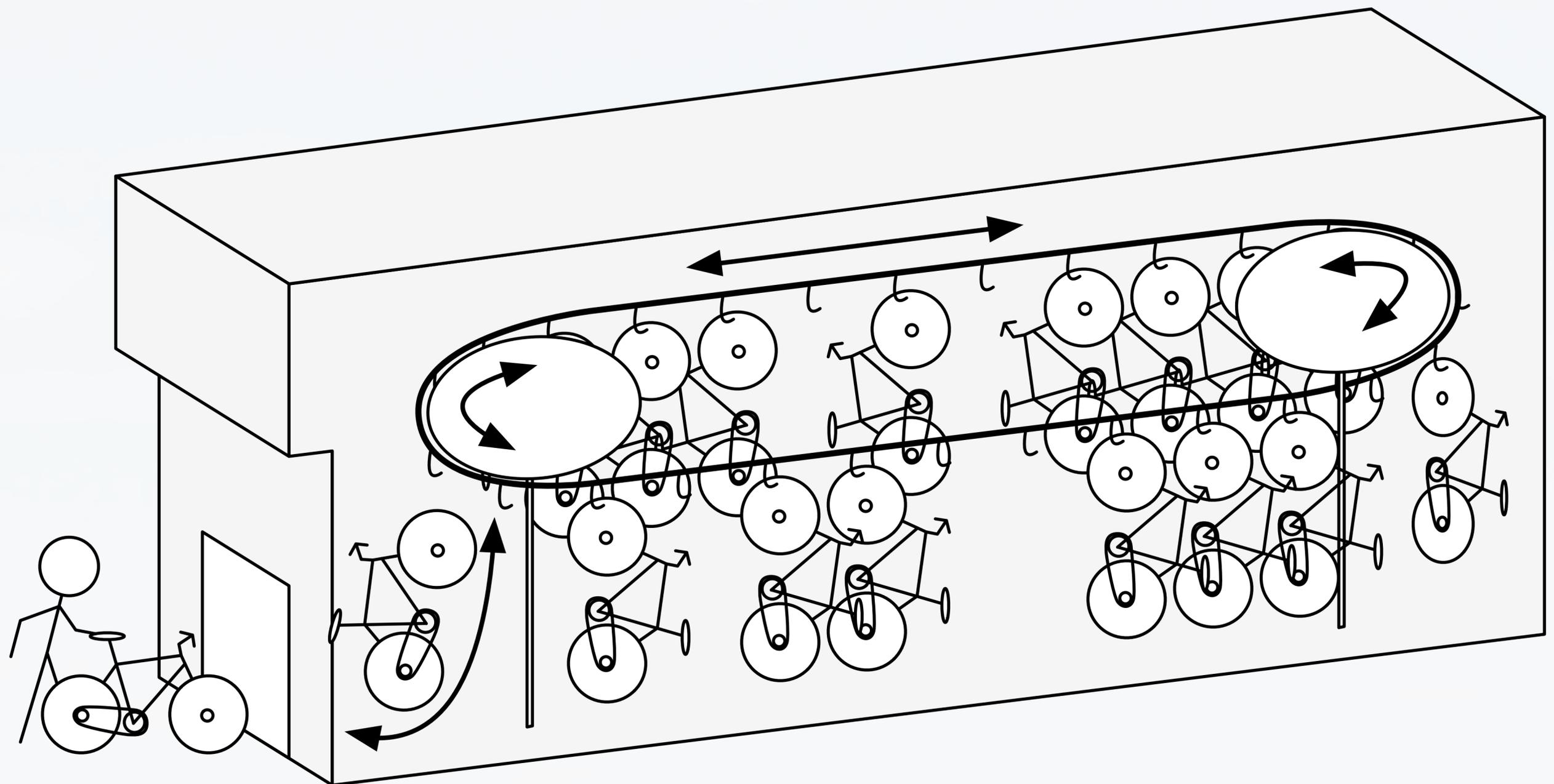
Example: Radhaus in Offenburg (D)



Example: Radhaus in Offenburg (D)



Cyclic chain of hooks, one central access point



Example: VeloMinck in the Netherlands

Example: VeloMinck in the Netherlands



Video by Lo Minck Systemen BV

Example: Paternoster Car Parking in Chicago 1932



Video by Pathé News

Conclusion



Scheduling Problem

- algorithms for arrival-only with a single door
- *NP*-hardness of the two-door problem
- *NP*-hardness of the all-day problem

Sorting Problem

- algorithms for sorting on paths, trees and cycles
- *NP*-hardness for planar graphs
- *NP*-hardness for trees when minimizing swaps

Open research questions

- approximation algorithms for two-door setting
- sorting problem on other graph classes
- further robot variations, multiple robots
- testing these models with real usage data



ETH zürich
Daniel Graf

Thank you for your attention!



